

8-bit Proprietary Microcontroller

CMOS

F²MC-8L MB89670AR Series

MB89673AR/675AR/677AR/P677A/PV670A

■ OUTLINE

The MB89670AR series has been developed as a line of proprietary 8-bit, single-chip microcontrollers.

In addition to the F²MC*-8L family CPU core which can operate at low voltage but at high speed, the microcontrollers contain peripheral functions such as timers, a serial interface, a 10-bit A/D converter, a UART, an 8/16-bit up/down counter/timer, and an external interrupt.

The MB89670AR series is applicable to a wide range of applications from consumer appliances to industrial equipment, including portable devices.

*: F²MC is the abbreviation of FUJITSU Flexible Microcontroller.

■ FEATURES

- F²MC-8L family CPU core

Instruction set optimized for controllers

Multiplication and division instructions
16-bit arithmetic operations
Test and branch instructions
Bit manipulation instructions, etc.

- High-speed processing at low voltage
- Minimum execution time: 0.4 μ s@3.5 V, 0.8 μ s@2.7 V, 2.0 μ s@2.2 V
- I/O ports: max. 69 channels

(Continued)

For the information for microcontroller supports, see the following web site.

<http://edevic.fujitsu.com/micom/en-support/>

MB89670AR Series

(Continued)

- Timers: 12 channels
 - 8-bit PWM timer: 6 channels (also usable as a reload timer or 8-bit PWM timer)
 - 16-bit timer/counter
 - 21-bit timebase timer
 - 8/16-bit timer (8 bits × 2 channels or 16 bits)
 - 8/16-bit up/down counter/timer (8 bits × 2 channels or 16 bits)
- 2-channel serial interfaces
 - 8-bit synchronized serial: 1 channel (Switchable transfer direction allows communication with various equipment.)
 - UART: 1 channel (internal full-duplex double buffer)
- External interrupts: 8 channels
 - Eight channels are independent and capable of wake-up from low-power consumption modes (with an edge detection function).
- Buzzer output
- 10-bit A/D converter
 - Input: 8 channels
 - 10-bit resolution
- Low-power consumption modes
 - Stop mode (Oscillation stops to minimize the current consumption.)
 - Sleep mode (The CPU stops to reduce the current consumption to approx. 1/3 of normal.)
- Bus interface function
 - Including hold and ready functions

MB89670AR Series

■ PRODUCT LINEUP

Part number	MB89673AR	MB89675AR	MB89677AR	MB89P677A	MB89PV670A
Item					
Classification	Mass-produced products (mask ROM products)			One-time PROM product (for development)	Piggyback/ evaluation product (for development)
ROM size	8 K × 8 bits (internal mask ROM)	16 K × 8 bits (internal mask ROM)	32 K × 8 bits (internal mask ROM)		48 K × 8 bits (external ROM)
RAM size	384 × 8 bits	512 × 8 bits	1 K × 8 bits		
CPU functions	The number of instructions:		136		
	Instruction bit length:		8 bits		
	Instruction length:		1 to 3 bytes		
	Data bit length:		1, 8, 16 bits		
	Minimum execution time:		0.4 μs@10 MHz to 6.4 μs@10 MHz		
	Interrupt processing time:		3.6 μs@10 MHz to 57.6 μs@10 MHz		
Ports	Output ports (N-channel open-drain):		14 (12 also serve as peripherals.)		
	Output ports (CMOS):		8 (All also serve as peripherals.)		
	I/O ports (N-channel open-drain):		7 (All also serve as peripherals.)		
	I/O ports (CMOS):		32 (All also serve as peripherals.)		
	Input ports:		8 (All also serve as peripherals.)		
	Total:		69		
Option	Specify when ordering masking			Set with EPROM programmer	Setting not possible
Timebase timer	21 bits (0.81 ms, 3.27 ms, 26.21 ms, 419 ms@10 MHz)				
8/16-bit up/down counter/timer	8 bits × 2 channels or 16 bits × 1 channel Timer operation Up/down counter operation Phase difference counting (double mode, quadruple mode)				
16-bit timer/counter	16-bit timer operation 16-bit event counter operation (edge selectable)				
8/16-bit timer/counter	8 bits × 2 channels or 16 bits × 1 channel Reload timer operation (toggled output capable) Event counter operation				
8-bit PWM timer 1, 2	8 bits × 2 channels reload timer operation (toggled output capable) 8 bits × 2 channels PWM operation (four frequencies fixed) 8 bits × 1 channel PPG operation (variable frequency) Capable of output switching between 2 channels in any mode				
8-bit PWM timer 3, 4, 5, 6	8-bit reload timer operation (toggled output capable) 8-bit PWM operation (four frequencies fixed) Capable of output switching between 2 channels in any mode				
8-bit serial I/O	8 bits LSB first/MSB first selectable One clock selectable from four transfer clocks (one external shift clock, three internal shift clocks)				

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MB89670AR Series

(Continued)

Part number	MB89673AR	MB89675AR	MB89677AR	MB89P677A	MB89PV670A
Item					
UART	Variable data length (7 or 8 bits) On-chip baud rate generator Error detection function On-chip full-duplex double buffer NRZ transfer format CLK synchronous/asynchronous data transfer capable				
10-bit A/D converter	10 bits × 8 channels				
External interrupt	8 channels (Rising edge/falling edge)				
Power supply voltage*	2.2 V to 6.0 V			2.7 V to 6.0 V	
EPROM for use	—				MBM27C512-20TV

* : The minimum operating voltage varies with the operating frequency, the function, and the connected ICE.

