

MiraBox User Guide

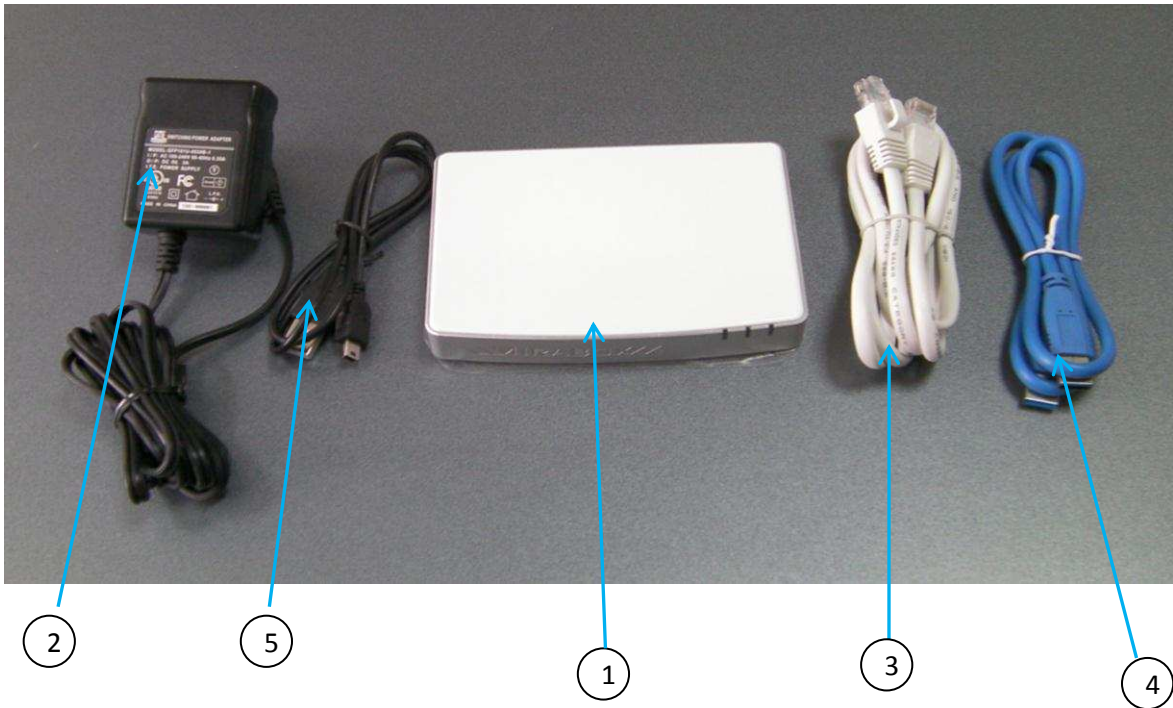
-Sep18, 2012

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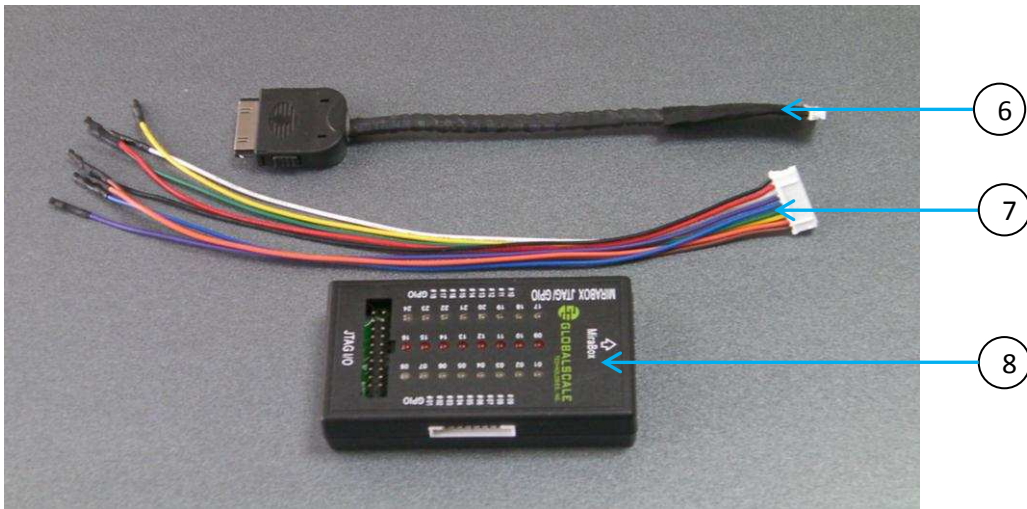
A. Package contents

1 • Standard package contents



	MiraBoxstandard content List		Remark
1	MiraBox	1 unit	Mirabox main unit
2	AC-DC Power Adapter	1 pc	Input 90-240VAC / output 5V,3A DC
3	Ethernet Cable	1 pc	Cat 5e
4	USB3.0 Cable	1 pc	
5	Mini-USB Cable	1 pc	For debug console use
6	Quick reference card	1 pc	
7	Warranty card	1 pc	

2. Optional package contents



MiraBox Optional Content List			
6	Multi I/O Cable	1 pc	Connect from MiraBox to JTAG/GPIO box
7	GPIO Cable	1 pc	For GPIO port connection
8	MiraBox JTAG/GPIO box	1 pc	External JTAG/GPIO box for debugging

B. MiraBox appearance and connecting ports



6

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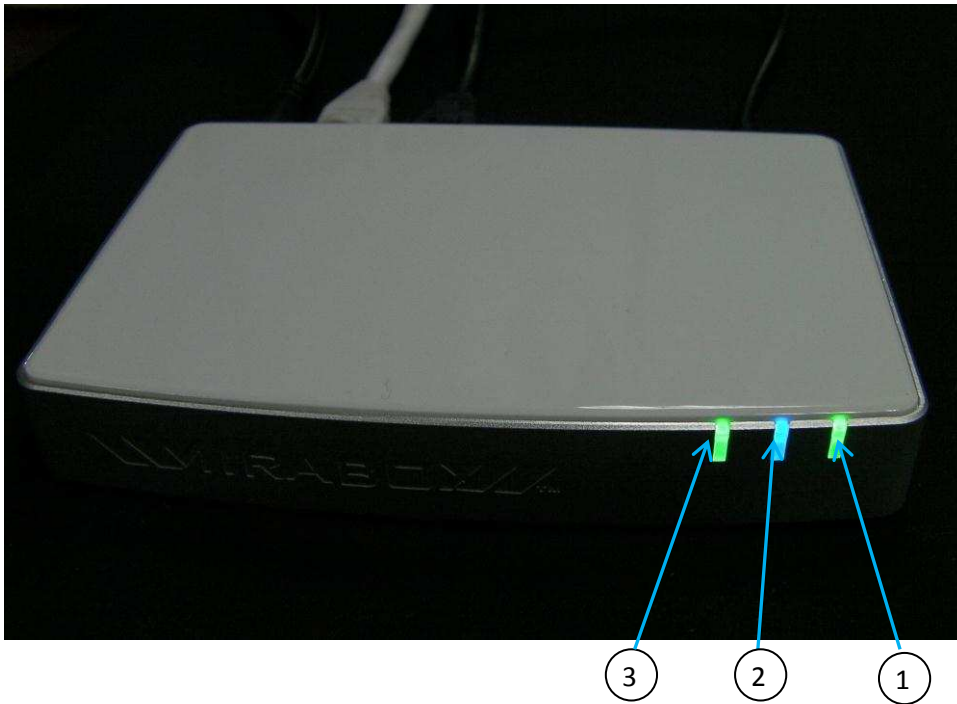
1



