



## Pressure sensors

### C33 series

<b>Series/Type:</b>	<b>Barometric pressure sensor die</b>
<b>Ordering code:</b>	
Date:	2009-08-03
Version:	3

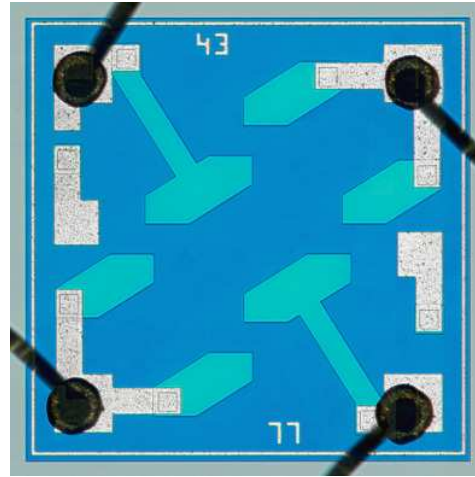
Preliminary data

Applications

- Medical devices
- Weather stations
- Handheld devices (Handy, Navigation,...)
- Automation

Features

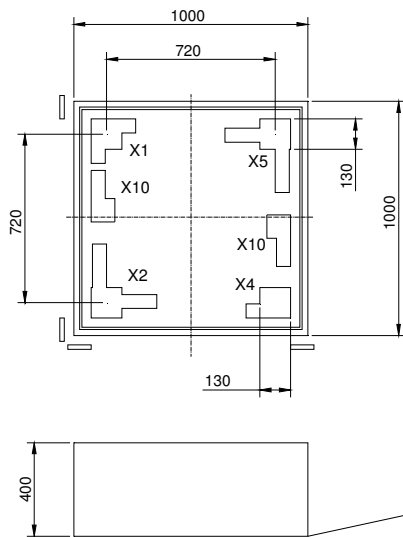
- Piezoresistive MEMS technology
- Small dimensions: 1.00 × 1.00 mm
- Square diaphragm
- Measured media (front side):  
Dry non-aggressive gases.  
Unsuitable for substances which react with silicon or aluminum.
- Wheatstone bridge with mV output, ratiometric to supply voltage
- Rated pressure range is 1.2 bar abs
- Outstanding long-term stability



Delivery mode

- Tray / foil

Dimensional drawings

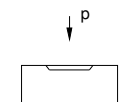
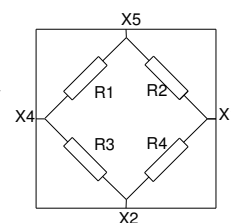


allowable edge disruptions  
50 µm max.

Si 100

all dimensions in µm

electrical diagram:



X1 : Vout+  
X2 : VDD-

X4 : Vout-  
X5 : VDD+

X10: Substrate

**Pressure sensors**
**C33 series**
**Barometric pressure sensor die**
**Preliminary data**
**Technical data**
**Absolute maximum ratings**

Parameter	Symbol	Conditions	Min.	Typ.	Max.	Unit
<b>Supply voltage</b>						
Maximum supply voltage	$V_{DD}$	Without damage <sup>1)</sup>			10	V
<b>Temperature ranges</b>						
Operating temperature range	$T_a$	<sup>2)</sup>	-40		135	°C
		For $t < 15$ min	-40		140	°C
Storage temperature range	$T_{st}$	<sup>3)</sup>	-40		150	°C
<b>Pressure ranges</b>						
Operating pressure ranges	$p_r$	Absolute pressure <sup>4)</sup>	0		1.2	bar
Over pressure	$p_{ov}$	Absolute pressure <sup>5)</sup>	3			$p_r$
Burst pressure	$p_{berst}$	Absolute pressure <sup>6)</sup>	5			$p_r$