■ PACKAGE AND CORRESPONDING PRODUCTS

Package	MB89673AR MB89675AR MB89677AR	MB89P677A	MB89PV670A
FPT-80P-M06	○	○	×
FPT-80P-M22	○	○	×*
MQP-80C-P01	×	×	○

○ : Available × : Not available

* : Lead pitch converter sockets are available

Note: For more information about each package, see section “■ Package Dimensions”.

■ DIFFERENCES AMONG PRODUCTS

1. Memory Size

Before evaluating using the piggyback product, make sure of its differences from the product that will actually be used. Take particular care on the following points:

- On the MB89P677A, the program area starts from address 8007_H, while on the MB89677AR and MB89PV670A starts from 8000_H.

(On the MB89P677A, the option setting data can be read by reading the addresses “8000_H” to “8006_H”, while on the MB89677AR and MB89PV670A, addresses 8000_H to 8006_H could also be used as a program ROM. However, do not use these addresses in order to maintain compatibility of the MB89P677A.)

- The stack area, etc., is set at the upper limit of the RAM.
- The external area is used.

2. Current Consumption

- In the case of the MB89PV670A, add the current consumed by the EPROM which is connected to the top socket.
- When operated at low speed, the product with an OTPROM (one-time PROM) or an EPROM will consume more current than the product with a mask ROM.

However, the current consumption in sleep/stop modes is the same. (For more information, see sections “■ Electrical Characteristics” and “■ Example Characteristics”.)

3. Mask Options

Functions that can be selected as options and how to designate these options vary by the product.

Before using options check section “■ Mask Options”.

Take particular care on the following point:

- Options are fixed on the MB89PV670A.

4. Differences between the MB89670/670A and MB89670AR Series

- Memory access area

Memory access area of both the MB89677A and MB89677AR is the same.

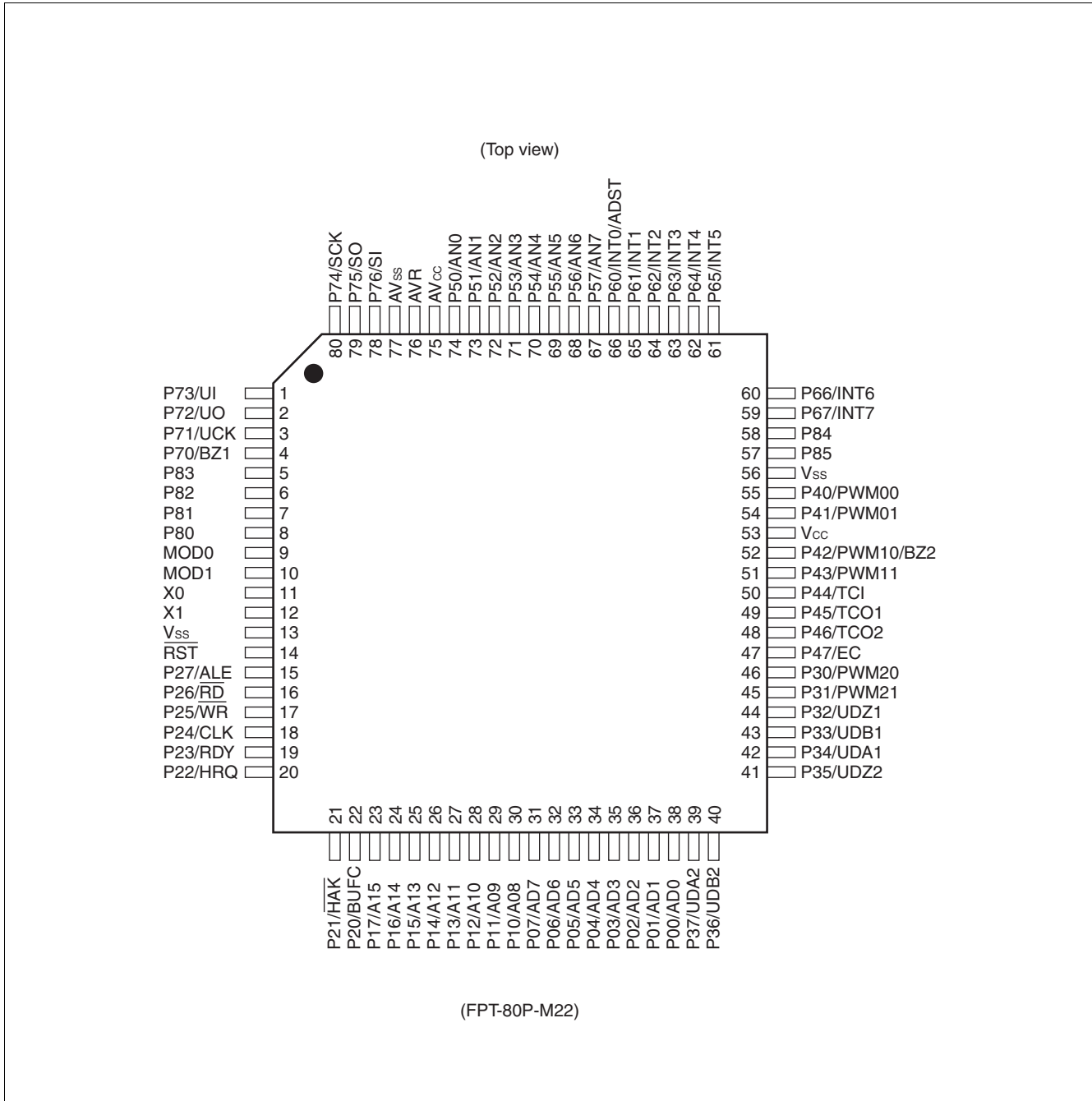
The access area of the MB89673 is different from that of the MB89673AR respectively in the external bus mode. See below.

