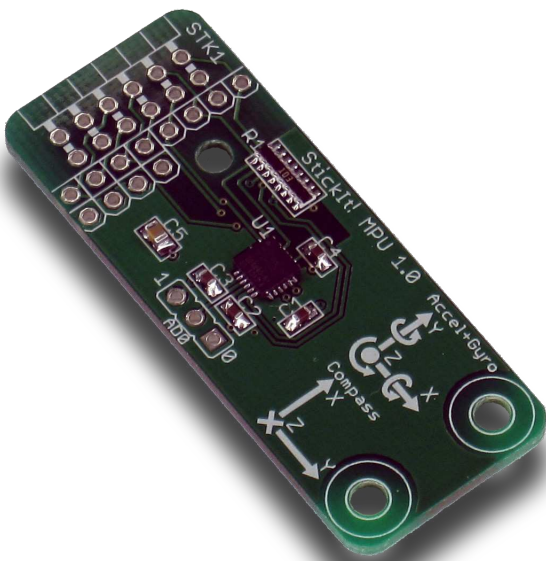


StickIt! MPU-6050 Manual

*How to install and use your new
StickIt! MPU-6050 Module*



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StickIt! MPU-6050 Manual
MAN011 (V1.0) January 5, 2014

The following table shows the revision history for this document.

| Date | Version | Revision |
|----------|---------|--|
| 01/05/14 | 1.0 | Initial release for StickIt! MPU-6050 module V1.0. |
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C.1 Preliminaries

Here's some helpful information before getting started.

Getting Help!

Here are some places to get help if you encounter problems:

- If you can't get the StickIt! MPU-6050 module to work, send an e-mail message describing your problem to help@xess.com or submit a problem report at <http://www.xess.com/help.php>.
- Our web site also has
 - answers to frequently-asked-questions,
 - example designs, application notes and tutorials,
 - a forum where you can post questions.

Take Notice!

This module is meant to be powered by 3.3V and should only be powered by 3.3V.

Packing List

Here is what you should have received in your package:

- a StickIt! MPU-6050 module.
- PMOD™ male header.
- Wing male headers (8-pin & 4-pin).

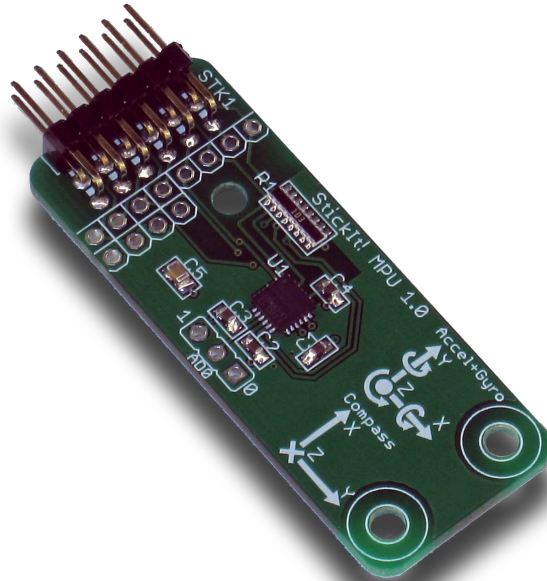
C.2 Setup

The StickIt! MPU-6050 module contains an [integrated three-axis accelerometer, three-axis gyroscope and temperature sensor](#) that connects to an eight-bit PMOD or a Wing socket on your StickIt! board.

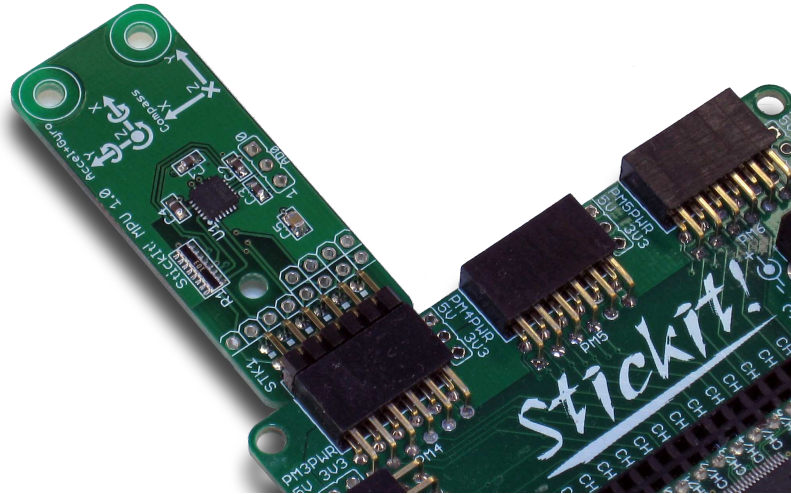
Inserting Your StickIt! MPU-6050 Module Into Your StickIt! Board

