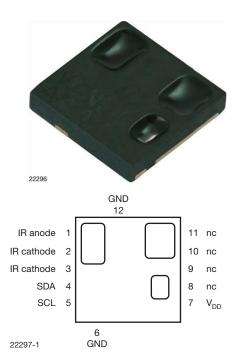


**Vishay Semiconductors** 

## Fully Integrated Proximity and Ambient Light Sensor with Infrared Emitter and I<sup>2</sup>C Interface



## DESCRIPTION

VCNL4000 is a fully integrated proximity and ambient light digital 16 bit resolution sensor in a miniature lead less package (LLP) for surface mounting. It includes a signal processing IC and supports an easy to use I<sup>2</sup>C bus communication interface.

## APPLICATIONS

- Proximity sensor for mobile devices (e.g. smart phones, touch phones, PDA, GPS) for touch screen locking, power saving, etc.
- Integrated ambient light function for display/keypad contrast control and dimming of mobile devices
- Proximity/optical switch for consumer, computing and industrial devices and displays
- Dimming control for consumer, computing and industrial displays

## FEATURES

- Package type: surface mount
- Dimensions (L x W x H in mm): 3.95 x 3.95 x 0.75
- Integrated module with ambient light sensor, proximity sensor and signal conditioning IC
- Supply voltage range V<sub>DD</sub>: 2.5 V to 3.6 V
- Supply voltage range IR anode: 2.5 V to 5 V
- Communication via I<sup>2</sup>C interface
- I<sup>2</sup>C Bus H-level range: 1.7 V to 5 V
- Floor life: 168 h, MSL 3, acc. J-STD-020
- Low stand by current consumption: 1.5 μA
- Material categorization: For definitions of compliance please see <u>www.vishay.com/doc?99912</u>

### **PROXIMITY FUNCTION**

- Built in infrared LED and photo-pin-diode for proximity function
- 16 bit effective resolution for proximity detection range ensures excellent cross talk immunity
- Programmable LED drive current from 10 mA to 200 mA (in 10 mA steps)
- Excellent ambient light suppression by signal modulation
- Proximity distance up to 200 mm

### AMBIENT LIGHT FUNCTION

- Built in ambient light photo-pin-diode with close to human eye sensitivity characteristic
- 16 bit dynamic range for ambient light detection from 0.25 lx to 16 klx
- 100 Hz and 120 Hz flicker noise rejection

PRODUCT SUMM	PRODUCT SUMMARY										
PART NUMBER	OPERATING RANGE (mm)	OPERATING VOLTAGE RANGE (V)	I <sup>2</sup> C BUS VOLTAGE RANGE (V)	LED PULSE CURRENT <sup>(1)</sup> (mA)	AMBIENT LIGHT RANGE (lx)	AMBIENT LIGHT RESOLUTION (Ix)	OUTPUT CODE				
VCNL4000	1 to 200	2.5 to 3.6	1.7 to 5	10 to 200	0.25 to 16 383	0.25	16 bit, I <sup>2</sup> C				

#### Note

<sup>(1)</sup> Adjustable through I<sup>2</sup>C interface





COMPLIANT

GREEN

(5-2008)



ORDERING INFORMATION					
ORDERING CODE	PACKAGING	VOLUME <sup>(1)</sup>	REMARKS		
VCNL4000-GS08	Tape and reel	MOQ: 1800 pcs	3.95 mm x 3.95 mm x 0.75 mm		
VCNL4000-GS18	Tape and reel	MOQ: 7000 pcs	3.95 mm x 3.95 mm x 0.75 mm		
VCNL4000demokit ( <u>www.vishay.com/doc?83395</u> )	-	MOQ: 1 pc	-		

Note

SHAY

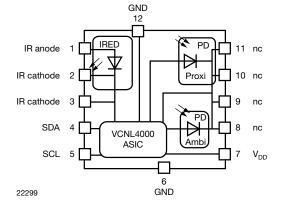
<sup>(1)</sup> MOQ: minimum order quantity

ABSOLUTE MAXIMUM RATINGS (T <sub>amb</sub> = 25 °C, unless otherwise specified)										
PARAMETER	TEST CONDITION	SYMBOL	MIN.	MAX.	UNIT					
Supply voltage		V <sub>DD</sub>	- 0.3	5.5	V					
Operation temperature range		T <sub>amb</sub>	- 25	+ 85	°C					
Storage temperature range		T <sub>stg</sub>	- 40	+ 85	°C					
Total power dissipation	$T_{amb} \le 25 \ ^{\circ}C$	P <sub>tot</sub>		50	mW					
Junction temperature		Тj		100	°C					