Address	Memory area	
	MB89673	MB89673AR
0000 _H to 007F _H	I/O area	I/O area
0080 _H to 01FF _H	RAM area	RAM area
0200 _H to 027F _H	External area	Access prohibited
0280 _H to BFFF _H		External area
C000 _H to DFFF _H		Access prohibited
E000 _H to FFFF _H	ROM area	ROM area

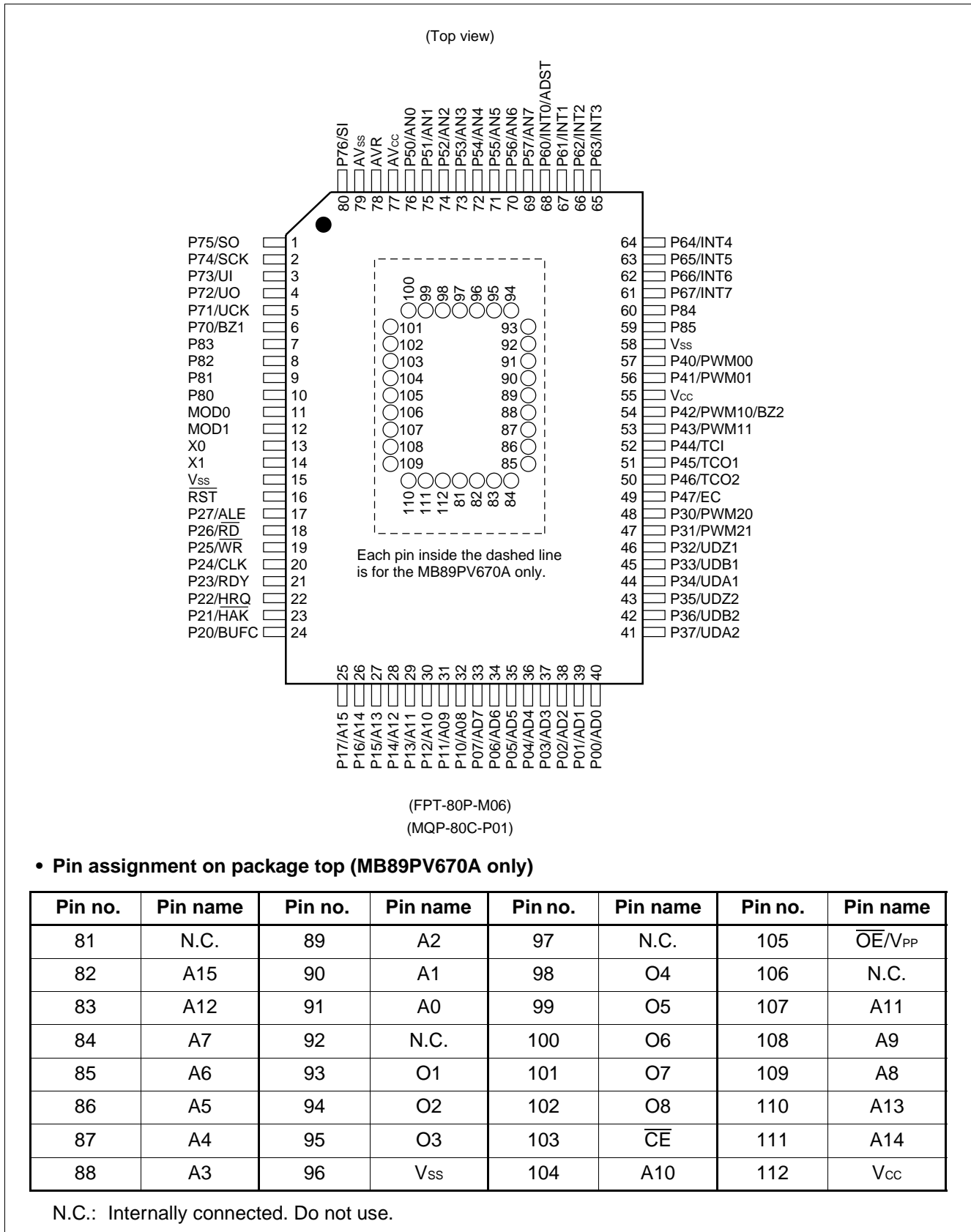
MB89670AR Series

- Electrical specifications/characteristics
Electrical specifications/characteristics of the MB89673AR/677AR are the same with that of the MB89670/670A series.
- The other specifications
Both the MB89673AR/677AR and the MB89670/670A series are the same.

