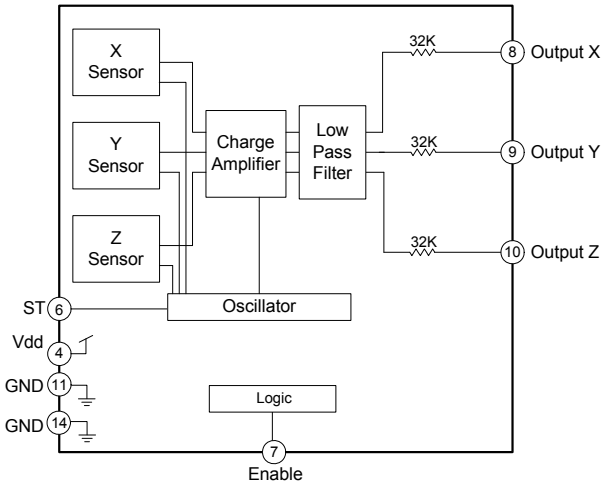
Kionix®	**± 2g Tri-axis Analog Accelerometer Specifications**	**PART NUMBER:** **KXSC4-2050** **Rev. 3** **Dec-2009**

Product Description

The KXSC4-2050 is a Tri-axis, silicon micromachined accelerometer with a full-scale output range of +/-2g (19.6 m/s/s). The sense element is fabricated using Kionix's proprietary plasma micromachining process technology. Acceleration sensing is based on the principle of a differential capacitance arising from acceleration-induced motion of the sense element, which further utilizes common mode cancellation to decrease errors from process variation, temperature, and environmental stress. The sense element is hermetically sealed at the wafer level by bonding a second silicon lid wafer to the device using a glass frit. A separate ASIC device packaged with the sense element provides signal conditioning and self-test. The accelerometer is delivered in a 5 x 5 x 1.2mm Dual Flat No-lead (DFN) plastic package operating from a 1.8 – 3.6V DC supply.

Functional Diagram



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Product Specifications

Table 1. Mechanical

(specifications are for operation at 3.3V and T = 25C unless stated otherwise)

Parameters	Units	Min	Typical	Max
Operating Temperature Range	ºC	-40	-	85
Zero-g Offset	V	1.518	1.65	1.782
Zero-g Offset Variation from RT over Temp.	mg/ºC		0.4	
Sensitivity	mV/g	640	660	680
Sensitivity Variation from RT over Temp.	%/ºC		0.02	
Offset Ratiometric Error (V_{dd} = 3.3V ± 5%)	%		0.3	
Sensitivity Ratiometric Error (V_{dd} = 3.3V ± 5%)	%		0.6 (xy) 0.3 (z)	
Self Test Output change on Activation	g	1.5 1.4 1.1	1.9 (x) 1.8 (y) 1.5 (z)	2.3 2.2 1.9
Mechanical Resonance (-3dB)[1]	Hz		3500 (xy) 1800 (z)	
Non-Linearity	% of FS		0.2	
Cross Axis Sensitivity	%		2	
Noise Density (on filter pins)	µg / √Hz	50	125	200

Notes:

1. Resonance as defined by the dampened mechanical sensor.

Table 2. Electrical

(specifications are for operation at 3.3V and T = 25C unless stated otherwise)

Parameters		Units	Min	Typical	Max
Supply Voltage (V_{dd})	Operating	V	1.8	3.3	3.6
Current Consumption	Operating	µA	195	230	265
	Standby	µA	-	0.05	0.1
Analog Output Resistance(R_{out})		kΩ	24	32	40
Power Up Time[1]		ms	-	16	-
Bandwidth (-3dB)[2]		Hz	40	50	60

Notes:

1. Power up time is determined by 5 times the RC time constant of the factory programmed or user defined low pass filter.

2. Factory programmable to have a switched capacitor low pass filter at 2kHz, 1kHz, 500Hz, 100Hz, 50Hz, or no low pass filter. Optionally, the user can define with external capacitors. Maximum defined by the frequency response of the sensors.

