

Incremental encoders

Hollow shaft $\varnothing 120$ to $\varnothing 150$ mm

Resolution 1024...2048 pulses

HOG 28



HOG 28 - Version with terminal box

Features

- Encoder with hollow shaft $\varnothing 120$ -150 mm
- Optical sensing
- Robust light-metal housing
- Logic level TTL with regulator UB 9...26 VDC
- Logic level HTL with power linedriver
- Big terminal box, turn by 180°

Optional

- Earthing brush (no explosion protection)
- Plug-in electronics
- Redundant sensing (version M)

Technical data - electrical ratings

Voltage supply	5 VDC ± 5 % 9...26 VDC
Consumption w/o load	≤ 100 mA
Resolution (steps/turn)	1024...2048
Phase shift	90° ± 20 °
Scan ratio	40...60 %
Reference signal	Zero pulse, width 90°
Sensing method	Optical
Output frequency	≤ 120 kHz
Output signals	K1, K2, K0 + inverted
Output circuit	TTL (RS422) HTL (power linedriver)
Interference immunity	DIN EN 61000-6-2
Emitted interference	DIN EN 61000-6-4
Approval	UL approval / E256710

Technical data - mechanical design

Dimensions (flange)	$\varnothing 287$ mm
Shaft	$\varnothing 120$...150 mm hollow shaft
Shaft loading	≤ 250 N axial ≤ 320 N radial
Protection DIN EN 60529	IP 54
Operating speed	≤ 3600 rpm (mechanical)
Operating torque typ.	50 Ncm
Rotor moment of inertia	240 kgcm ² ($\varnothing 150$)
Materials	Housing: aluminium alloy Shaft: stainless steel
Operating temperature	-30...+85 °C
Resistance	IEC 60068-2-6 Vibration 10 g, 10-2000 Hz IEC 60068-2-27 Shock 200 g, 6 ms
Explosion protection	II3G Ex nA IIC T4 Gc (gas) II3D Ex tc IIIB T135°C Dc (dust)
Connection	Terminal box Connector M23, 12-pin
Weight approx.	20 kg ($\varnothing 150$)

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Hollow shaft $\varnothing 120$ to $\varnothing 150$ mm

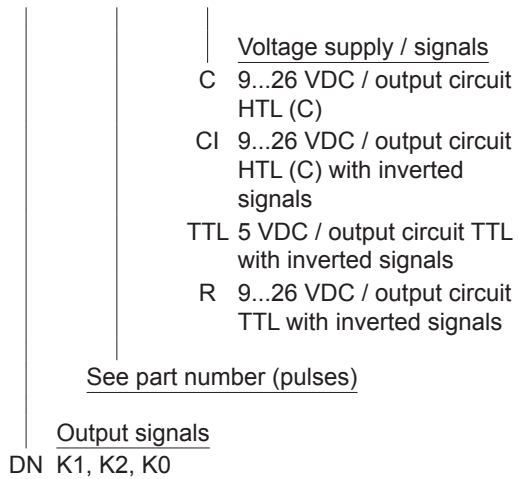
Resolution 1024...2048 pulses

HOG 28

Part number

HOG 28

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Accessories

Connectors and cables

HEK 8 Sensor cable for encoders

Mounting accessories

DMS 12 Torque arm size M12

Diagnostic accessories

HENQ 1100 Analyzer for encoders

Part number (pulses)

1024 | 1800 | 2048

Other pulse numbers upon request.

Incremental encoders

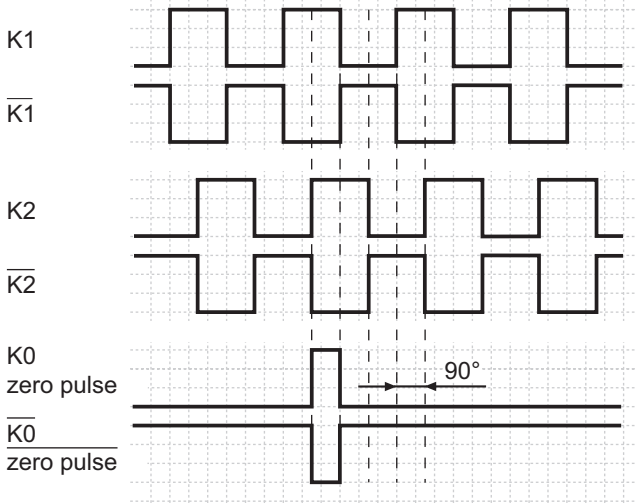
Hollow shaft $\varnothing 120$ to $\varnothing 150$ mm