Mirabox ports description

	Connection port	Description	Remark
1	Power Port	DC 5V/3A port	
2	RJ45 #1	Gigabit Ethernet port1	
3	RJ45 #2	Gigabit Ethernet port2	
4	USB 3.0 port#1	USB 3.0 high speed host	
5	USB 3.0 port#2	USB 3.0 high speed host	
6	Mini USB console port	Debug console	Connect to PC USB port
7	Multi-I/O port	JTAG and GPIO port	Connect to external JTAG/GPIO box for system development.
8	Micro SD slot	External Micro-SD slot	
9	Reset button hole	System reset button	Reset through GPIO

C. LED indication



LED indication table

	LED	Color/ Pattern	Description
1	Power on LED	Solid green	Upon power on, this LED lights up
2	WiFi AP	Blinking blue	Indicate WiFi AP mode is activated as default after boot up
		Off	WiFi AP mode is not activated
3	WiFi client	Blinking green	WiFi client mode is activated
		Off	WiFi client mode is not activated

D. System console and debugging

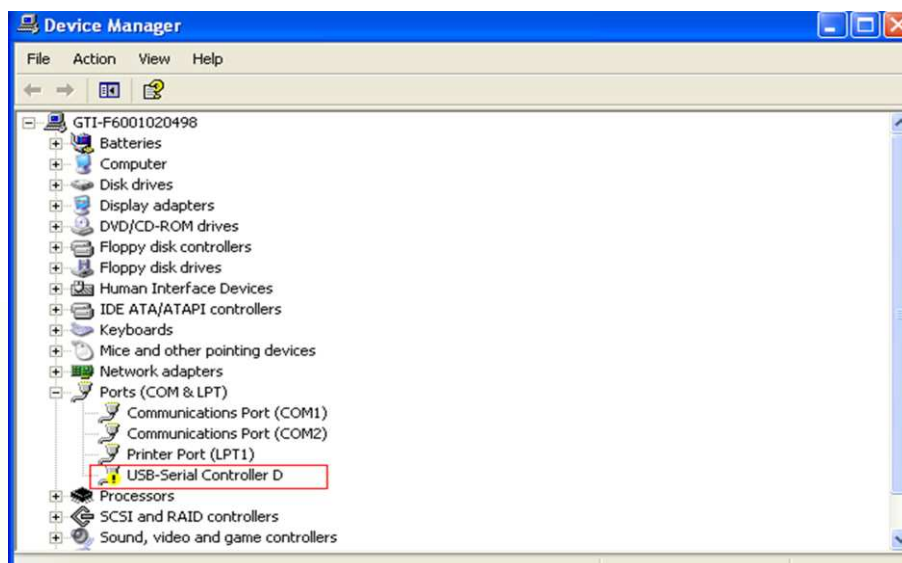
1. Driver and tool installation.

- (1) Prepare one Windows PC
- (2) Download the serial communication tool “putty.exe”.
- (3) Download the driver “2KXPVDock.exe”forProlific-USB-to-Serial-Comm-Portat our Website.
<http://www.globalscaletechnologies.com/t-downloads.aspx>
- (4) Install driver on your PC (only for the first time)

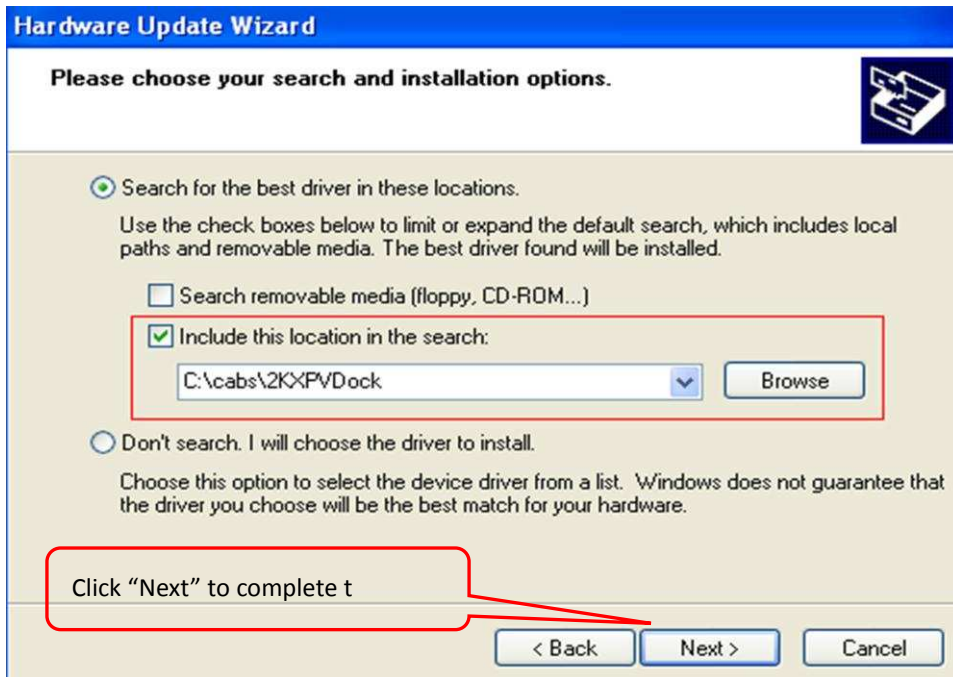
- (4-1) Connect Mirabox to your Windows PC



- (4-2) The first time when you connect Mirabox to the Windows computer you will be asked to install the driver

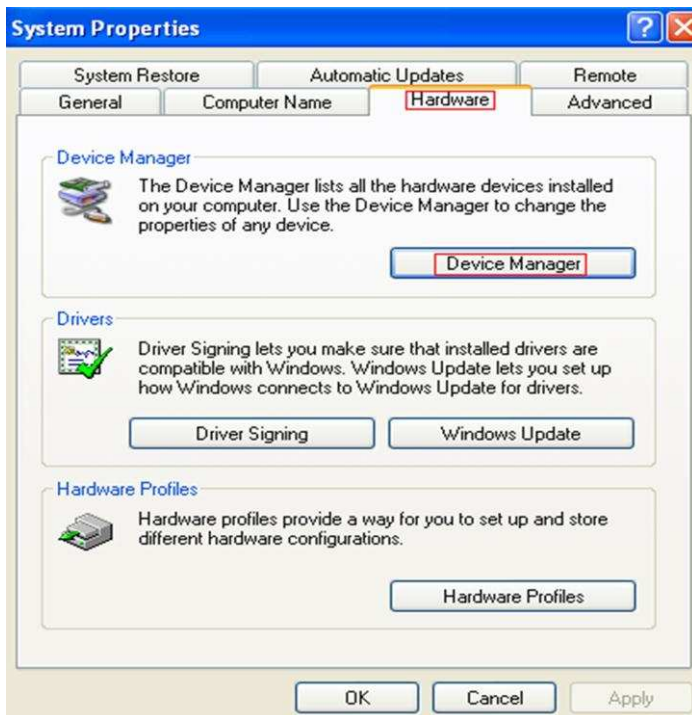


(4-3) Run file “2KXPVDock.exe”and the driver will be installed to the PATH C:\cabs\2KXPVDock”.

