

CANopen ABSOLUTE MULTI-TURN ENCODERS, PHM5 RANGE

PHM5, the new generation of CANopen absolute multi-turn encoders :

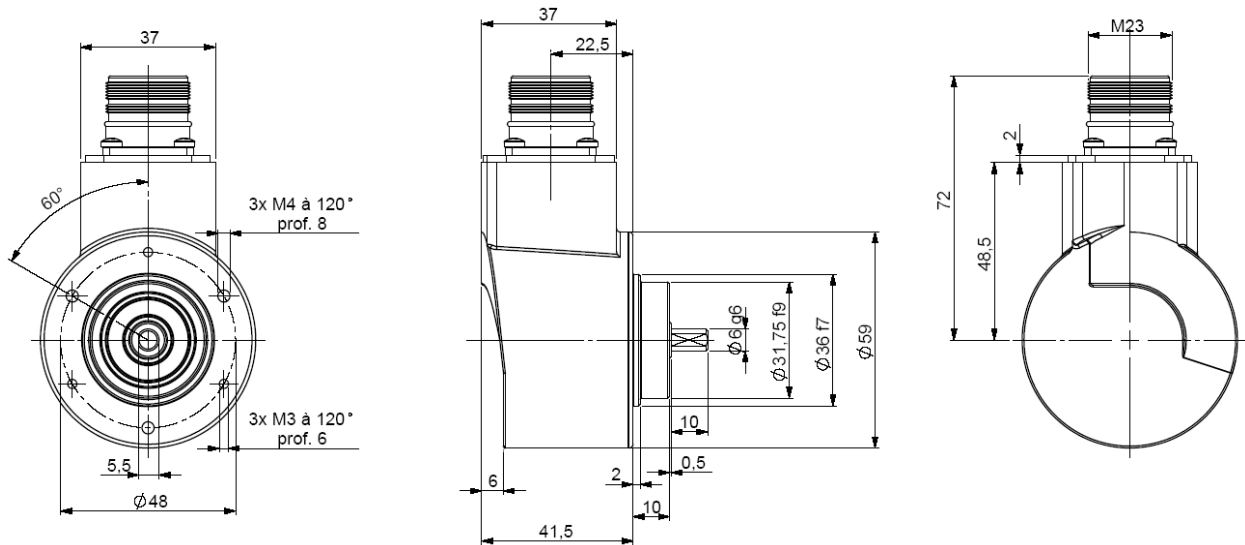
- 58mm encoder, extra-flat,
- Ø 6 & Ø 10 mm solid shaft version,
- Robustness and excellent resistance to shocks/vibrations,
- High protection level IP65,
- High performances in temperature -20°C to 85° (-30°C option)
- Universal power supply from 5 to 30 Vdc,
- High resolutions up to 8192 points per turn (2¹³),
- Turns numération up to 65 536 (16 bits).

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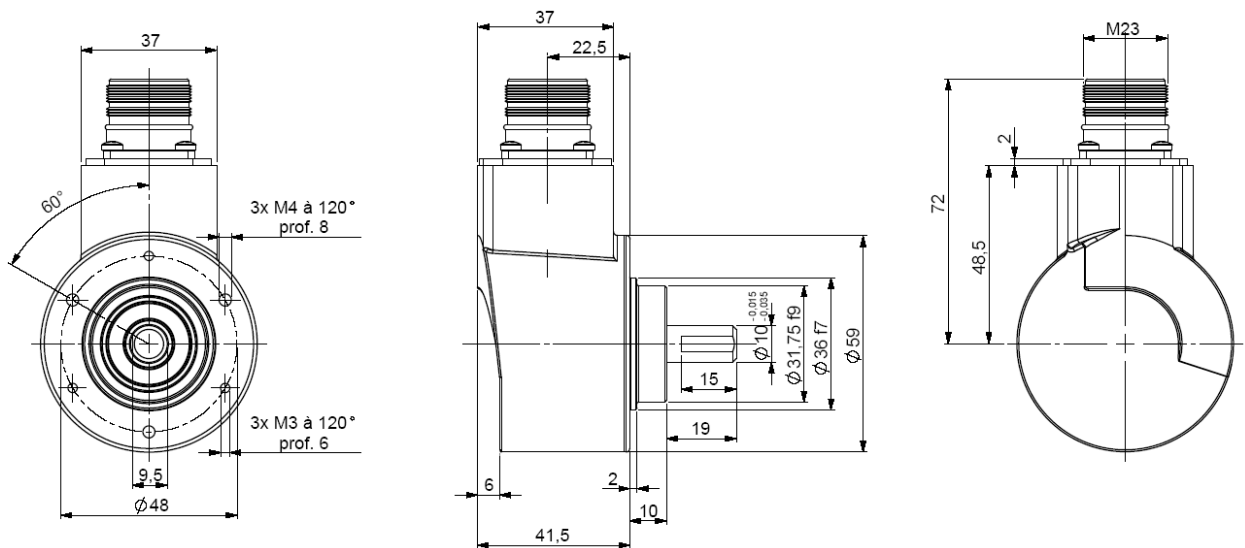
DS 301 V4.02
DS 406 V3.1