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Table 3. Environmental

Parameters		Units	Min	Typical	Max
Supply Voltage (V_{dd})	Absolute Limits	V	-0.3	-	6.0
Operating Temperature Range		ºC	-40	-	85
Storage Temperature Range		ºC	-55	-	150
Mech. Shock (powered and unpowered)		g	-	-	5000 for 0.5ms 10000 for 0.2ms
ESD	HBM	V	-	-	2000

Caution: ESD Sensitive and Mechanical Shock Sensitive Component, improper handling can cause permanent damage to the device.

This product conforms to Directive 2002/95/EC of the European Parliament and of the Council of the European Union (RoHS). Specifically, this product does not contain lead, mercury, cadmium, hexavalent chromium, polybrominated biphenyls (PBB), or polybrominated diphenyl ethers (PBDE) above the maximum concentration values (MCV) by weight in any of its homogenous materials. Homogenous materials are "of uniform composition throughout."

HF

This product is halogen-free per IEC 61249-2-21. Specifically, the materials used in this product contain a maximum total halogen content of 1500 ppm with less than 900-ppm bromine and less than 900-ppm chlorine.

Soldering

Soldering recommendations are available upon request or from www.kionix.com.

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Application Schematic

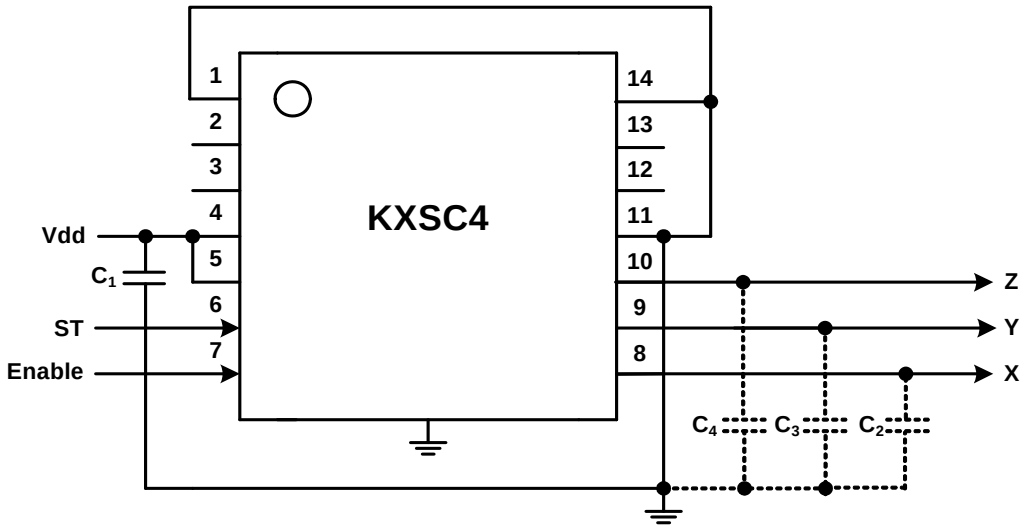

Table 4. KXSC4 Pin Descriptions

Pin	Name	Description
1	GND	Ground
2	NC	Not Connected Internally
3	NC	Not Connected Internally
4	Vdd	The power supply input. Decouple this pin to ground with a 0.1uF ceramic capacitor (C_1).
5	Reserved	Pin must be held at Vdd for normal operation.
6	ST	Self Test: **Low** – Normal operation; **High** – Device is in self-test mode.
7	Enable	Enable pin: **High** - Normal operation; **Low** - Device is in standby, power down mode
8	X Output	Analog output of the x-channel (Optional filter capacitor, C_2, shown).
9	Y Output	Analog output of the y-channel (Optional filter capacitor, C_3, shown).
10	Z Output	Analog output of the z-channel (Optional filter capacitor, C_4, shown).
11	GND	Ground
12	NC	Not Connected Internally
13	NC	Not Connected Internally
14	GND	Ground
	Center Pad	Ground

Application Design Equations

The bandwidth is determined by a factory programmable switched capacitor filter. The filter can be set at the factory to be 2kHz, 1kHz, 500Hz, 100Hz, 50Hz, or no low pass filter. Alternatively, bandwidth can be reduced by addition of a capacitor on the output pins 8, 9, and 10 according to the equation:

$$C_2 = C_3 = C_4 = \frac{4.97x10^{-6}}{f_{BW}}$$

Note:
When the Enable pin is connected to GND or left floating, the KXSC4 is shutdown and drawing very little power. When the Enable pin is tied to Vdd, the unit is fully functional.