■ PIN ASSIGNMENT



MB89670AR Series



■ PIN DESCRIPTION

Pin no.		Pin name	Circuit type	Function
LQFP ^{*1}	QFP ^{*2} MQFP ^{*3}			
11	13	X0	A	Clock oscillator pins
12	14	X1		
9	11	MOD0	B	Operating mode selection pins Connect directly to V _{CC} or V _{SS} .
10	12	MOD1		
14	16	RST	C	Reset I/O pin This pin is of a N-ch open-drain output type with pull-up resistor and a hysteresis input type. “L” is output from this pin by an internal reset source. The internal circuit is initialized by the input of “L”.
38 to 31	40 to 33	P00/AD0 to P07/AD7	D	General-purpose I/O ports When an external bus is used, these ports function as multiplex pins of lower address output and data I/O.
30 to 23	32 to 25	P10/A08 to P17/A15	D	General-purpose I/O ports When an external bus is used, these ports function as upper address output pins.
22	24	P20/BUFC	F	General-purpose output port When an external bus is used, this port can also be used as a buffer control output by setting the BCTR.
21	23	P21/HAK	F	General-purpose output port When an external bus is used, this port can also be used as a hold acknowledge output by setting the BCTR.
20	22	P22/HRQ	D	General-purpose output port When an external bus is used, this port can also be used as a hold request input by setting the BCTR.
19	21	P23/RDY	D	General-purpose output port When an external bus is used, this port functions as a ready input.
18	20	P24/CLK	F	General-purpose output port When an external bus is used, this port functions as a clock output.
17	19	P25/WR	F	General-purpose output port When an external bus is used, this port functions as a write signal output.
16	18	P26/RD	F	General-purpose output port When an external bus is used, this port functions as a read signal output.
15	17	P27/ALE	F	General-purpose output port When an external bus is used, this port functions as an address latch signal output.

*1: FPT-80P-M22

*2: FPT-80P-M06

*3: MQP-80C-P01

(Continued)

MB89670AR Series

Pin no.		Pin name	Circuit type	Function
LQFP ^{*1}	QFP ^{*2} MQFP ^{*3}			
46	48	P30/PWM20	D	General-purpose I/O port Also serves as the PWM20 output for the 8-bit PWM timer.
45	47	P31/PWM21	D	General-purpose I/O port Also serves as the PWM21 output for the 8-bit PWM timer.
44	46	P32/UDZ1	E	General-purpose I/O port Also serves as the Z-phase input for the 8/16-bit up/down counter/timer.
43	45	P33/UDB1	E	General-purpose I/O port Also serves as the B-phase input for the 8/16-bit up/down counter/timer.
42	44	P34/UDA1	E	General-purpose I/O ports Also serves as the A-phase input for the 8/16-bit up/down counter/timer.
41	43	P35/UDZ2	E	General-purpose I/O port Also serves as the Z-phase input for the 8/16-bit up/down counter/timer.
40	42	P36/UDB2	E	General-purpose I/O port Also serves as the B-phase input for the 8/16-bit up/down counter/timer.
39	41	P37/UDA2	E	General-purpose I/O port Also serves as the A-phase input for the 8/16-bit up/down counter/timer.
55	57	P40/PWM00	D	General-purpose I/O port Also serves as the PWM00 output for the 8-bit PWM timer.
54	56	P41/PWM01	D	General-purpose I/O port Also serves as the PWM01 output for the 8-bit PWM timer.
52	54	P42/PWM10/ BZ2	D	General-purpose I/O port Also serves as the PWM10 and the BZ2 output for the 8-bit PWM timer.
51	53	P43/PWM11	D	General-purpose I/O port Also serves as the PWM11 output for the 8-bit PWM timer.
50	52	P44/TCI	E	General-purpose I/O port Also serves as the TCI input for the 8/16-bit timer/counter.
49	51	P45/TCO1	D	General-purpose I/O port Also serves as the TCO1 output for the 8/16-bit timer/counter.
48	50	P46/TCO2	D	General-purpose I/O port Also serves as the TCO2 output for the 8/16-bit timer/counter.

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- *1: FPT-80P-M22
- *2: FPT-80P-M06
- *3: MQP-80C-P01

MB89670AR Series

(Continued)

Pin no.		Pin name	Circuit type	Function
LQFP ^{*1}	QFP ^{*2} MQFP ^{*3}			
47	49	P47/EC	E	General-purpose I/O port Also serves as the input for the 16-bit timer/counter. The EC input is of a hysteresis input type.
74 to 67	76 to 69	P50/AN0 to P57/AN7	I	N-ch open-drain output ports Also serve as the analog inputs for the 10-bit A/D converter.
66	68	P60/INT0/ ADST	J	General-purpose input port The software pull-up resistor is provided. Also serves as an external interrupt input (INT0) and an 10-bit A/D converter external start-up. This port is of a hysteresis input type.
65 to 59	67 to 61	P61/INT1 to P67/INT7	J	General-purpose input ports A software pull-up resistor is provided. Also serve as external interrupt inputs (INT1 to INT7). These ports are of a hysteresis input type.
4	6	P70/BZ1	G	N-ch open-drain I/O port Also serves as a buzzer output.
3	5	P71/UCK	K	N-ch open-drain I/O port Also serves as a UART clock I/O (UCK), switchable to CMOS.
2	4	P72/UO	K	N-ch open-drain I/O port Also serves as a UART data output (UO), switchable to CMOS.
1	3	P73/UI	G	N-ch open-drain I/O port Also serves as a UART data input (UI).
80	2	P74/SCK	K	N-ch open-drain I/O port Also serves as the clock I/O (SCK) for the 8-bit serial I/O, switchable to CMOS.
79	1	P75/SO	K	N-ch open-drain I/O port Also serves as the data output (SO) for the 8-bit serial I/O, switchable to CMOS.
78	80	P76/SI	G	N-ch open-drain I/O port Also serves as the data input (SI) for the 8-bit serial I/O.
8 to 5, 57, 58	10 to 7, 59, 60	P80 to P83, P85, P84	H	N-ch open-drain output ports
53	55	V _{cc}	—	Power supply pin
13, 56	15, 58	V _{ss}	—	Power supply (GND) pin
75	77	AV _{cc}	—	A/D converter power supply pin Use this pin at the same voltage as V _{cc} .
76	78	AV _R	—	A/D converter reference voltage input pin
77	79	AV _{ss}	—	A/D converter power supply pin Use this pin at the same voltage as V _{ss} .