PARAMETER	TEST CONDITION	SYMBOL	MIN.	TYP.	MAX.	UNIT
Supply voltage V <sub>DD</sub>			2.5		3.6	V
Supply voltage IR anode			2.5		5	V
I <sup>2</sup> C Bus H-level range			1.7		5	V
Current consumption	Standby current, no IRED-operation			1.5	2	μA
Current consumption proximity mode incl. IRED (averaged)	2 measurements per second, IRED current 20 mA			4		μA
	250 measurements per second, IRED current 20 mA			500		μA
	2 measurements per second, IRED current 200 mA			31		μA
	250 measurements per second, IRED current 200 mA			3.8		mA
	2 measurements per second averaging = 1			2.5		μA
Current consumption ambient	8 measurements per second averaging = 1			10		μA
light mode	2 measurements per second averaging = 64			160		μA
	8 measurements per second averaging = 64			635		μA
Ambient light resolution	Digital resolution (LSB count )			0.25		lx
Ambient light output	E <sub>V</sub> = 100 lx averaging = 64			400		counts
I <sup>2</sup> C clock rate range		f <sub>SCL</sub>		T	3400	kHz

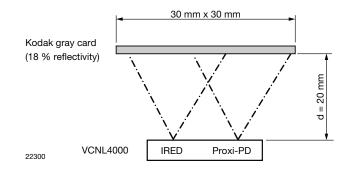
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## CIRCUIT BLOCK DIAGRAM



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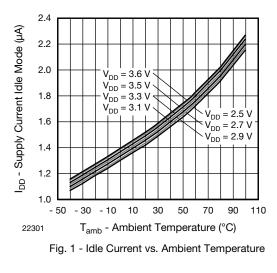
### **TEST CIRCUIT**

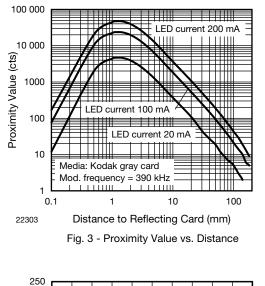


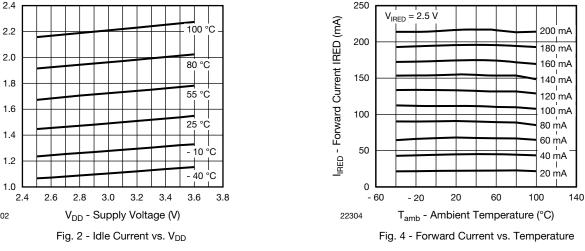
#### Note

 nc must not be electrically connected Pads 8 to 11 are only considered as solder pads

### **BASIC CHARACTERISTICS** (T<sub>amb</sub> = 25 °C, unless otherwise specified)







Rev. 1.8, 10-May-12

22302

IDD - Supply Current Idle Mode (µA)

For technical questions, contact: <u>sensorstechsupport@vishay.com</u>

Document Number: 83798

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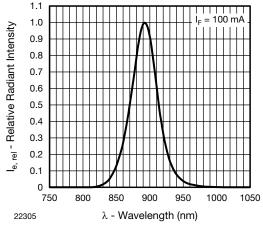