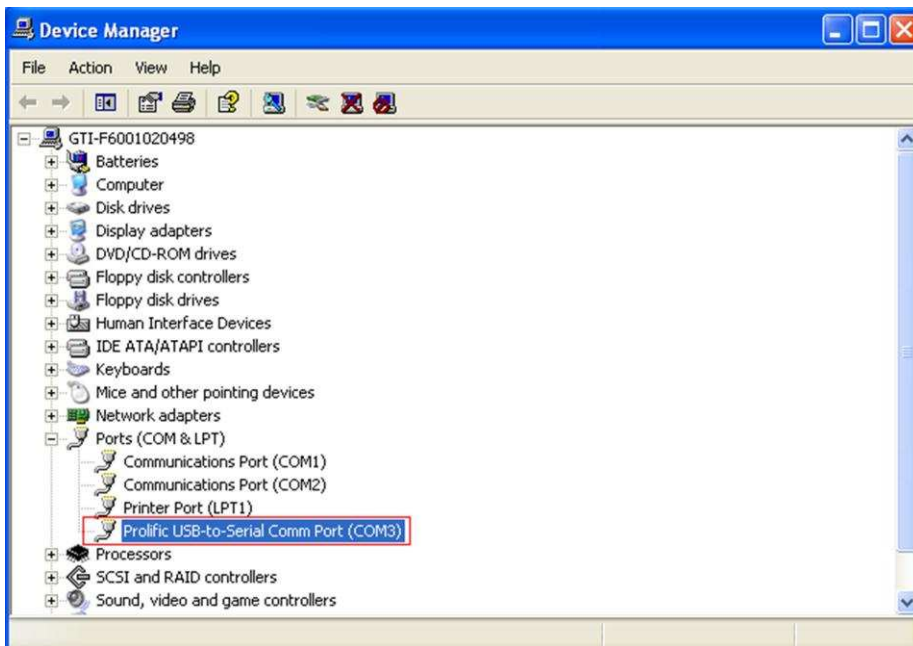


(5) Find out the com port of your debugger on your windows PC.

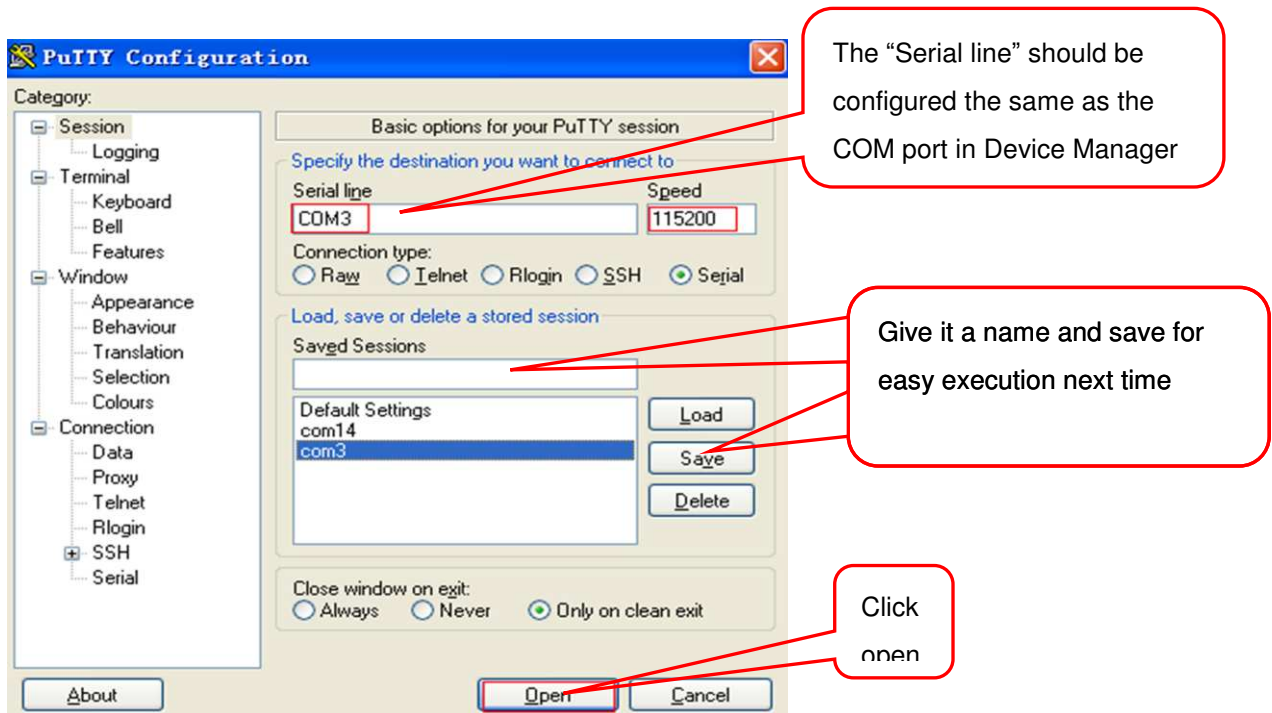
(5-1) Right click [My Computer] → [Properties] → [Hardware] → [Device Manager]



(5-2) Find out your com port as below (here is com3 for example)



(6) Run “putty.exe” and configure as below on your Windows PC.



2. Debugging console.

(1) Power on the MiraBox and you will see messages on screen as below

```

U-Boot 2009.08 (Sep 16 2012 - 22:50:06) Marvell version: 1.1.2 NQ
U-Boot Addressing:
    Code:          00600000:006AFFFO
    BSS:           006F8E40
    Stack:         0x5fff70
    PageTable:     0x8e0000
    Heap address:  0x900000:0xe00000
Board: DB-88F6710-BP
SoC:  MV6710 A1
CPU:  Marvell PJ4B v7 UP (Rev 1) LE
      CPU @ 1200Mhz, L2 @ 600Mhz
      DDR @ 600Mhz, TClock @ 200Mhz
      DDR 16Bit Width, FastPath Memory Access
PEX 0: Detected No Link.
PEX 1: Root Complex Interface, Detected Link X1
DRAM:  1 GB
      CS 0: base 0x00000000 size 512 MB
      CS 1: base 0x20000000 size 512 MB
      Addresses 14M - 0M are saved for the U-Boot usage.
NAND:  1024 MiB
Bad block table found at page 262016, version 0x01
Bad block table found at page 261888, version 0x01
FPU not initialized
USB 0: Host Mode
USB 1: Host Mode
Modules/Interfaces Detected:
    RGMII0 Phy
    RGMII1 Phy
    PEX0 (Lane 0)
    PEX1 (Lane 1)
phy16= 72
phy16= 72
MMC:  MRVL_MMC: 0
Net:  egiga0 [PRIME], egiga1
Hit any key to stop autoboot:  0
Marvell>>

```

(2) You can press any key to stop auto-boot when you see the bootdelay timer is counting down.

After entering the uboot prompt, you can also change the uboot environment variables such as bootdelay time, ipaddr, serverip and so on.

(3) If no key was pressed to interrupt the uboot, it will continue running to the login screen where urges you to input the login name and password, here is the default login information.

Login :[root](#)

Password: [nosoup4u](#)

```

Bluetooth: BNEP (Ethernet Emulation) ver 1.3
=====
BT does not work by default, please execute the following command to enable
turnon_bt.sh----on, turnoff_bt.sh----off
=====
Bluetooth: SCO (Voice Link) ver 0.6
Bluetooth: SCO socket layer initialized

Debian GNU/Linux 6.0 mirabox-debian ttyS0
mirabox-debian login:

```

(4) Now you are the root user and have the full control of the mirabox

3. WiFi AP mode testing

MiraBox Server has a built-in WiFi module which is in compliance with 802.11 b/g/n standard. The WiFi can work as client or AP mode but only one at a time. The default mode is AP mode every time when it powers on, and the indication light D6 is blinking blue.