*1: FPT-80P-M22

*2: FPT-80P-M06

*3: MQP-80C-P01

MB89670AR Series

- External EPROM pins (MB89PV670A only)

Pin no.	Pin name	I/O	Function
82 83 84 85 86 87 88 89 90 91	A15 A12 A7 A6 A5 A4 A3 A2 A1 A0	O	Address output pins
93 94 95	O1 O2 O3	I	Data input pins
96	V _{SS}	O	Power supply (GND) pin
98 99 100 101 102	O4 O5 O6 O7 O8	I	Data input pins
103	\overline{CE}	O	ROM chip enable pin Outputs "H" during standby.
104	A10	O	Address output pin
105	\overline{OE}/V_{PP}	O	ROM output enable pin Outputs "L" at all times.
107 108 109	A11 A9 A8	O	Address output pins
110	A13	O	
111	A14	O	
112	V _{CC}	O	Power supply pin for EPROM
81 92 97 106	N.C.	—	Internally connected pins Be sure to leave them open.

■ I/O CIRCUIT TYPE

Type	Circuit	Remarks
A	<p>Standby control signal</p>	<ul style="list-style-type: none"> • Crystal or ceramic oscillation type • Oscillation feedback resistor of approximately 1 MΩ at 5.0 V
B		
C		<ul style="list-style-type: none"> • Output pull-up resistor (P-ch) of approximately 50 kΩ at 5.0 V • Hysteresis input
D		<ul style="list-style-type: none"> • CMOS output • CMOS inout • Pull-up resistor optional (except P22 and P23)
E		<ul style="list-style-type: none"> • CMOS output • CMOS input • The peripheral is of a hysteresis input type. • Pull-up resistor optional

(Continued)

MB89670AR Series

(Continued)

Type	Circuit	Remarks
F		<ul style="list-style-type: none"> • CMOS output
G		<ul style="list-style-type: none"> • N-ch open-drain output • Hysteresis input • Pull-up resistor optional
H		<ul style="list-style-type: none"> • N-ch open-drain output
I		<ul style="list-style-type: none"> • N-ch open-drain output • Analog input
J		<ul style="list-style-type: none"> • Hysteresis input • With software pull-up resistor
K		<ul style="list-style-type: none"> • CMOS output • Hysteresis input • Pull-up resistor optional

■ HANDLING DEVICES

1. Preventing Latchup

Latchup may occur on CMOS ICs if voltage higher than V_{CC} or lower than V_{SS} is applied to input and output pins other than medium- and high-voltage pins or if higher than the voltage which shows on “1. Absolute Maximum Ratings” in section “■ Electrical Characteristics” is applied between V_{CC} and V_{SS} .

When latchup occurs, power supply current increases rapidly and might thermally damage elements. When using, take great care not to exceed the absolute maximum ratings.

Also, take care to prevent the analog power supply (AV_{CC} and AVR) and analog input from exceeding the digital power supply (V_{CC}) when the analog system power supply is turned on and off.

2. Treatment of Unused Input Pins

Leaving unused input pins open could cause malfunctions. They should be connected to a pull-up or pull-down resistor.

3. Treatment of Power Supply Pins on Microcontrollers with A/D and D/A Converters

Connect to be $AV_{CC} = DAVC = V_{CC}$ and $AV_{SS} = AVR = V_{SS}$ even if the A/D and D/A converters are not in use.

4. Treatment of N.C. Pins

Be sure to leave (internally connected) N.C. pins open.

5. Power Supply Voltage Fluctuations

Although V_{CC} power supply voltage is assured to operate within the rated range, a rapid fluctuation of the voltage could cause malfunctions, even if it occurs within the rated range. Stabilizing voltage supplied to the IC is therefore important. As stabilization guidelines, it is recommended to control power so that V_{CC} ripple fluctuations (P-P value) will be less than 10% of the standard V_{CC} value at the commercial frequency (50 Hz to 60 Hz) and the transient fluctuation rate will be less than 0.1 V/ms at the time of a momentary fluctuation such as when power is switched.

6. Precautions when Using an External Clock

When an external clock is used, oscillation stabilization time is required even for power-on reset (optional) and wake-up from stop mode.