Inserting Into a PMOD Socket

To use the StickIt! MPU-6050 module with a PMOD socket, first solder the included male PMOD header to the module as shown. (**To insure a stable connection, only use a header with 0.025" square pins.**)

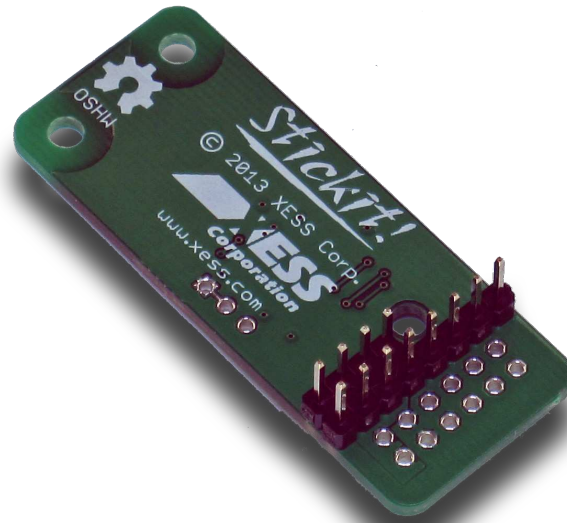


Then insert the module into one of the PMOD sockets on the StickIt! Board.

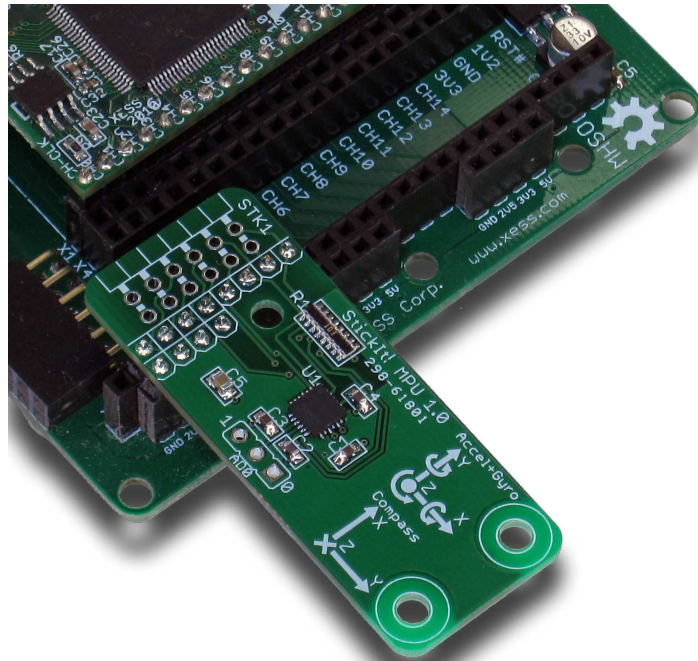


Inserting Into a Wing Socket

To use the StickIt! MPU-6050 module with a Wing socket, first solder the included male Wing headers to the module as shown. (**To insure a stable connection, only use a header with 0.025" square pins.**)



Then insert the module into one of the eight-bit Wing sockets on the StickIt! board.



Setting the Address Jumper

The AD0 jumper sets the least-significant bit of the MPU-6050 I²C address. By default, the jumper is set to 0 (giving an address of 0x68) by a shorting trace on the backside of the PCB. This trace must be cut if you want to change the address to 0x69 by placing a shunt on the '1' position of AD0.