**Electrical specifications**

Parameter	Symbol	Conditions	Min.	Typ.	Max.	Unit
<b>Supply voltage / bridge resistance</b>						
Operating supply voltage	$V_{DD}$	<sup>7)</sup>	1.0	3.0	6.0	V
Total bridge resistance	$R_S$	@ 25 °C <sup>8)</sup>	2.6	3.3	4.0	k $\Omega$
Temperature coefficient of total bridge resistance	$\alpha_{R_S}$	@ 25 °C <sup>9)</sup>	2.1	2.4	2.7	10 <sup>-3</sup> /K
	$\beta_{R_S}$		4	6	8	10 <sup>-6</sup> /K <sup>2</sup>
<b>Output signal @ <math>V_{DD} = 5</math> V</b>						
Offset	$V_0$	@ 25 °C <sup>10)</sup>	-30	0	+30	mV
Sensitivity	$S$	@ 25 °C <sup>13)</sup>	See next table			mV/bar
Temperature coefficient of the sensitivity	$\alpha_S$	@ 25 °C <sup>15)</sup>	-2.5	-2.2	-1.9	10 <sup>-3</sup> /K
	$\beta_S$		3	5	8	10 <sup>-6</sup> /K <sup>2</sup>
Pressure hysteresis	$p_{Hys}$	<sup>16)</sup>	-0.1		0.1	% FS
<b>Long-term stability (Full scale normal output FSON = 120 mV)</b>						
Temperature hysteresis of offset	$THV_0$	<sup>17)</sup>		tbd		% FSON
Temperature cycle drift of offset	$TCDV_0$	<sup>17)</sup>		tbd		% FSON
High temperature drift of offset	$HTDV_0$	<sup>17)</sup>		tbd		% FSON
Long term stability of offset	$LTSV_0$	<sup>17)</sup>		tbd		% FSON

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**Operating pressures and ordering codes**

Parameter @ 25 °C, V <sub>DD</sub> = 5 V	Symbol	Typ.	Units
Operating pressure <sup>4)</sup>	p <sub>r</sub>	1.2	bar
Temperature coefficient of offset voltage (unglued) <sup>11)</sup> [min/typ/max]	TCV <sub>0</sub> <sup>-</sup>	-8	μV/VK
	TCV <sub>0</sub> <sup>+</sup>	-6	μV/VK
Nonlinearity <sup>14)</sup> [typ]	L	±0.3	% FS
Sensitivity <sup>13)</sup> [typ]	S	100	mV/bar
Product type		AEA 1.200 C33/1	
Ordering code		B5860010000A001	

**Preliminary data**
**Symbols and Terms**

- 1) **Maximum power supply  $V_{DD}$**   
This is the maximal allowed voltage, which may be applied to the piezoresistive bridge circuit without damage.
- 2) **Operating temperature range  $T_a$**   
This is the operating Temperature range  $T_{a,min}$  to  $T_{a,max}$ . Because most of the sensor parameters depend on assembling conditions like gluing, wire bonding etc, the die has to be tested over the operating temperature range by the customer fully assembled. For design verification and process control samples, mounted on a TO39 base are tested over a reduced measuring temperature range of  $T_{meas,min}$  to  $T_{meas,max}$ .
- 3) **Storage temperature range  $T_{st}$**   
If the pressure sensor dies are stored in the temperature range  $T_{st,min}$  to  $T_{st,max}$  without applied voltage power supply, this will not affect the performance of the pressure sensor dies.
- 4) **Operating pressure range  $p_r$**   
In the operating pressure range 0 to  $p_{r,max}$  the pressure sensor die output characteristic is as defined in this specification.
- 5) **Over pressure  $p_{ov}$**   
Pressure cycles in the pressure range 0 to  $p_{ov}$  do not affect the performance of the pressure sensor dies.
- 6) **Burst pressure  $p_{berst}$**   
Up to the burst pressure  $p_{berst}$  the diaphragm of the sensor die will not be destroyed mechanically. This parameter is tested at room temperature on samples mounted on a TO39 base by increasing the applied pressure until the diaphragm is destroyed.
- 7) **Operating power supply  $V_{DD}$**   
The pressure sensor parameters are defined for a power supply voltage of  $V_{DD} = 5\text{ V}$ . In the operating power supply voltage range  $V_{DD,min}$  to  $V_{DD,max}$  the ratiometric parameters  $r(V_{DD})$  like sensitivity, offset voltage and the temperature coefficient of the offset voltage are defined by:

$$r(V_{DD}) = r(5[V]) \frac{V_{DD}}{5[V]}$$

- 8) **Total bridge resistance  $R_S$**   
The total bridge resistance is defined between pad X5 and X2 (see the dimensional drawing in this data sheet) of the closed piezoresistive bridge circuit. The total bridge resistance is in a good approximation the output impedance of the piezoresistive bridge circuit. This parameter is tested completely on a wafer (wafer level test measurement).
- 9) **Temperature coefficients of resistance  $\alpha_{R_S}$  and  $\beta_{R_S}$ :**  
The temperature coefficients of resistance are tested for design verification on samples, mounted on a TO39 base over a reduced temperature range  $T_{meas,min} = -20\text{ °C}$  to  $T_{meas,max} = 80\text{ °C}$  with  $T_R = 25\text{ °C}$ .  
The temperature coefficients of first and second order are defined with the polynomial:

$$R_S(T) = R_S(T=25\text{°C}) \left[ 1 + \alpha_{R_S}(T-25\text{°C}) + \beta_{R_S}(T-25\text{°C})^2 \right]$$