Here are steps for testing:

(1) Enter command and you will see message for uap0 device.

ifconfig

```

root@mirabox-debian:~# ifconfig
eth0      Link encap:Ethernet  HWaddr f0:ad:4e:01:a3:ea
          UP BROADCAST MULTICAST  MTU:1500  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:512
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)
          Interrupt:8

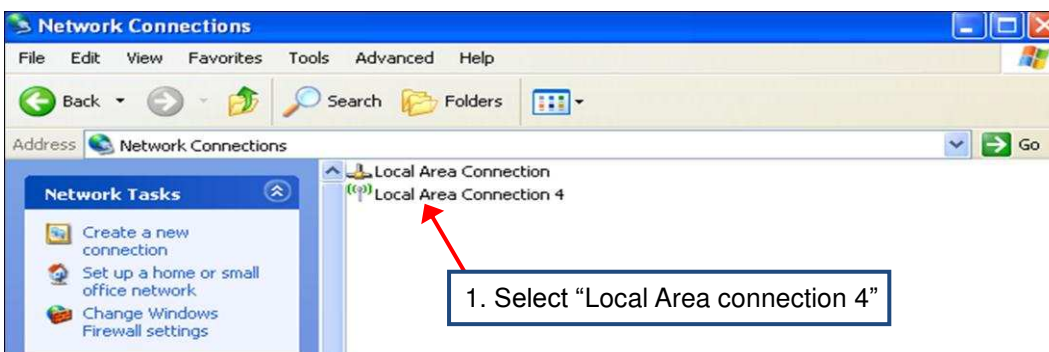
eth1      Link encap:Ethernet  HWaddr f0:ad:4e:01:a3:eb
          UP BROADCAST MULTICAST  MTU:1500  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:512
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)
          Interrupt:10

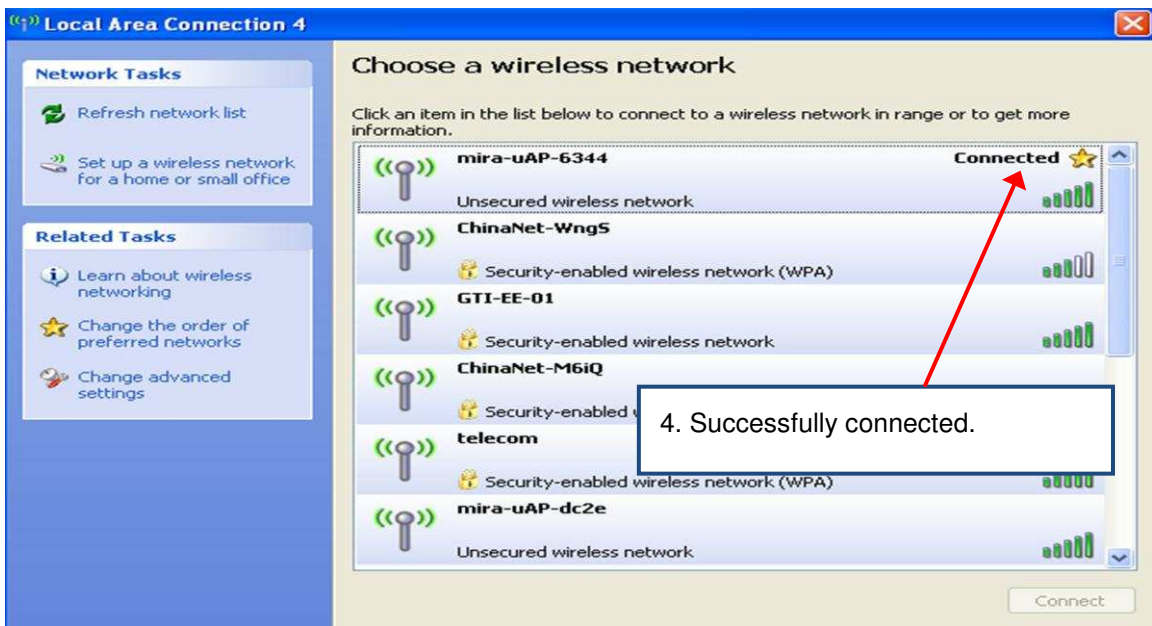
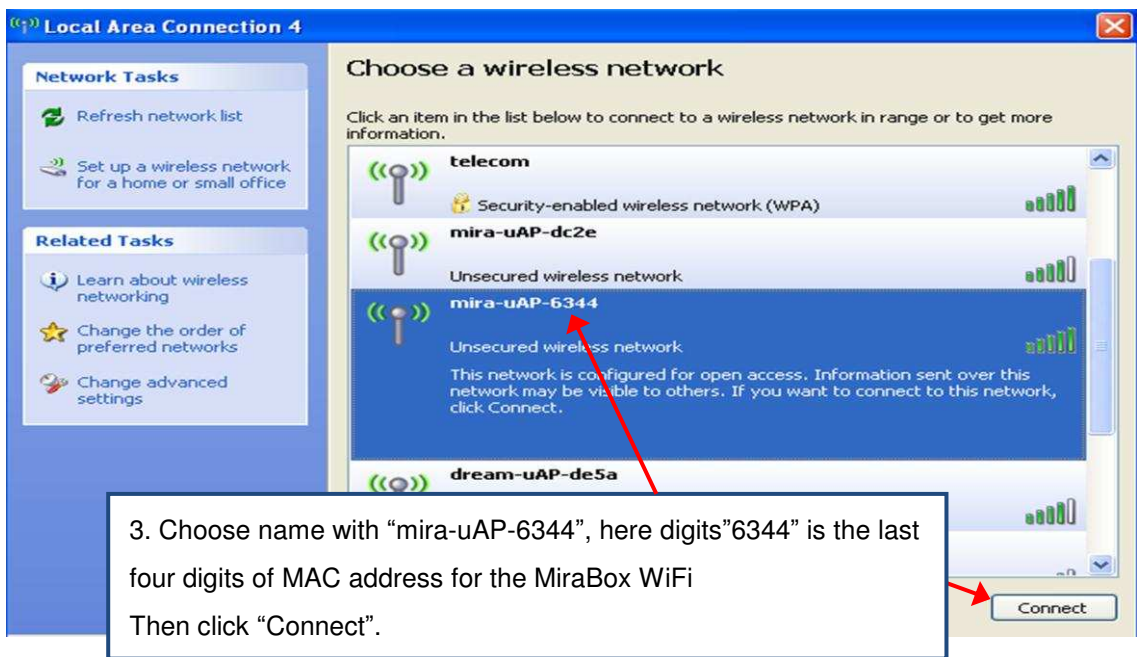
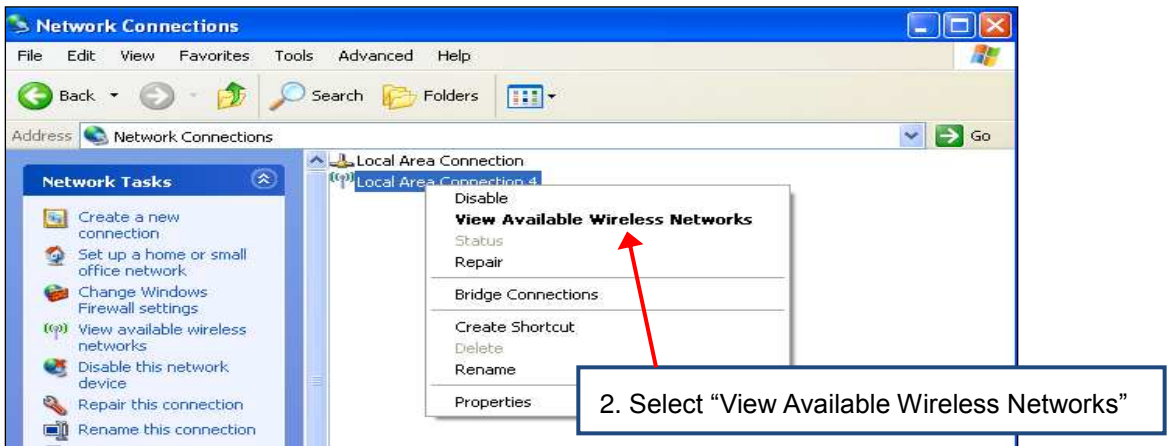
lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          inet6 addr: ::1/128 Scope:Host
          UP LOOPBACK RUNNING  MTU:16436  Metric:1
          RX packets:8 errors:0 dropped:0 overruns:0 frame:0
          TX packets:8 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:480 (480.0 B)  TX bytes:480 (480.0 B)

uap0     Link encap:Ethernet  HWaddr 00:90:a2:4a:63:44
          inet addr:192.168.1.1  Bcast:192.168.1.255  Mask:255.255.255.0
          UP BROADCAST MULTICAST  MTU:1500  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)
    
```

(2) Prepare one computer installed with a Wi-Fi Lan card, here we use a computer with a Windows XP operating system for example.