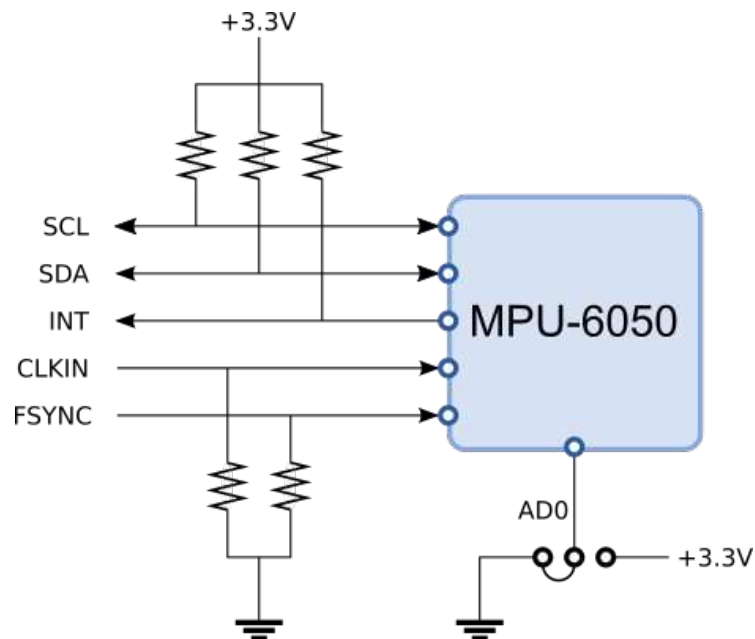


C.3 Operation

This chapter describes the operation of the StickIt! MPU-6050 module using a simplified schematic. You can find a complete [schematic](#) at the end of this manual.

There are six pins of the MPU chip that you can control. The SCL and SDA pins provide the main I²C communication path to-and-from the chip. The AD0 jumper sets the I²C address to be either 0x68 or 0x69. Most of your interactions with the MPU will occur through the I²C interface.

The use of the remaining pins is optional. An interrupt output (INT) can be used to alert external systems about changes sensed by the MPU. The internal clock of the chip can be overridden by a clock signal supplied on the CLKIN input. The FSYNC input can be used to synchronize the MPU with external systems.



C.4 Using the Module

To use the StickIt! MPU-6050 module, you will need to do the following:

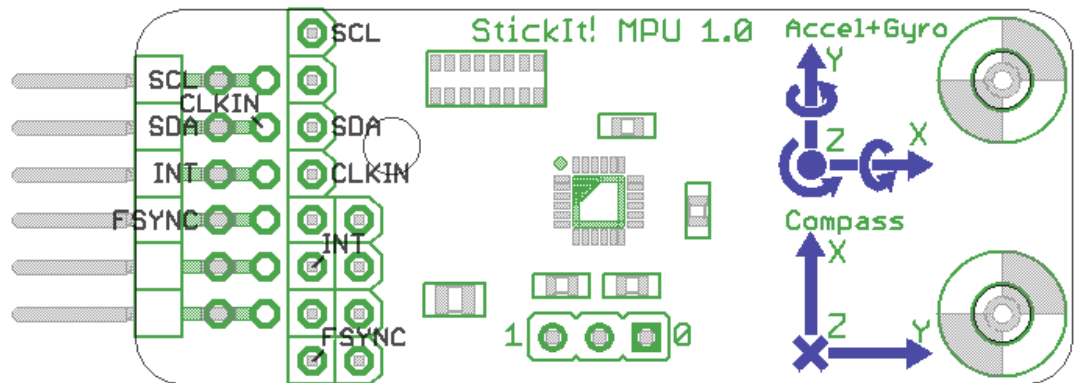
- Create a Xilinx ISE FPGA project that contains (among other things) an I²C master module for controlling the MPU and reading the accelerometer, gyroscope and temperature sensors. The project can also have circuitry for handling the INT, CLKIN and FSYNC pins of the MPU, but it's not necessary. You will find the information in the MPU-6050 [datasheet](#) and [register map](#) invaluable for this portion of the design process.
- Allocate from two to five pins to connect to the I/O signals (at least SCL and SDA) of the module.
- Attach the module to either a PMOD or Wing socket on the StickIt! board.
- Determine the channel signals on the PMOD or Wing socket that connect to each I/O pin of the module.
- Find which FPGA pin of the XuLA board connects to each channel signal. (You can find this information in the StickIt! Board manual.)
- Make a UCF file associating each FPGA pin with an I/O pin of the module.
- Include the UCF file in your ISE project.

That's a lot of work, so we've built an example for you. Just go to <http://github.com/xesscorp/StickIt>. There, you will find a subdirectory with a Xilinx ISE project that includes:

- an example that gets the accelerometer, gyroscope and temperature sensor readings from the MPU and sends them back to the PC through the USB link,
- a UCF file containing the FPGA pin assignments to use when installing the StickIt! MPU-6050 module into any of the PMOD or Wing sockets,
- and a Python file that queries the MPU sensor readings and displays them on the PC.

A.1 I/O Locations

The connections of the PMOD and Wing header I/O signals to the MPU chip on the StickIt! MPU-6050 module are shown below.



A.2 Schematic

