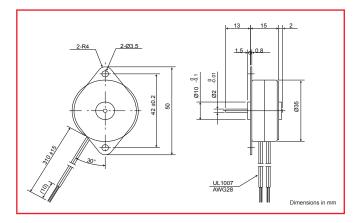


# Synchronous Motors PTM-24T





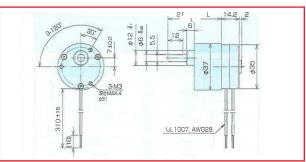
# **Specifications**

<u>-</u>					
Specifications	Units	PTM-24T			
Rated Voltage	V	24 ±10%			
Frequency	Hz	50/60			
Rated Current	mA	68/70			
Revolutions	rpm	250/300			
Rotating Direction		Dual Direction (CC/CCW)			
Torque @ 60Hz	mN⋅m	9/9.5			
Temperature Rise	К	55			
Operating Temp. Range	°C	-10 to +50			
Dielectric Strength	V	500Vac for 1 min			
Weight	g	77			
Capacitor	μF	3.3			

Magnet type: Anisotropic

# **Geared Models**

## PTM-24TG



# **Geared Motor Torque Characteristics**

Model		PTM-24TG					
Speed	Torque (	Torque (mN·m)		Gear Ratio			
rpm	50Hz	60Hz	50Hz	60Hz			
60		30		1/5			
30		60		1/10			
20		72		1/15			
10	115	145	1/25	1/30			
5	180	230	1/50	1/60			
4		290		1/75			
3		300*		1/100			
2	365	465	1/125	1/150			
1		600*		1/300			

RPM	L			
60				
30	10 5			
20	19.5mm			
10				
5				
4	21.7mm			
3				
2	23.8mm			
1	23.0MM			

\*Values regulated by normal gear strength. Do not apply any load exceeding the normal gear strength.

## **Dual Direction Synchronous Motors**

PTM(C) - 24 F 3 4 G 1/2

#### 1 - Series Designation

PTM: Flying lead joint type PTMC: Connector joint type

#### 2 - Number of Poles

12: Speed is 500 rpm w/50Hz Speed is 600 rpm w/60Hz24: Speed is 250 rpm w/50Hz Speed is 300 rpm w/60Hz

#### 3 - Outer Diameter (Type)

P: 22mm, M: 35mm, T: 35mm (thin), H: 42mm, S: 42mm (thin), F: 55mm, R: 55mm (w/ connector)

#### 4 - Coil Specification

Blank: Standard Coil

(continuous for 24, 100, 200 Vac) 1-18: Coil # for specific rating

#### 5 - Magnet Type

Blank: Anisotropic

- 3: Isotropic
- 4: Neodymium
- 5: Plastic

#### 6 - Gear Head

Blank: No Gear Head G: Gear Head Integrated

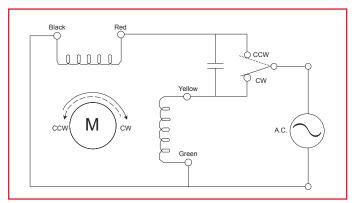
#### 7 - Gear Ratio

see chart below

Gear Ratio	rpm w/12 poles		rpm w/24 poles			
Gedi Ralio	50Hz	60Hz	50Hz	60 Hz		
Motor only	500	600	250	300		
1/10	50	60	25	30		
1/50	10	12	5	6		
1/100	5	6	2.5	3		

## **Dual Direction Synchronous Motors**

Motors that move in two directions are capacitor-based phase advancing motors. Because the rotor is moved by shifting the phase current by  $90^{\circ}$  it is essential for the circuit to have a capacitor. The proper wiring is below.



As viewed from the output shaft of the motor

# **About Synchronous Motors**

## **No Power or Load Fluctuation Effect**

Synchronous motors rotate in synch with supplied power frequency. If power frequency is constant, the motor will rotate at a constant speed (synchronized speed).

### **Impedance Protected**

Unless otherwise stated, these motors provide high electrical resistance, which prevents overcurrent from flowing to the motor, which would in turn burn the coils.

#### **No Control Circuit Required**

Because these motors are AC motors, they start rotating when a power connection is made.

#### **Excellent Response**

The type of magnet used in these motors ensures excellent response and also ensures the motor will start and stop immediately when power is supplied or removed.