MB89670AR Series

■ PROGRAMMING TO THE PROM ON THE MB89P677A

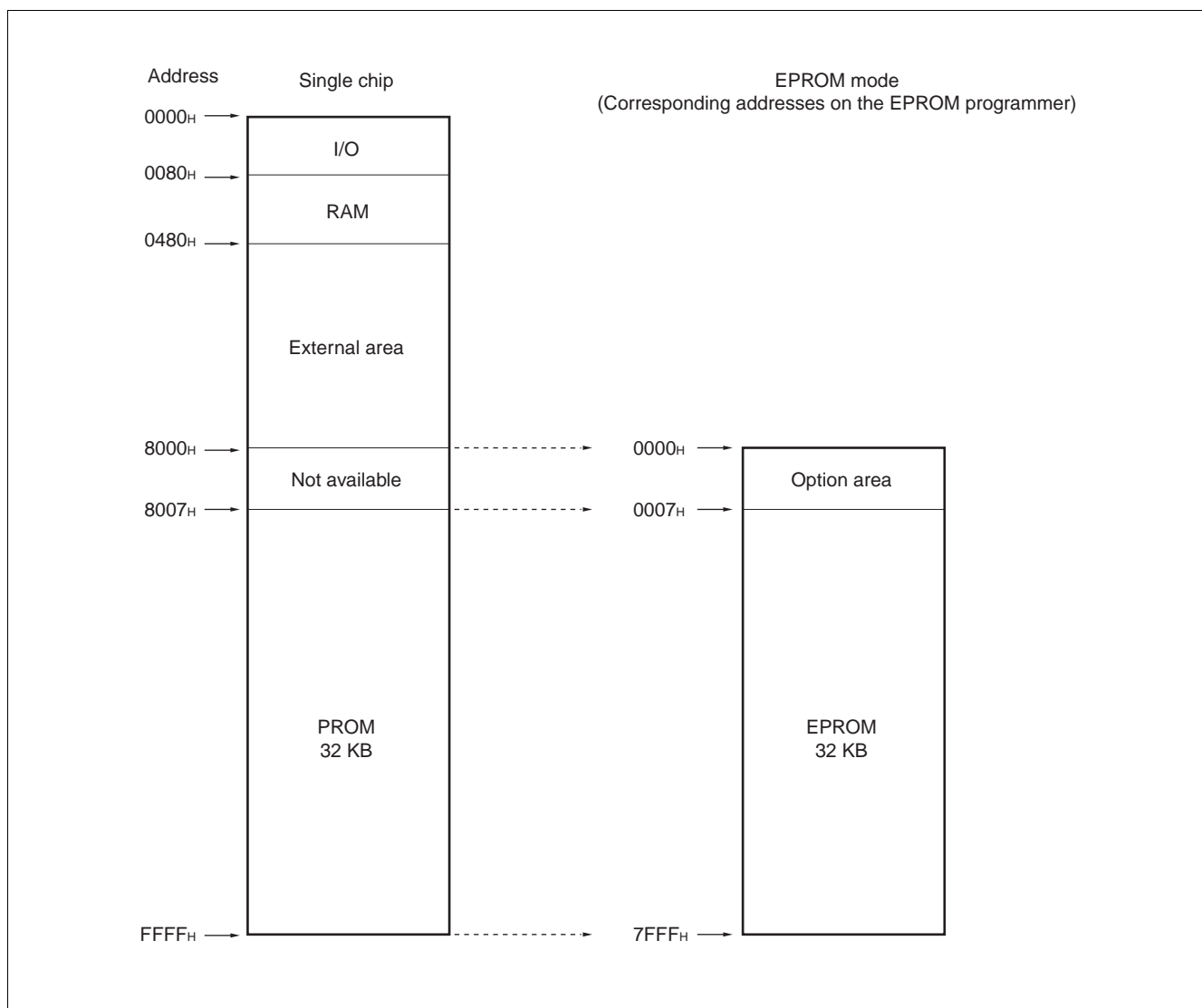
The MB89P677A is an OTPROM version of the MB89670AR series.

1. Features

- 32-Kbyte PROM on chip
- Options can be set using the EPROM programmer.
- Equivalency to the MBM27C256A in the EPROM mode (when programmed with the EPROM programmer)

2. Memory Space

Memory space in the EPROM mode is diagrammed below.



3. Programming to the PROM

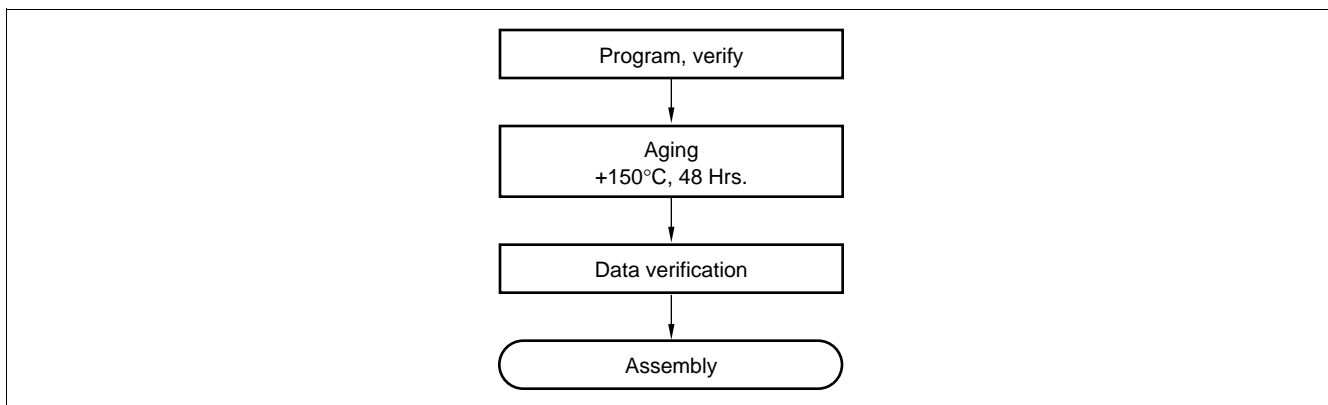
In EPROM mode, the MB89P677A functions equivalent to the MBM27C256A. This allows the PROM to be programmed with a general-purpose EPROM programmer (the electronic signature mode cannot be used) by using the dedicated socket adapter.

- **Programming procedure**

- (1) Set the EPROM programmer to the MBM27C256A.
- (2) Load program data into the EPROM programmer at 0007_H to 7FFF_H (note that addresses 8007_H to FFFF_H while operating as a single chip assign to 0007_H to 7FFF_H in the EPROM mode).
Load option data into addresses 0000_H to 0006_H of the EPROM programmer. (For information about each corresponding option, see “7. Setting OTPROM Options”.)
- (3) Program with the EPROM programmer.