(3) Go to “Network Connections” as shown below..





4. WIFI Client mode testing

- (1) Switch to WiFi client mode by giving command as following.

```
# wlan.sh
```

```
root@mirabox-debian:~# wlan.sh
Stopping very small Busybox based DHCP server: Stopped /usr/sbin/udhcpd (pid 1911).
udhcpd.
Stopping DNS forwarder and DHCP server: dnsmasq.
WLAN FW already running! Skip FW download
WLAN FW is active
ADDRCONF(NETDEV_UP): wlan0: link is not ready
```

When done successfully, the LED(D7) is blinking green and wlan0 is activated.

- (2) To check wlan0 with ifconfig command

```
# ifconfig
```

```
root@mirabox-debian:~# ifconfig
eth0      Link encap:Ethernet  HWaddr f0:ad:4e:01:a3:ea
          UP BROADCAST MULTICAST  MTU:1500  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:512
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)
          Interrupt:8

eth1      Link encap:Ethernet  HWaddr f0:ad:4e:01:a3:eb
          UP BROADCAST MULTICAST  MTU:1500  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:512
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)
          Interrupt:10

lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          inet6 addr: ::1/128 Scope:Host
          UP LOOPBACK RUNNING  MTU:16436  Metric:1
          RX packets:8 errors:0 dropped:0 overruns:0 frame:0
          TX packets:8 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:480 (480.0 B)  TX bytes:480 (480.0 B)

wlan0     Link encap:Ethernet  HWaddr 00:90:a2:4a:63:44
          UP BROADCAST MULTICAST  MTU:1500  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)
```


(4) Connect to WiFi AP

```
# iwconfig wlan0 essid<AP's ID>
# dhclient wlan0
# ifconfig wlan0
#ping 192.168.1.1
```

The below screenshot is an example for how to connect a wlan device. If you can see IP address (for example: 192.168.1.102) means you have already connected and got an IP.

```
root@mirabox-debian:~# iwconfig wlan0 essid "dream-uAP-de5a"
ADDRCONF (NETDEV_CHANGE): wlan0: link becomes ready
root@mirabox-debian:~# dhclient wlan0
Reloading /etc/samba/smb.conf: smbd only.
root@mirabox-debian:~# ifconfig wlan0
wlan0      Link encap:Ethernet  HWaddr 00:90:a2:4a:63:44
          inet addr:192.168.1.102  Bcast:192.168.1.255  Mask:255.255.255.0
          inet6 addr: fe80::290:a2ff:fe4a:6344/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:5 errors:0 dropped:0 overruns:0 frame:0
          TX packets:31 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:794 (794.0 B)  TX bytes:3750 (3.6 KiB)

root@mirabox-debian:~# ping 192.168.1.1
PING 192.168.1.1 (192.168.1.1) 56(84) bytes of data:
64 bytes from 192.168.1.1: icmp_req=1 ttl=64 time=4.74 ms
64 bytes from 192.168.1.1: icmp_req=2 ttl=64 time=5.03 ms
64 bytes from 192.168.1.1: icmp_req=3 ttl=64 time=4.47 ms
64 bytes from 192.168.1.1: icmp_req=4 ttl=64 time=4.49 ms
64 bytes from 192.168.1.1: icmp_req=5 ttl=64 time=3.65 ms
^C
--- 192.168.1.1 ping statistics ---
5 packets transmitted, 5 received, 0% packet loss, time 4040ms
rtt min/avg/max/mdev = 3.655/4.478/5.032/0.462 ms
```

(5) Switch back to WiFi AP mode

There are two useful script files:

Client_ap.sh – switch from wifi client mode to wifi AP mode

Wlan.sh – switch from wifi AP mode to wifi client mode

```
root@mirabox-debian:~# client_ap.sh
WLAN FW already running! Skip FW download
WLAN FW is active
ADDRCONF (NETDEV_UP): uap0: link is not ready
SSID setting successful
BSS started!
Starting very small Busybox based DHCP server: Starting /usr/sbin/udhcpd...
udhcpd.
Starting DNS forwarder and DHCP server: dnsmasq.
root@mirabox-debian:~# wlan.sh
Stopping very small Busybox based DHCP server: Stopped /usr/sbin/udhcpd (pid 10278).
udhcpd.
Stopping DNS forwarder and DHCP server: dnsmasq.
WLAN FW already running! Skip FW download
WLAN FW is active
ADDRCONF (NETDEV_UP): wlan0: link is not ready
```

5. Bluetooth testing

There is bluetooth chip built-in Mirabox but disabled as default.

(1) Enable the Bluetooth function.

```
# turnon_bt.sh
# hcitool -i hci0 dev
```

```
root@mirabox-debian:~# turnon_bt.sh
BT FW is active(0)
BT FW already downloaded!
root@mirabox-debian:~# hcitool -i hci0 dev
Devices:
  hci0    00:90:A2:4A:63:45
```

If you see the message like this means your Bluetooth is up and run

(2) Scan near-by Bluetooth devices

- a. Please turn on the Bluetooth device such as your mobile phone, BT earphone or laptop computer then put it into “to be discovered” mode
- b. Giving command as following on your Mirabox

```
# hciconfig
# hcitool-i hci0 scan --flush
```

Normally, the Bluetooth devices near-by will be searched and shown as below.

```
root@mirabox-debian:~# hciconfig
hci0:  Type: BR/EDR Bus: SDIO
      BD Address: 00:90:A2:4A:63:71  ACL MTU: 1021:7  SCO MTU: 120:6
      UP RUNNING PSCAN
      RX bytes:1348 acl:0 sco:0 events:37 errors:0
      TX bytes:1527 acl:0 sco:0 commands:37 errors:0

root@mirabox-debian:~# hcitool -i hci0 scan --flush
Scanning ...
  00:25:66:9E:3E:35    GT-S5230C

root@mirabox-debian:~# sdptool browse
Inquiring ...
```

This is a mobile phone with Bluetooth enabled that is found

```
# sdptool browse
```

This command shows the protocol of Bluetooth device found.

```
root@mirabox-debian:~# sdptool browse
Inquiring ...
Browsing 00:25:66:9E:3E:35 ...
Service RecHandle: 0x10000
Service Class ID List:
  "PnP Information" (0x1200)

Service Name: HSP PS Audio Gateway
Service RecHandle: 0x10001
Service Class ID List:
  "Headset Audio Gateway" (0x1112)
  "Generic Audio" (0x1203)
```

6. Gigabit Ethernet ports

- (1) Connect the two Gigabit Ethernet ports to Gigabit switch by Network cables. Normally it will get an IP address assigned by DHCP.