Test Specifications

! ***Special Characteristics**:*

These characteristics have been identified as being critical to the customer. Every part is tested to verify its conformance to specification prior to shipment.

Table 5. Test Specifications

Parameter	Specification	Test Conditions
Zero-g Offset @ RT	1.65 +/- 0.132 V	25C, Vdd = 3.3 V
Sensitivity @ RT	660 +/- 20 mV/g	25C, Vdd = 3.3 V
Current Consumption -- Operating	195 <= Idd <= 265 uA	25C, Vdd = 3.3 V

All specifications in Tables 1, 2, and 3 which are not listed in Table 5 (above) are tested on an audit or validation basis only and are not guaranteed to be within the minimum and maximum values prior to shipment.

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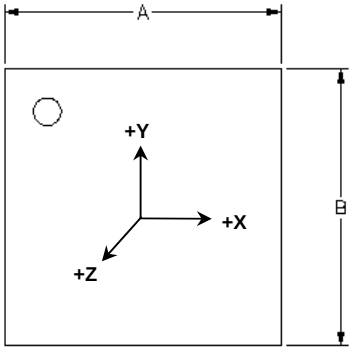
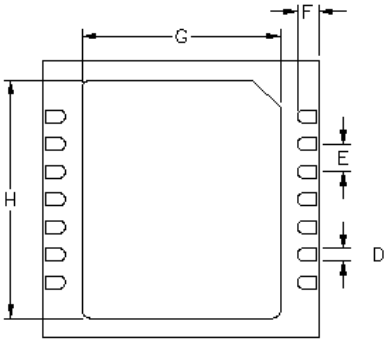
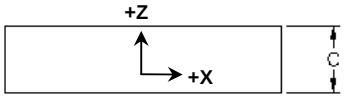
Package Dimensions and Orientation

5 x 5 x 1.2 mm DFN







Dimension	mm			inch		
	Min	Nom	Max	Min	Nom	Max
A		5.00			0.197	
B		5.00			0.197	
C	1.10	1.20	1.30	0.043	0.047	0.051
D	0.18	0.23	0.28	0.007	0.009	0.011
E		0.50			0.020	
F	0.35	0.40	0.45	0.014	0.016	0.018
G	3.50	3.60	3.70	0.138	0.142	0.146
H	4.20	4.30	4.40	0.165	0.169	0.173

All dimensions and tolerances conform to ASME Y14.5M-1994

When device is accelerated in +X, +Y or +Z direction, the corresponding output will increase.

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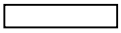
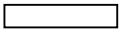
Static X/Y/Z Output Response versus Orientation to Earth's surface (1-g):

Position	1	2	3	4	5	6
Diagram					Top  Bottom	Bottom  Top
X	1.65 V	2.31 V	1.65 V	0.99 V	1.65 V	1.65 V
Y	2.31 V	1.65 V	0.99 V	1.65 V	1.65 V	1.65 V
Z	1.65 V	1.65 V	1.65 V	1.65 V	2.31 V	0.99 V
X-Polarity	**0**	**+**	**0**	**-**	**0**	**0**
Y-Polarity	**+**	**0**	**-**	**0**	**0**	**0**
Z-Polarity	**0**	**0**	**0**	**0**	**+**	**-**

Earth's Surface

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Revision History

REVISION	DESCRIPTION	DATE
1	Initial release	14-Jan-2008
2	Updated to new format and revisioning.	10-Sep-2009
3	Transition to new sensor	17-Dec-2009

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