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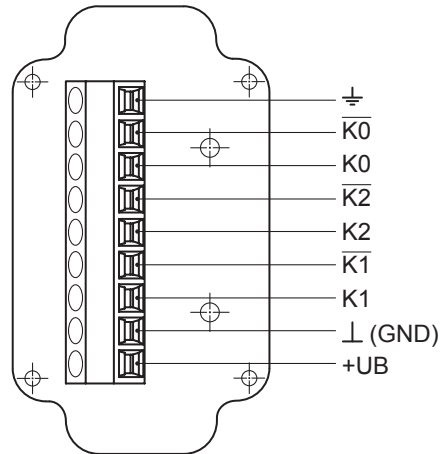
Output signals

at positive rotating direction



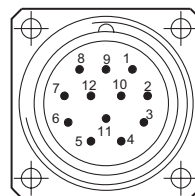
Terminal assignment

View A - Connecting terminal in terminal box



View B - Flange socket, male contacts, clockwise

Male	Assignment
Pin 1	$\overline{K2}$ (B- K2 inv.)
Pin 2	do not use
Pin 3	K0 (R+ zero pulse)
Pin 4	$\overline{K0}$ (R- zero pulse inv.)
Pin 5	K1 (A+)
Pin 6	$\overline{K1}$ (A- K1 inv.)
Pin 7	do not use
Pin 8	K2 (B+)
Pin 9	do not use
Pin 10	GND
Pin 11	do not use
Pin 12	+UB



Incremental encoders

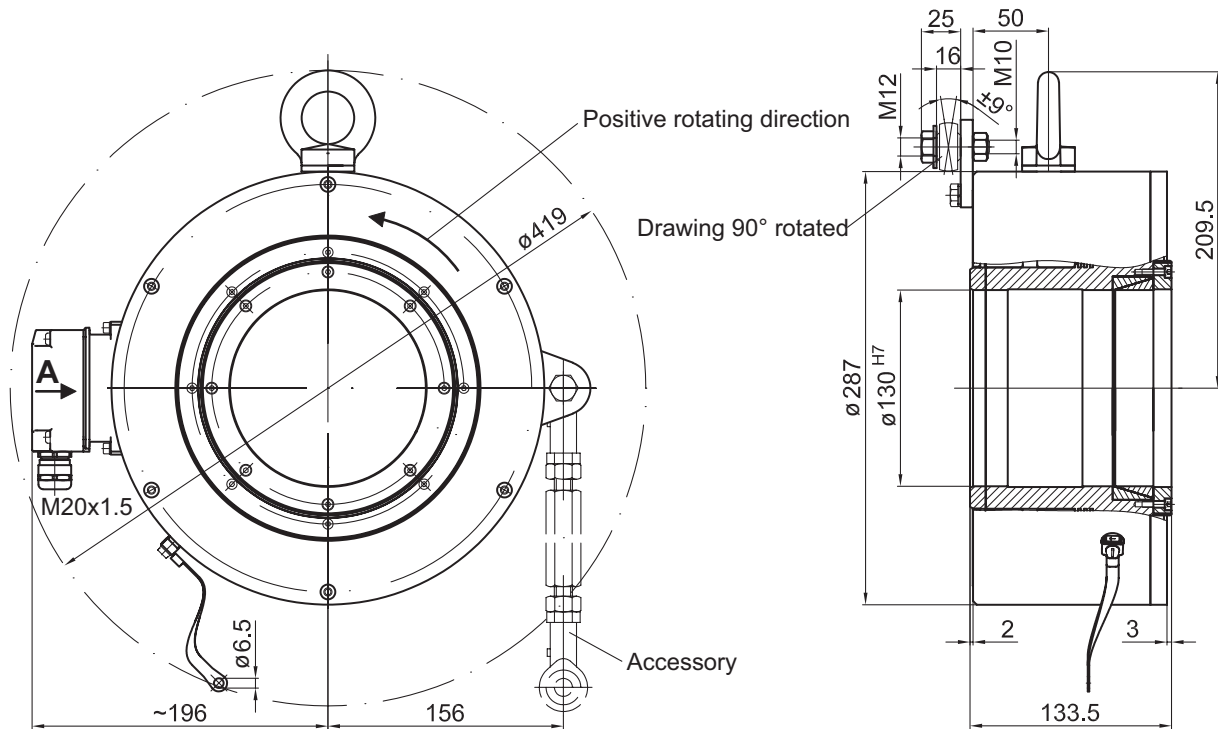
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Dimensions

Version with terminal box



Version with flange socket and mating connector