Enter command as below to check:

```
# ifconfig
```

```
Mon Sep 17 06:20:41 2012 -0.252600 seconds
root@mirabox-debian:~# ifconfig
eth0      Link encap:Ethernet  HWaddr 00:50:43:9d:2b:2d
          inet addr:10.10.10.152  Bcast:10.10.10.255  Mask:255.255.255.0
          inet6 addr: fe80::250:43ff:fe9d:2b2d/64  Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:1309  errors:0  dropped:0  overruns:0  frame:0
          TX packets:138  errors:0  dropped:0  overruns:0  carrier:0
          collisions:0  txqueuelen:512
          RX bytes:136008 (132.8 KiB)  TX bytes:15562 (15.1 KiB)
          Interrupt:8

eth1      Link encap:Ethernet  HWaddr 00:50:43:81:2b:2d
          inet addr:10.10.10.189  Bcast:10.10.10.255  Mask:255.255.255.0
          inet6 addr: fe80::250:43ff:fe81:2b2d/64  Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:1359  errors:0  dropped:0  overruns:0  frame:0
          TX packets:11  errors:0  dropped:0  overruns:0  carrier:0
          collisions:0  txqueuelen:512
          RX bytes:141431 (138.1 KiB)  TX bytes:1278 (1.2 KiB)
          Interrupt:10

lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          inet6 addr: ::1/128  Scope:Host
          UP LOOPBACK RUNNING  MTU:16436  Metric:1
          RX packets:8  errors:0  dropped:0  overruns:0  frame:0
          TX packets:8  errors:0  dropped:0  overruns:0  carrier:0
          collisions:0  txqueuelen:0
          RX bytes:480 (480.0 B)  TX bytes:480 (480.0 B)

uap0     Link encap:Ethernet  HWaddr 94:db:c9:d2:ae:ec
          inet addr:192.168.1.1  Bcast:192.168.1.255  Mask:255.255.255.0
          UP BROADCAST MULTICAST  MTU:1500  Metric:1
          RX packets:0  errors:0  dropped:0  overruns:0  frame:0
          TX packets:0  errors:0  dropped:0  overruns:0  carrier:0
          collisions:0  txqueuelen:1000
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)
```

- (2) Testing the speed of Gigabit Ethernet ports

```
# ethtool eth0
```

Normally you will see the information as below:

```
root@mirabox-debian:~# ethtool eth0
Settings for eth0:
Supported ports: [ TP MII ]
Supported link modes:   10baseT/Half 10baseT/Full
                       100baseT/Half 100baseT/Full
                       1000baseT/Full
Supports auto-negotiation: Yes
Advertised link modes:  10baseT/Half 10baseT/Full
                       100baseT/Half 100baseT/Full
                       1000baseT/Half 1000baseT/Full
Advertised pause frame use: No
Advertised auto-negotiation: No
Link partner advertised link modes:  10baseT/Half 10baseT/Full
                                      100baseT/Half 100baseT/Full
                                      1000baseT/Half 1000baseT/Full
Link partner advertised pause frame use: No
Link partner advertised auto-negotiation: Yes
Speed: 1000Mb/s
Duplex: Full
Port: MII
PHYAD: 0
Transceiver: internal
Auto-negotiation: on
Link detected: yes
```

7. USB 3.0 port

- (1) Plug in the usb3.0 hard disk or flash disk to the USB port then you can see some driver messages as below of this device

```

root@mirabox-debian:~# hub 3-0:1.0: unable to enumerate USB device on port 2
usb 3-4: new SuperSpeed USB device using xhci_hcd and address 3
xhci_hcd 0000:01:01.0: WARN: short transfer on control ep
xhci_hcd 0000:01:01.0: WARN: short transfer on control ep
xhci_hcd 0000:01:01.0: WARN: short transfer on control ep
xhci_hcd 0000:01:01.0: WARN: short transfer on control ep
scsi4 : usb-storage 3-4:1.0
scsi 4:0:0:0: Direct-Access      Seagate  Portable          SFO6 PQ: 0 ANSI: 4
sd 4:0:0:0: [sdc] 976773164 512-byte logical blocks: (500 GB/465 GiB)
sd 4:0:0:0: [sdc] Write Protect is off
sd 4:0:0:0: [sdc] Assuming drive cache: write through
sd 4:0:0:0: [sdc] Assuming drive cache: write through
   sdc: sdc1
sd 4:0:0:0: [sdc] Assuming drive cache: write through
sd 4:0:0:0: [sdc] Attached SCSI disk
    
```

- (2) View the usb3.0 hard disk

```
# fdisk-l
```

you will see below messages of the usb3.0 device which is usually shown as /dev/sdb*、 /dev/sdc*.

```

Disk /dev/sdc: 500.1 GB, 500107859968 bytes
255 heads, 63 sectors/track, 60801 cylinders
Units = cylinders of 16065 * 512 = 8225280 bytes
Sector size (logical/physical): 512 bytes / 512 bytes
I/O size (minimum/optimal): 512 bytes / 512 bytes
Disk identifier: 0x165060a4

   Device Boot      Start         End      Blocks   Id  System
/dev/sdc1             1         60802     488384032+  7   HPFS/NTFS
    
```

- (3) Testing the access speed of the usb3.0 ports

```
# hdparm-t /dev/sdc1
```

```

root@mirabox-debian:~# hdparm -t /dev/sdc1

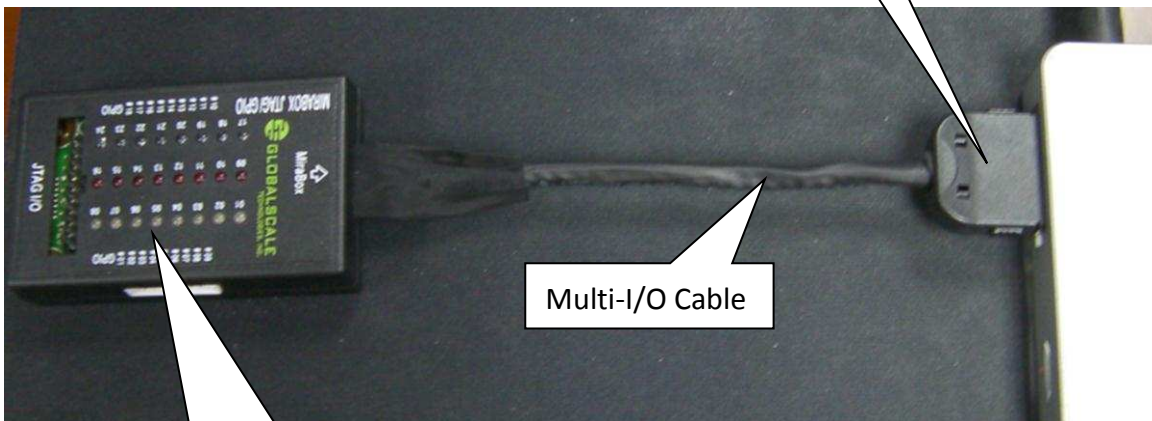
/dev/sdc1:
Timing buffered disk reads: 118 MB in  3.02 seconds = 39.10 MB/sec
    
```

8. Multi-IO port

Connect the MIRABOX JTAG/GPIO box to the Multi-IO port via Multi-IO cable.