Fig. 5 - Relative Radiant Intensity vs. Wavelength

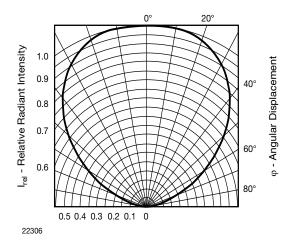


Fig. 6 - Relative Radiant Intensity vs. Angular Displacement

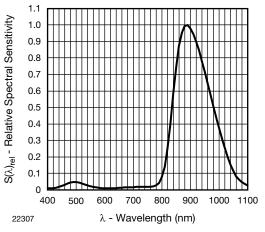


Fig. 7 - Relative Spectral Sensitivity vs. Wavelength

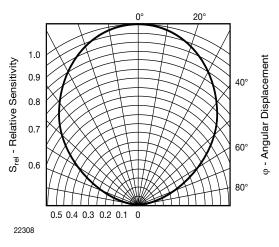


Fig. 8 - Relative Radiant Sensitivity vs. Angular Displacement

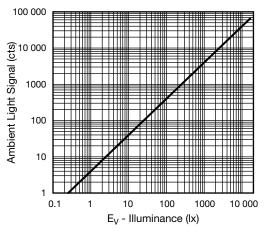


Fig. 9 - Ambient Light Value vs. Illuminance

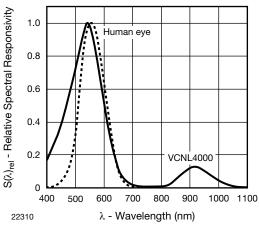
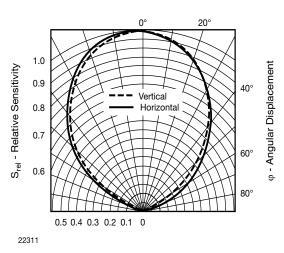


Fig. 10 - Relative Spectral Sensitivity vs. Wavelength

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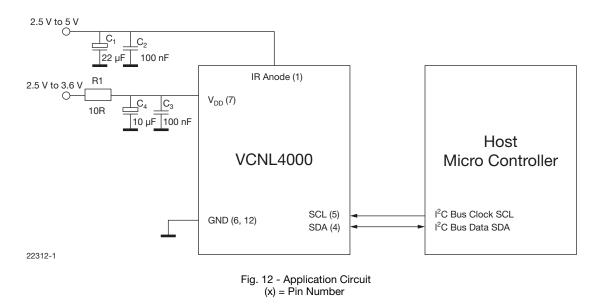
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Fig. 11 - Relative Radiant Sensitivity vs. Angular Displacement

#### **APPLICATION INFORMATION**

VCNL4000 is a cost effective solution of proximity and ambient light sensor with I<sup>2</sup>C Bus interface. The standard serial digital interface is easy to access "Proximity Signal" and "Light Intensity" without complex calculation and programming by external controller.

#### **1. Application Circuit**







#### 2. I<sup>2</sup>C Interface

The VCNL4000 contains twelve 8 bit registers for operation control, parameter setup and result buffering. All registers are accessible via I<sup>2</sup>C communication. Figure 13 shows the basic I<sup>2</sup>C communication with VCNL4000.

The built in I<sup>2</sup>C interface is compatible with all I<sup>2</sup>C modes (standard, fast and high speed).

 $I^2C$  H-level range = 1.7 V to 5 V.

Please refer to the I<sup>2</sup>C specification from NXP for details.

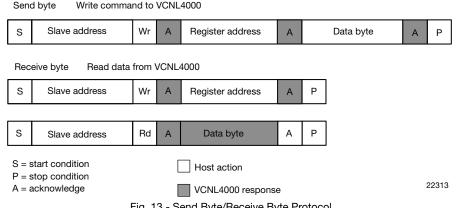


Fig. 13 - Send Byte/Receive Byte Protocol

#### **Device Address**

The VCNL4000 has a fix slave address for the host programming and accessing selection. The predefined 7 bit I<sup>2</sup>C bus address is set to 0010 011 = 13h. The least significant bit (LSB) defines read or write mode. Accordingly the bus address is set to  $0010\ 011x = 26h$  for write, 27h for read.

#### **Register Addresses**

VCNL4000 has twelve user accessible 8 bit registers. The register addresses are 80h (register #0) to 8Bh (register #11).

#### **REGISTER FUNCTIONS**

#### **Register #0 Command Register**

Register address = 80h

The register #0 is for starting ambient light or proximity measurements. This register contains 2 flag bits for data ready indication.

TABLE 1 -	TABLE 1 - COMMAND REGISTER #0										
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0				
config_lock	als_data_rdy	prox_data_rdy	als_od	prox_od	N/A	N/A	N/A				
Description											
config_lock Read only bit. Value = 1											
als_da	als_data_rdy Read only bit. Value = 1 when ambient light measurement data is available in the result registers. This will be reset when one of the corresponding result registers (reg #5, reg #6) is read.										
prox_d	lata_rdy	Read only bit. Val		imity measuremer the corresponding							
als	als_od R/W bit. Starts a single on-demand measurement for ambient light. If averaging is enabled, starts a sequence of readings and stores the averaged result. Result is available at the end of conversion for reading in the registers #5(HB) and #6(LB).										
prox_od R/W bit. Starts a single on-demand measurement for proximity. Result is available at the end of conversion for reading in the registers #7(HB) and #8(LB).							nd #8(LB).				

#### Notes

After a proximity start command [prox\_od] a WAIT time of  $\geq$  400 µs should be inserted before any read out commands.