4. Recommended Screening Conditions

High-temperature aging is recommended as the pre-assembly screening procedure for a product with a blanked OTPROM microcomputer program.



5. Programming Yield

Due to the nature of the blanked OTPROM microcomputer, bit programming test can't be conducted as Fujitsu's shipping test. Therefore a programming yield of 100% cannot be assured at all times.

MB89670AR Series

6. Setting PROM Options

The programming procedure is the same as that for the PROM.

Options can be set by programming values at the addresses shown on the memory map. The relationship between bits and options is shown on the following bit map:

- PROM option bit map

Address	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0000 _H	Vacancy	Vacancy	Vacancy	Vacancy	Reset pin output 1: Yes 0: No	Power-on reset 1: Yes 0: No	Oscillation stabilization time	
	Readable	Readable	Readable	Readable			00: 2 ⁴ /F _c 01: 2 ¹⁴ /F _c 10: 2 ¹⁷ /F _c 11: 2 ¹⁸ /F _c	
0001 _H	P17 Pull-up 1: No 0: Yes	P16 Pull-up 1: No 0: Yes	P15 Pull-up 1: No 0: Yes	P14 Pull-up 1: No 0: Yes	P13 Pull-up 1: No 0: Yes	P12 Pull-up 1: No 0: Yes	P11 Pull-up 1: No 0: Yes	P10 Pull-up 1: No 0: Yes
0002 _H	P37 Pull-up 1: No 0: Yes	P36 Pull-up 1: No 0: Yes	P35 Pull-up 1: No 0: Yes	P34 Pull-up 1: No 0: Yes	P33 Pull-up 1: No 0: Yes	P32 Pull-up 1: No 0: Yes	P31 Pull-up 1: No 0: Yes	P30 Pull-up 1: No 0: Yes
0003 _H	P47 Pull-up 1: No 0: Yes	P46 Pull-up 1: No 0: Yes	P45 Pull-up 1: No 0: Yes	P44 Pull-up 1: No 0: Yes	P43 Pull-up 1: No 0: Yes	P42 Pull-up 1: No 0: Yes	P41 Pull-up 1: No 0: Yes	P40 Pull-up 1: No 0: Yes
0004 _H	Vacancy Readable	Vacancy Readable	Vacancy Readable	Vacancy Readable	Vacancy Readable	Vacancy Readable	Vacancy Readable	Vacancy Readable
0005 _H	Vacancy Readable	Vacancy Readable	Vacancy Readable	P74 Pull-up 1: No 0: Yes	P73 Pull-up 1: No 0: Yes	P72 Pull-up 1: No 0: Yes	P71 Pull-up 1: No 0: Yes	P70 Pull-up 1: No 0: Yes
0006 _H	Vacancy Readable	Vacancy Readable	Vacancy Readable	Vacancy Readable	P04 to P07 Pull-up 1: No 0: Yes	P00 to P03 Pull-up 1: No 0: Yes	P76 Pull-up 1: No 0: Yes	P75 Pull-up 1: No 0: Yes

- Notes:
- Each bit is set to “1” as the initialized value.
 - Do not write “0” to the vacant bit.
The read value of the vacant bit is “1”, unless “0” is written to it.