Multi-I/O port



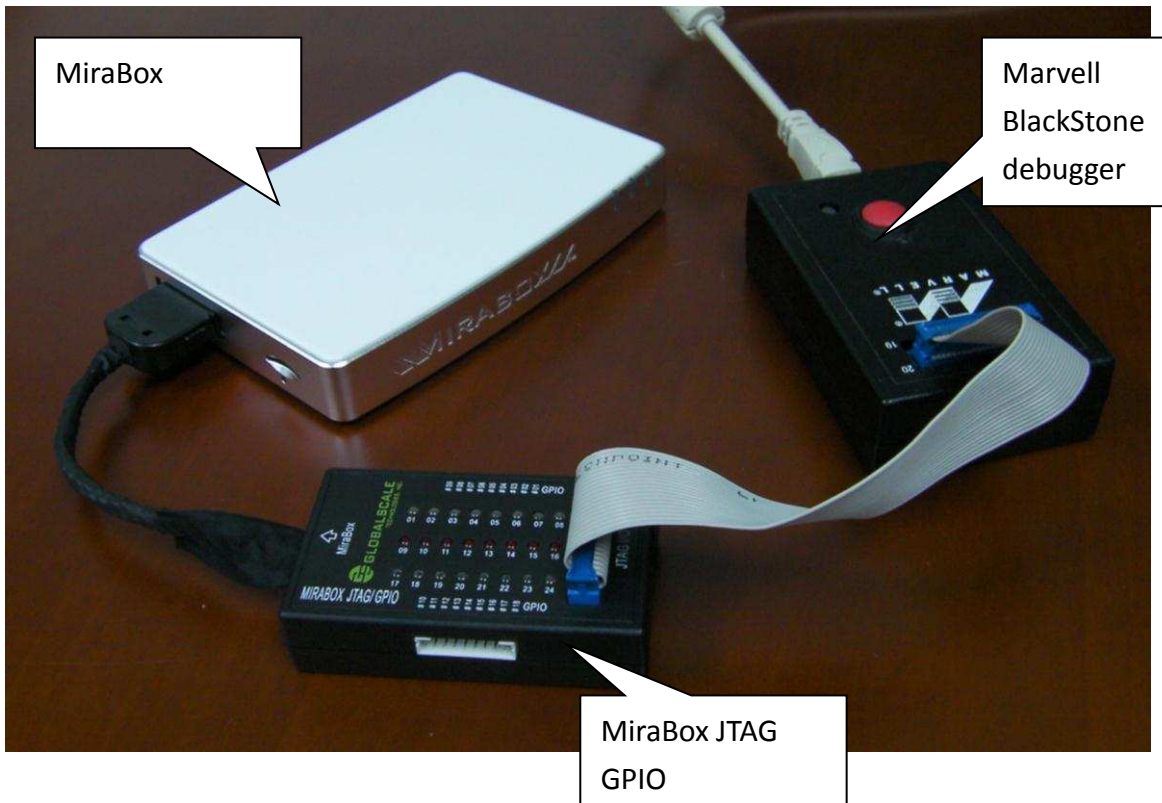
Multi-I/O Cable

MiraBox JTAG/GPIO box

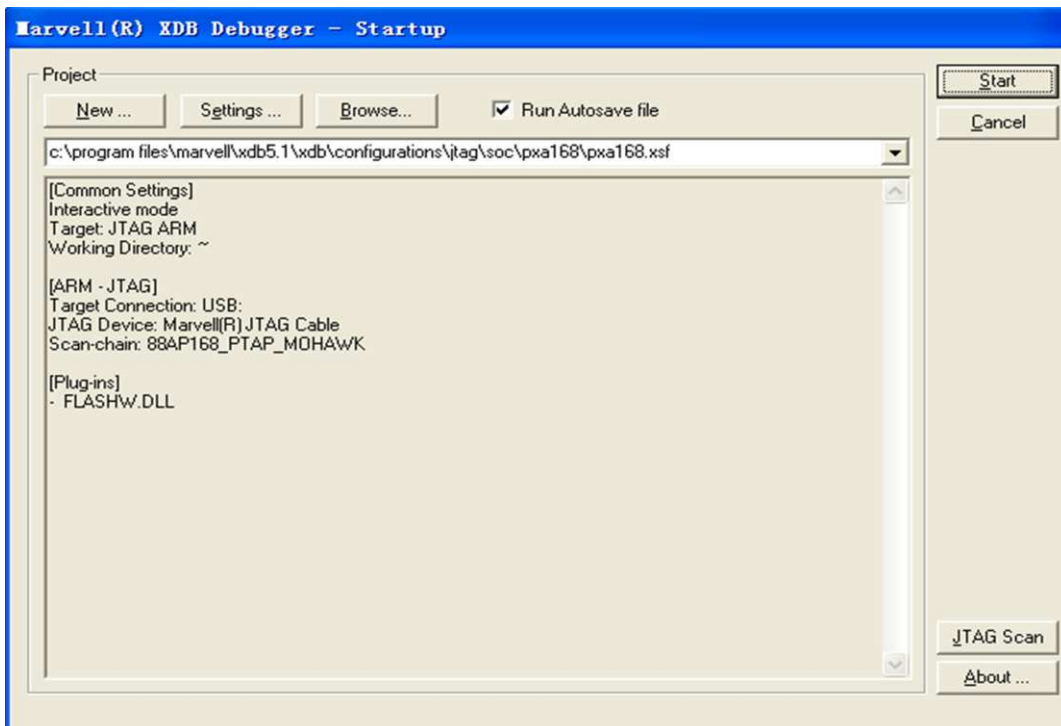
9. Multi-IO port- JTAG interface

Please connect the debugger to the 20-pin JTAG slot as shown in the picture, here we use the Marvell BlackStone debugger and XDB(Marvell eXtreme Debugger 5.1) software on Windows PC for example.

Debugger connection



Run XDB on Windows PC



10. GPIO interface and control

(1) LED demo program

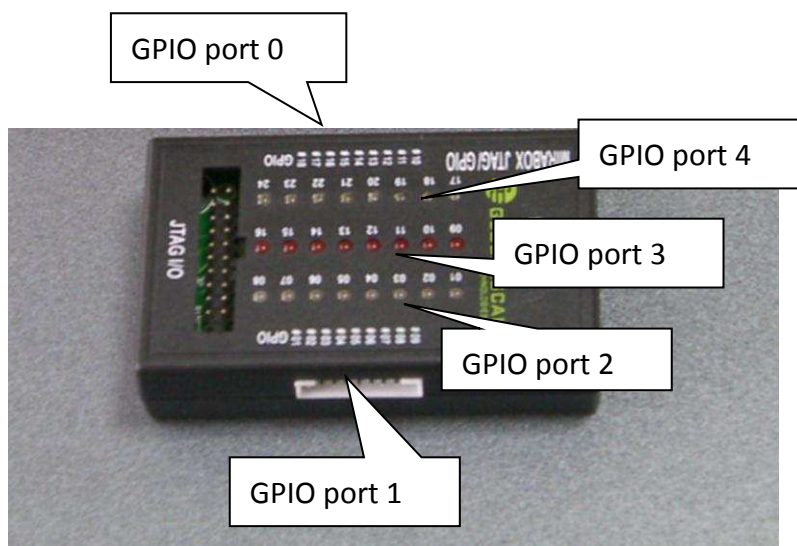
There is a demo program to show the GPIO LEDs by entering command as below:

```
# ledtest1
```

This will light up all the LEDs



(2) Write a simple program to control the LED



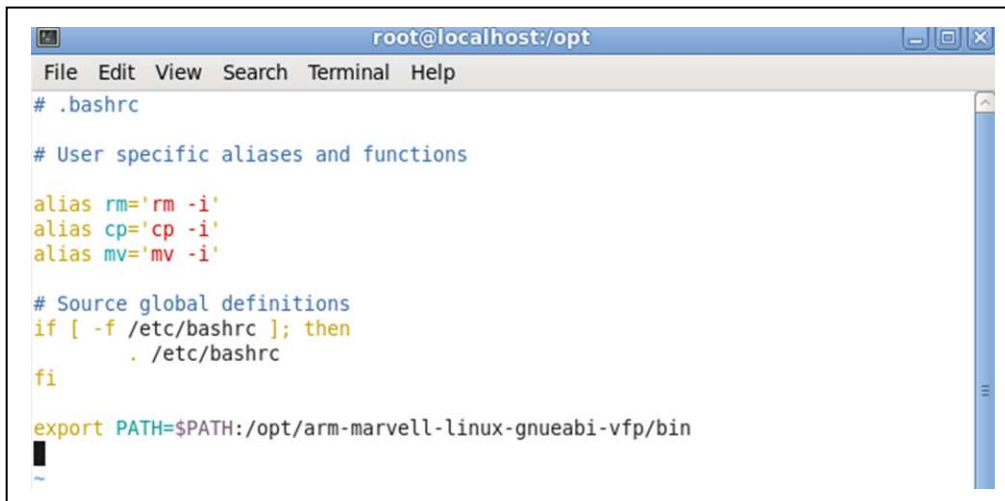
In this GPIO box we use NXP PCA9505 I/O port expansion IC to provide 40-bit parallel input/output GPIOs. Please download the datasheet to get the detailed description for this chip.