With setting bit 3 and bit 4 at the same write command, a simultaneously measurement of ambient light and proximity is done.



#### **Register #1 Product ID Revision Register**

Register address = 81h. This register contains information about product ID and product revision. Register data value of current revision = 11h.

TABLE 2 -	TABLE 2 - PRODUCT ID REVISION REGISTER #1										
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3 Bit 2 Bit 1 Bit 0							
	Produ	uct ID	•	Revision ID							
			Descr	iption							
Prod	uct ID										
Revision ID				Read only bits. Value = 1							

#### **Register #2 without Function in Current Version**

Register address = 82h.

#### **Register #3 LED Current Setting for Proximity Mode**

Register address = 83h. This register is to set the LED current value for proximity measurement.

The value is adjustable in steps of 10 mA from 0 mA to 200 mA.

This register also contains information about the used device fuse program ID.

TABLE 3 -	TABLE 3 - IR LED CURRENT REGISTER #3										
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0				
Fuse prog ID IR LED current value											
Description											
Fuse p	Fuse prog ID       Read only bits.         Information about fuse program revision used for initial setup/calibration of the device.						e device.				
R/W bits. IR LED current = Value (dec.) x 10 mA.IR LED current valueValid Range = 0 to 20d. e.g. 0 = 0 mA , 1 = 10 mA,, 20 = 200 mA (2 = 20 mA = DEFAULT)LED Current is limited to 200 mA for values higher as 20d.							DEFAULT)				

#### **Register #4 Ambient Light Parameter Register**

Register address = 84h.

TABLE 4 -	AMBIENT LI	GHT PARAM	ETER REGIS	TER #4					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0		
Cont. conv. mode		N/A		Auto offset compensation		Averaging function (number of measurements per run)			
			Desc	ription					
=-	t 7 ersion mode	This functior	n can be used for	R/W bit. Continuous conversion mode. Enable = 1; Disable = 0 = DEFAULT r performing faster ambient light measurements. Please refer to the formation chapter 3.3 for details about this function.					
Bit 3 Auto offset compensation With active auto offset compensati				W bit. Automatic offset compensation. Enable = 1 = DEFAULT; Disable = 0 ology, package or temperature related drift of the ambient light values built in automatic offset compensation function. tion the offset value is measured before each ambient light measurement ubtracted automatically from actual reading.					
Bit U to Dit 2				R/W bits. Averaging function. single conversions done during one measurement cycle. Result is the average value of all conversions. lecimal_value e.g. 0 = 1 conv., 1 = 2 conv, 2 = 4 conv.,7 = 128 conv. DEFAULT = 32 conv.					

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#### Register #5 and #6 Ambient Light Result Register

Register address = 85h and 86h. These registers are the result registers for ambient light measurement readings. The result is a 16 bit value. The high byte is stored in register #5 and the low byte in register #6.

TABLE 5 - AMBIENT LIGHT RESULT REGISTER #5									
Bit 7	Bit 7       Bit 6       Bit 5       Bit 4       Bit 3       Bit 2       Bit 1       Bit 0								
Description									
Read only bits. High byte (15:8) of ambient light measurement result									

TABLE 6 -	TABLE 6 - AMBIENT LIGHT RESULT REGISTER #6										
Bit 7	Bit 7       Bit 6       Bit 5       Bit 4       Bit 3       Bit 2       Bit 1       Bit 0										
	Description										
	Read only bits. Low byte (7:0) of ambient light measurement result										

#### Register #7 and #8 Proximity Measurement Result Register

Register address = 87h and 88h. These registers are the result registers for proximity measurement readings. The result is a 16 bit value. The high byte is stored in register #7 and the low byte in register #8.

TABLE 7 - PROXIMITY RESULT REGISTER #7										
Bit 7	Bit 7       Bit 6       Bit 5       Bit 4       Bit 3       Bit 2       Bit 1       Bit 0									
Description										
	Read only bits. High byte (15:8) of proximity measurement result									

TABLE 8 - PROXIMITY RESULT REGISTER #8										
Bit 7	Bit 7       Bit 6       Bit 5       Bit 4       Bit 3       Bit 2       Bit 1       Bit 0									
Description										
Read only bits. Low byte (7:0) of proximity measurement result										

#### **Register #9 Proximity Measurement Signal Frequency**

Register address = 89h.