PHM5_06 connection BCR(radial M23)



PHM5_10 connection BCR(radial M23)



Material	Cover: treated steel	Shock (EN60068-2-27)	≤ 500 m.s ⁻² (during 6 ms)
	Body: aluminium	Vibration (EN60068-2-6)	≤ 100 m.s ⁻² (10... 2 000 Hz)
	Shaft: stainless steel	EMC	EN 61000-6-4, EN 61000-6-2
Bearings	6 000 serie	Isolation	500V (1 min.)
Maximal load	Axial: 50 N	Weight (connector)	0,520 kg
	Radial: 100 N	Operating temperature	- 20 ... + 85 °C (encoder T)
Shaft inertia	≤ 1.10 ⁻⁶ kg.m ²	Storage temperature	- 20 ... + 85 °C
Torque	≤ 4.10 ⁻³ N.m	Protection(EN 60529)	IP 65 (IP67 with flange option)
Permissible max. speed	6 000 min ⁻¹	Theoretical mechanical life time 10 ⁹ turns (F _{axial} / F _{radial})	
Continuous max. speed	6 000 min ⁻¹	25 N / 50 N : 99	50 N / 100 N : 12

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ELECTRICAL CHARACTERISTICS

Power supply	5 – 30Vdc
Introduction	< 1 s
Consumption (without load)	< 50mA (at 24Vdc)
Accuracy	± ½ LSB (13 bits)

Programmable parameters

Resolution: defines the resolution per revolution (0 to 8192),

Global resolution: total amount of codes for the encoder (2 to 536 870 912),

Transmission speed: programmable from 10kbaud (1000m) to 1 Mbaud (40 m); value per default: 20 Kbaud,

Address: define the software address of the encoder on the bus (1 to 127, value by default: id = 1),

Direction: define the direction of count of the encoder,

RAX: defines the value of its preset position (non turning shaft),

CAM: Low and High Limits.

Communication modes

3 modes are available to interrogate the encoder:

POLLING mode: (Response to a RIR message): The position value is only given upon request (SDO mode),

CYCLIC mode: the encoder transmits its position in an asynchronous manner. The frequency of the transmission is defined by the programmable cyclic timer register from 0 to 65 535 ms,

SYNCHRO mode: the encoder transmits its position on a synchronous demand by the master.

CANOPEN CONNECTION

1	2	3	4	5	6	7	8, 9, 11	10	12
Reserved	CAN LOW	CAN GND	Reserved	Reserved	Reserved	CAN HIGH	Reserved	0V	+ 5/30Vdc

Pinout 3 (CAN GND) and 10 (0V) are connected together (intern the encoder).

Nota : Refer to the bus standards for the maximal derivation length.

ORDERING CODE (Special versions upon request, for ex. special flanges/electronic s/connection s...)

	Shaft Ø	Power supply	Output stages	Code	Resolution	Nb of turns	Connection	Connection orientation
PHM5	10 : 10mm 06 : 6mm	P: 5 to 30Vdc	BB: CANopen	B Binary	13 : 8192 points per turn (2 ¹³)	B16 : 65 536 turns (2 ¹⁶)	BC: M23 12 pins clockwise	R: radial
PHM5	10 //	P	BB	B //	13	B16 //	BC	R

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