- a. Prepare a pc with linux Fedora 14 installed, and download the cross tool chain “**arm-marvell-linux-gnueabi-vfp.tar.bz2**” from our website
<http://www.plugcomputer.org/downloads/d2plug/>
or
<http://www.globalscaletechnologies.com>
- b. Install and configure the tool chain

Copy “**arm-marvell-linux-gnueabi-vfp.tar.bz2**” to directory /opt

```
# cd /opt
# tar -jxf arm-marvell-linux-gnueabi-vfp.tar.bz2
# ls
# vim /root/.bashrc
```

Add “**export PATH=\$PATH:/opt/arm-marvell-linux-gnueabi-vfp/bin**” to last line as below, then save and exit.



```
root@localhost:/opt
File Edit View Search Terminal Help
# .bashrc
# User specific aliases and functions
alias rm='rm -i'
alias cp='cp -i'
alias mv='mv -i'
# Source global definitions
if [ -f /etc/bashrc ]; then
    . /etc/bashrc
fi
export PATH=$PATH:/opt/arm-marvell-linux-gnueabi-vfp/bin
```

Enable the PATH

```
# source /root/.bash_profile
```

- c. Write a program
Here is the sample program named “**i2c_led.c**”

```

/*i2c_led.c*GTI--Globalscaletechnologies.,INC**/

#include <stdio.h>

#include <linux/types.h>

#include <stdlib.h>

#include <fcntl.h>

#include <unistd.h>

#include <sys/types.h>

#include <sys/ioctl.h>

#include <errno.h>

#define I2C_RETRIES 0x0701

#define I2C_TIMEOUT 0x0702

#define I2C_RDWR 0x0707

#define I2C_M_RD 0x0001

#define I2C_M_NOSTART      0x4000      /* if I2C_FUNC_PROTOCOL_MANGLING */

#define I2C_M_REV_DIR_ADDR 0x2000      /* if I2C_FUNC_PROTOCOL_MANGLING */

#define I2C_M_IGNORE_NAK 0x1000      /* if I2C_FUNC_PROTOCOL_MANGLING */

#define I2C_M_NO_RD_ACK    0x0800      /* if I2C_FUNC_PROTOCOL_MANGLING */

#define I2C_M_RECV_LEN     0x0400      /* length will be first received byte */

/*****define struct i2c_rdwr_ioctl_data and struct i2c_msg , they must be consistent to kernel*****/

struct i2c_msg

{

unsigned short addr;

unsigned short flags;

#define I2C_M_TEN 0x0010

unsigned short len;

unsigned char *buf;

};

struct i2c_rdwr_ioctl_data

{

struct i2c_msg *msgs;

int nmsgs; /* the nmsgs decide the num of start signal */

};

/*****the main program*****/

int main()

{

int fd, ret;

```

```

        struct i2c_rdwr_ioctl_data e2prom_data;
fd=open("/dev/i2c-0",O_RDWR);/* /dev/i2c-0 is registered to the system */
if(fd<0)
    {
perror("open error");
    }
    e2prom_data.nmsgs=2;
    e2prom_data.msgs=(struct i2c_msg*)malloc(e2prom_data.nmsgs*sizeof(struct i2c_msg));
if(!e2prom_data.msgs)
    {
perror("malloc error");
exit(1);
    }
ioctl(fd,I2C_TIMEOUT,1);/*timeout */
ioctl(fd,I2C_RETRIES,2);/*retries times*/
/**write data to e2prom**/
    e2prom_data.nmsgs=1;
    (e2prom_data.msgs[0]).len=2;
    (e2prom_data.msgs[0]).addr=0x25;//e2prom device address
    (e2prom_data.msgs[0]).flags=0; //write
    (e2prom_data.msgs[0]).buf=(unsigned char*)malloc(2);
    /***** control the GPIO OP-0 *****/
    (e2prom_data.msgs[0]).buf[0]=0x18;// e2prom write address
    (e2prom_data.msgs[0]).buf[1]=0x0;//the data to write
        ret=ioctl(fd,I2C_RDWR,(unsigned long)&e2prom_data);
if(ret<0)
    {
perror("ioctl error2");
    }
    /***** control the GPIO OP-1 *****/
(e2prom_data.msgs[0]).buf[0]=0x19;// e2prom write address
    (e2prom_data.msgs[0]).buf[1]=0x0;//the data to write
        ret=ioctl(fd,I2C_RDWR,(unsigned long)&e2prom_data);
if(ret<0)
    {
perror("ioctl error2");
    }

```

```

/***** control the GPIO OP-2 *****/
//turn on LED
(e2prom_data.msgs[0]).buf[0]=0x1a;// e2prom write address
        (e2prom_data.msgs[0]).buf[1]=0x0;//the data to write
        ret=ioctl(fd,I2C_RDWR,(unsigned long)&e2prom_data);
if(ret<0)
    {
perror("ioctl error3");
    }
//turn off LED
sleep(1);                //delay 1 second
        (e2prom_data.msgs[0]).buf[0]=0x1a;// e2prom write address
        (e2prom_data.msgs[0]).buf[1]=0xFF;//the data to write
        ret=ioctl(fd,I2C_RDWR,(unsigned long)&e2prom_data);
if(ret<0)
    {
perror("ioctl error3");
    }
/***** control the GPIO OP-3 *****/
//turn on LED
sleep(1);
        (e2prom_data.msgs[0]).buf[0]=0x1b;// e2prom write address
        (e2prom_data.msgs[0]).buf[1]=0x0;//the data to write
        ret=ioctl(fd,I2C_RDWR,(unsigned long)&e2prom_data);
if(ret<0)
    {
perror("ioctl error4");
    }
//turn off LED
sleep(1);
(e2prom_data.msgs[0]).buf[0]=0x1b;// e2prom write address
        (e2prom_data.msgs[0]).buf[1]=0xFF;//the data to write
        ret=ioctl(fd,I2C_RDWR,(unsigned long)&e2prom_data);
if(ret<0)
    {
perror("ioctl error4");
    }

```

```

/***** control the GPIO OP-4 *****/
//turn on LED
sleep(1);

(e2prom_data.msgs[0]).buf[0]=0x1c;// e2prom write address
(e2prom_data.msgs[0]).buf[1]=0x0;//the data to write
ret=ioctl(fd,I2C_RDWR,(unsigned long)&e2prom_data);
if(ret<0)
{
perror("ioctl error5");
}

//turn off LED
sleep(1);

(e2prom_data.msgs[0]).buf[0]=0x1c;// e2prom write address
(e2prom_data.msgs[0]).buf[1]=0xFF;// the data to write
ret=ioctl(fd,I2C_RDWR,(unsigned long)&e2prom_data);
if(ret<0)
{
perror("ioctl error5");
}

printf("testing ok\n");
close(fd);
return 0;
}

```

Give this program the name **“i2c_led.c”** and save to **“/home”** directory then compile it .

```
# cd /home
```

```
# arm-marvell-linux-gnueabi-gcc -o led i2c_led.c
```

Then copy the executable file “led” to Mirabox and run it. You can see the LED is controlled by yourself.

11. Reset



6、GPIO reset button hole.

(1) GPIO reset button

The reset button is connected to one GPIO which means controlled by software.

When you press down this button by using a sharp pin, it arouses attention of CPU then CPU asserts the master reset low signal to start the system reset session.

Below is the reboot screen after reset

```

root@mirabox-debian:/# reset button is pressed

BootROM 1.08
Booting from NAND flash
DDR3 Training Sequence - Ver 2.1.6
DDR3 Training Sequence - Number of DIMMs detected: 1
DDR3 Training Sequence - Ended Successfully
BootROM: Image checksum verification PASSED

MIRABOX
U-Boot
** LOADER **
    
```

Note: Since this reset function is controlled by software so it has no effect during boot-up session.

(2) More push button functions

System developer can program this button to have more functions by different press-then-release delay time.

12. Download sites

To download the files for MiraBox server, please visit:

<http://www.globalscaletechnologies.com/t-downloads.aspx>

Other useful resource links are:

<http://www.plugcomputer.org/>

<http://plugcomputer.org/plugwiki/index.php/GuruPlug>