TABLE 9 - PROXIMITY MEASUREMENT SIGNAL FREQUENCY #9											
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0				
		Proximity frequency									
Description											
Bit 0 and 1 Proximity frequency		R/W bits. Setting the proximity IR test signal frequency. The proximity measurement is using a square IR signal as measurement signal. Four different values are possible: 00 = 3.125 MHz 01 = 1.5625 MHz 02 = 781.25 kHz (DEFAULT) 03 = 390.625 kHz									



#### **Register #10 Proximity Modulator Timing Adjustment**

Register address = 8Ah.

TABLE 10 - PROXIMITY MODULATOR TIMING ADJUSTMENT #10											
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0				
Modulation delay time			N/A		Modulation dead Time						
Description											
Modulation	ı delay time	R/W bits. Setting a delay time between IR LED signal and IR input signal evaluation. This function is for compensation of delays from IR LED and IR photo diode. Also in respect to the possibility for setting different proximity signal frequency. Correct adjustment is optimizing measurement signal level.									
Modulation	dead Time	R/W bi	bits. Setting a dead time in evaluation of IR signal at the slopes of the IR signal. This function is for reducing of possible disturbance effects. This function is reducing signal level and should be used carefully.								

Note

• The settings for best performance will be provided by Vishay. With first samples this is evaluated to: delay time = 4 and dead time = 1, with that register #10 should be programmed with: 129 (dez.)

#### Register #11 Ambient IR Light Level Register

Register address = 8Bh.

This register is not intended to be used by customer.

## **3. IMPORTANT APPLICATION HINTS AND EXAMPLES**

#### 3.1 Receiver standby mode

In standby mode the receiver has the lowest current consumption of about 1.5  $\mu$ A. In this mode only the I<sup>2</sup>C interface is active. This is always valid, when there are no measurement demands for proximity and ambient light executed. Also the current sink for the IR-LED is inactive, so there is no need for changing register #3 (IR LED current).

#### 3.2 Data Read

In order to get a certain register value, the register has to be addressed without data like shown in the following scheme. After this register addressing, the data from the addressed register is written after a subsequent read command.

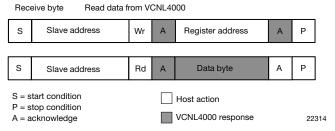


Fig. 14 - Send Byte/Receive Byte Protocol

The stop condition between these write and read sequences is not mandatory. It works also with a repeated start condition.

#### Note

• For reading out 2 (or more) subsequent registers like the result registers, it is not necessary to address each of the registers separately. After one read command the internal register counter is increased automatically and any subsequent read command is accessing the next register.

Example: read register "Ambient Light Result Register" #5 and #6:

Addressing:command: 26h, 85h (VCNL4000\_l<sup>2</sup>C\_Bus\_Write\_Adr., Ambient Light Result Register #5 [85])

Read register #5:command: 27h, data (VCNL4000\_I<sup>2</sup>C\_Bus\_Read\_Adr., {High Byte Data of Ambient Light Result Register #5 [85])} Read register #6:command: 27h, data (VCNL4000\_I<sup>2</sup>C\_Bus\_Read\_Adr., {Low Byte Data of Ambient Light Result Register #6 [86])}

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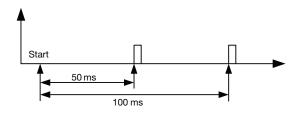
#### 3.3 Continuous Conversion Mode in Ambient Light Measurement

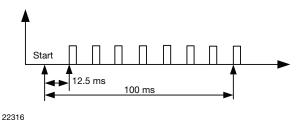
In the following is a detail description of the function "continuous conversion" (bit 7 of register #4)

#### Standard mode (bit 7 of reg #4 = 0):

In standard mode the ambient light measurement is done during a fixed time frame of 100 ms. The single measurement itself takes actually only appr. 300 µs.

The following figures show examples of this measurement timing in standard mode using averaging function 2 and 8 as examples for illustration (possible values up to 128).





22315

Fig. 15 - Ambient Light Measurement with Averaging = 2; Final Measurement Result = Average of these 2 Measurements Fig. 16 - Ambient Light Measurement with Averaging = 8; Final Measurement Result = Average of these 8 Measurements

#### Note

• ≥ Independent of setting of averaging the result is available only after 100 ms.

#### Continuous conversion mode (bit7 of reg #4 = 1):

In continuous conversion mode the single measurements are done directly subsequent after each other.