The coefficients  $\alpha_{R_S}$  and  $\beta_{R_S}$  are calculated using the three measurement points of  $R_S(T)$  at  $T_{meas,min}$ ,  $T_R$  and  $T_{meas,max}$ .

- 10) **Offset voltage  $V_0$**   
The offset voltage  $V_0$  is the output voltage  $V_{out}(p = 0\text{ bar abs})$  at zero absolute pressure and for a bridge voltage power supply  $V_{DD} = 5\text{ V}$ . For design verification  $V_0$  is measured on samples, mounted on a TO39 base by extrapolating the output characteristic to zero bar.  
It should be noted that this parameter may be influenced by the assembly.
- 11) **Temperature coefficient of offset voltage  $TCV_0$**   
The temperature coefficients of offset voltage are defined for a bridge voltage power supply  $V_{DD} = 5\text{ V}$ . These parameters strongly depend on assembly conditions like gluing, wire bonding etc.  
The temperature coefficients of offset voltage are tested for design verification on samples, mounted on a TO39 base over a reduce temperature range, using the temperature  $T_{meas,min} = -20\text{ °C}$ ,  $T_{meas,max} = 80\text{ °C}$  and  $T_R = 25\text{ °C}$ . Assuming the offset voltage is mainly due to induce stress  $TCV_0$  may be calculated by extrapolating using:

$$V_0(T) = \left( 1 + \alpha_s(T - 25\text{°C}) + \beta_s(T - 25\text{°C})^2 \right) \left( V_0(25\text{°C}) + v_1(T - 25\text{°C}) + v_2(T - 25\text{°C})^2 \right)$$

**Preliminary data**

$\alpha_s$  and  $\beta_s$  are the linear and nonlinear temperature coefficient of the sensitivity respectively (see <sup>15)</sup>). Therefore  $TCV_0^+$  and  $TCV_0^-$  are defined for the measurement temperature range by:

$$TCV_0^+ = \frac{V_o(T_{max}) - V_o(25^\circ C)}{T_{max} - 25^\circ C} \quad TCV_0^- = \frac{V_o(T_{min}) - V_o(25^\circ C)}{T_{min} - 25^\circ C}$$

**12) Full scale value FS**

$$FS = V_{out}(p_{rmax}) - V_o$$

**13) Sensitivity S**

The sensitivity is defined for a bridge voltage power supply  $V_{DD} = 5 V$ . It can be determined by the formula:

$$S = \frac{V_{out}(p_{rmax}) - V_o}{p_{rmax}}$$

This parameter is tested for process control on samples, mounted on a TO39 base.

**14) Nonlinearity L**

This parameter may be influenced by assembly.

The nonlinearity is measured using the endpoint method. Assuming a characteristic, this can be approximated by a polynomial of second order, where the maximum is at  $p_x = p_{rmax}/2$ . The nonlinearity is defined at  $p_x = p_{rmax}/2$ , using the equation:

$$L = \frac{V_{out}(p_x) - V_o}{V_{out}(p_{rmax}) - V_o} - \frac{p_x}{p_{rmax}}$$

This parameter is tested for process control on samples, mounted on a TO39 base.

**15) Temperature coefficient of sensitivity  $\alpha_s$  and  $\beta_s$ :**

These parameters may be influenced by assembly.

The temperature coefficients of sensitivity are tested for design verification on samples, mounted on a TO39 base over a reduced temperature range  $T_{meas,min} = -20^\circ C$  to  $T_{meas,max} = 80^\circ C$  with  $T_R = 25^\circ C$ .

The temperature coefficients of first and second order are defined with the polynomial:

$$S(T) = S(T=25^\circ C) \left[ 1 + \alpha_s(T-25^\circ C) + \beta_s(T-25^\circ C)^2 \right]$$

The coefficients  $\alpha_s$  and  $\beta_s$  are calculated using the three measurement points of  $S(T)$  at  $T_{meas,min}$ ,  $T_R$  and  $T_{meas,max}$ .