See following examples in figure 17 and 18

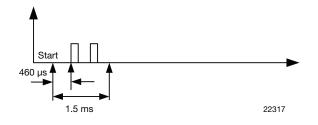
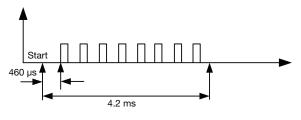


Fig. 17 - Ambient Light Measurement with Averaging = 2; using Continuous Conversion Mode



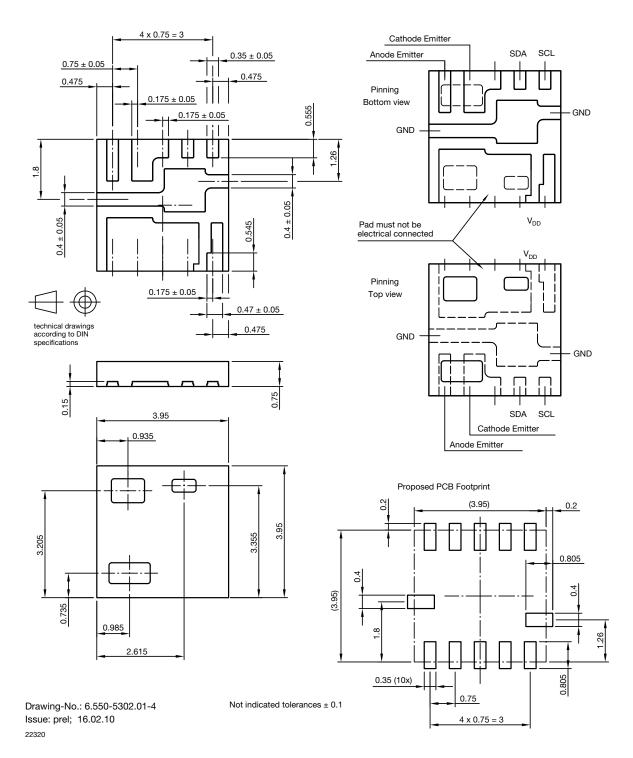
22318

Fig. 18 - Ambient Light Measurement with Averaging = 8; using Continuous Conversion Mode



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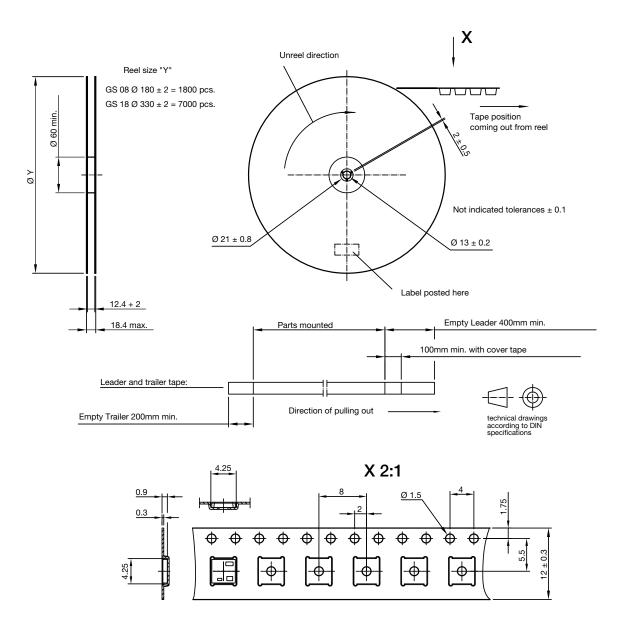
## **PACKAGE DIMENSIONS** in millimeters



11



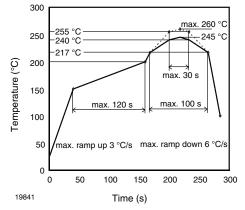
#### TAPE AND REEL DIMENSIONS in millimeters



Drawing-No.: 9.800-510301-4 Issue: prel; 02.12.09 22319



## SOLDER PROFILE



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Fig. 19 - Lead (Pb)-free Reflow Solder Profile acc. J-STD-020

#### DRYPACK

Devices are packed in moisture barrier bags (MBB) to prevent the products from moisture absorption during transportation and storage. Each bag contains a desiccant.

## FLOOR LIFE

Floor life (time between soldering and removing from MBB) must not exceed the time indicated on MBB label:

Floor life: 168 h

Conditions:  $T_{amb}$  < 30 °C, RH < 60 %

Moisture sensitivity level 3, acc. to J-STD-020.

#### DRYING

In case of moisture absorption devices should be baked before soldering. Conditions see J-STD-020 or label. Devices taped on reel dry using recommended conditions 192 h at 40 °C (+ 5 °C), RH < 5 %.