**16) Pressure hysteresis pHys**

The pressure hysteresis is the difference between output voltages at constant pressure and constant temperature while applying a pressure cycle with pressure steps of  $p_{r,min}$ ,  $p_1$ ,  $p_2$ ,  $p_3$ ,  $p_{r,max}$ ,  $p_3$ ,  $p_2$ ,  $p_1$ ,  $p_{r,min}$ :

$$pHys = \frac{V_{out,2}(p_k) - V_{out,1}(p_k)}{FS}$$

With  $k = \min, 1, 2, 3, \max$ . The pressure steps are:  $p_{rmin} = 0$ ,  $p_1 = 0.25 \cdot p_{r,max}$ ,  $p_2 = 0.5 \cdot p_{r,max}$ ,  $p_3 = 0.75 \cdot p_{r,max}$ ,  $p_{r,max}$ .

This parameter is tested for design verification on samples, mounted on a TO39 base.

**17) Reliability data**

For long-term stability of offset voltage  $LTSV_0$  please refer to the defined Aktiv Sensor's standard AS100001 in chapter "Reliability data" on the internet.

## Preliminary data

### Cautions and warnings

#### Storage (general)

All pressure sensors should be stored in their original packaging. They should not be placed in harmful environments such as corrosive gases nor exposed to heat or direct sunlight, which may cause deformations. Similar effects may result from extreme storage temperatures and climatic conditions. Avoid storing the sensor dies in an environment where condensation may form or in a location exposed to corrosive gases, which will adversely affect their performance. Plastic materials should not be used for wrapping/packing when storing or transporting these dies, as they may become charged. Pressure sensor dies should be used soon after opening their seal and packaging.

#### Operation (general)

Media compatibility with the pressure sensors must be ensured to prevent their failure. The use of other media can cause damage and malfunction. Never use pressure sensors in atmospheres containing explosive liquids or gases.

Ensure pressure equalization to the environment, if gauge pressure sensors are used. Avoid operating the pressure sensors in an environment where condensation may form or in a location exposed to corrosive gases. These environments adversely affect their performance.

If the operating pressure is not within the rated pressure range, it may change the output characteristics. This may also happen with pressure sensor dies if an incorrect mounting method is used. Be sure that the applicable pressure does not exceed the overpressure, as it may damage the pressure sensor.

Do not exceed the maximum rated supply voltage nor the rated storage temperature range, as it may damage the pressure sensor.

Temperature variations in both the ambient conditions and the media (liquid or gas) can affect the accuracy of the output signal from the pressure sensors. Be sure to check the operating temperature range and thermal error specification of the pressure sensors to determine their suitability for the application.

Connections must be wired in accordance with the terminal assignment specified in the data sheets. Care should be taken as reversed pin connections can damage the pressure transmitters or degrade their performance. Contact between the pressure sensor terminals and metals or other materials may cause errors in the output characteristics.

#### Design notes (dies)

This specification describes the mechanical, electrical and physical requirements of a piezoresistive sensor die for measuring pressure. The specified parameters are valid for the pressure sensor die with pressure application either to the front or back side of the diaphragm as described in the data sheet. Pressure application to the other side may result in differing data. Most of the parameters are influenced by assembly conditions. Hence these parameters and the reliability have to be specified for each specific application and tested over its temperature range by the customer.

#### Handling/Mounting (dies)

Pressure sensor dies should be handled appropriately and not be touched with bare hands. They should only be picked up manually by the sides using tweezers. Their top surface should never be touched with tweezers. Latex gloves should not be used for handling them, as this will inhibit the curing of the adhesive used to bond the die to the carrier. When handling, be careful to avoid cuts caused by the sharp-edged terminals. The sensor die must not be contaminated during manufacturing processes (gluing, soldering, silk-screen process).

The package of pressure sensor dies should not to be opened until the die is mounted and should be closed after use. The sensor die must not be cleaned. The sensor die must not be damaged during the assembly process (especially scratches on the diaphragm).

#### Soldering (transducers, transmitters)

The thermal capacity of pressure sensors is normally low, so steps should be taken to minimize the effects of external heat. High temperatures may lead to damage or changes in characteristics.

A non-corrosive type of flux resin should normally be used and complete removal of the flux is recommended. Avoid rapid cooling due to dipping in solvent. Note that the output signal may change if pressure is applied to the terminals during soldering.

This listing does not claim to be complete, but merely reflects the experience of EPCOS AG.

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