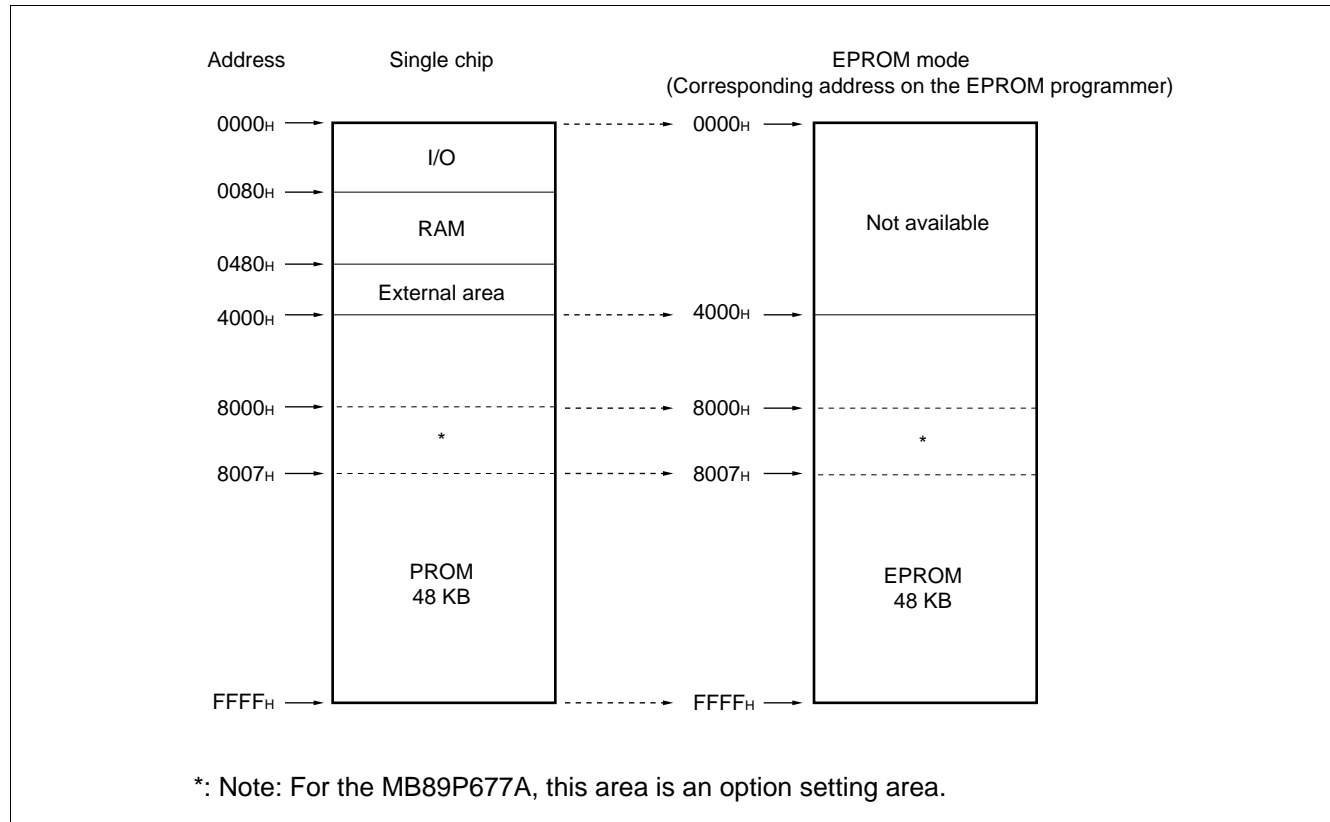
■ PROGRAMMING TO THE EPROM WITH PIGGYBACK/EVALUATION DEVICE

1. EPROM for Use

MBM27C512-20TV

2. Memory Space

Memory space in each mode is diagrammed below.



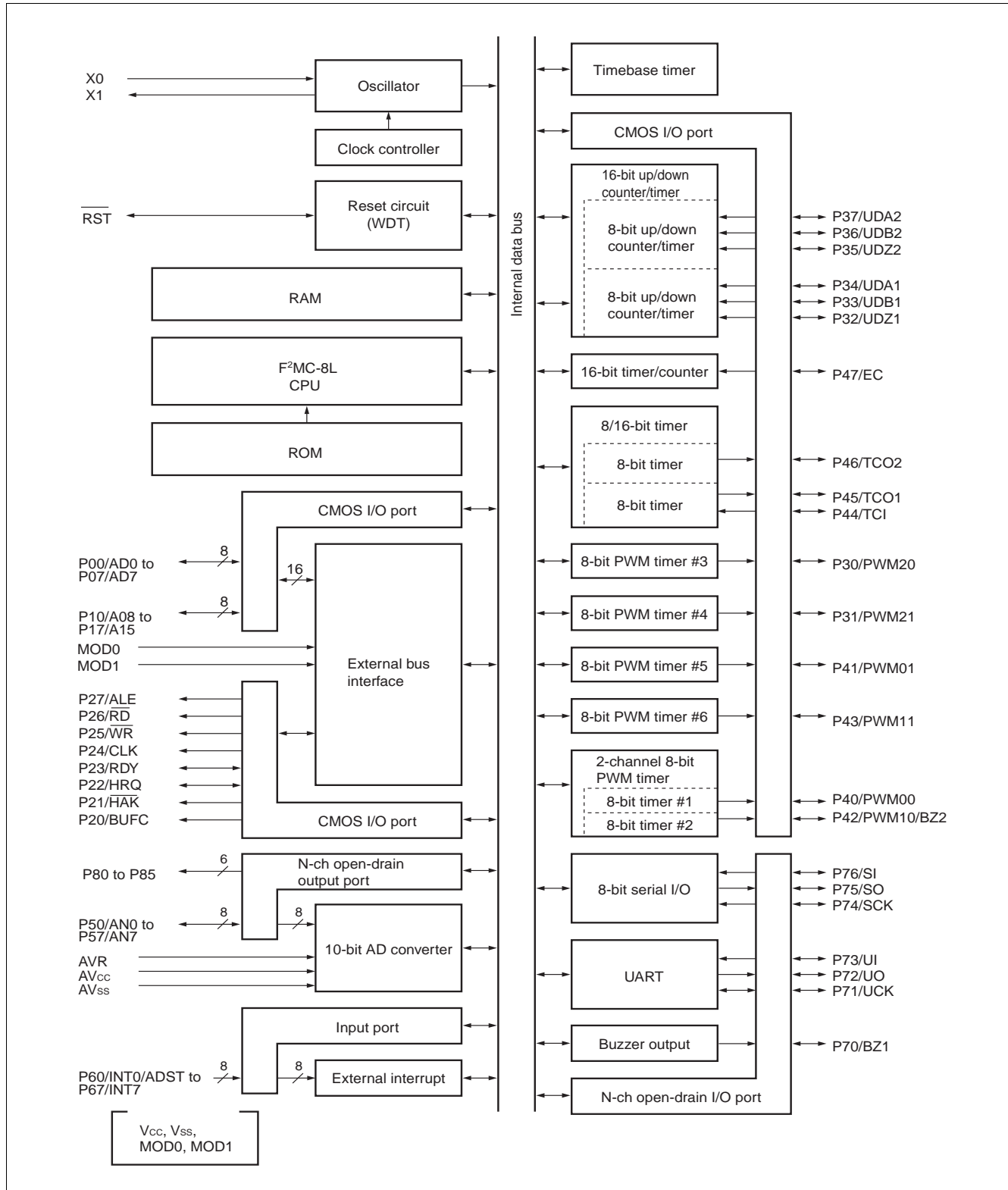
3. Programming to the EPROM

- (1) Set the EPROM programmer to the MBM27C512.
- (2) Load program data into the EPROM programmer at 4000H to FFFFH.
- (3) Program to 4000H to FFFFH with the EPROM programmer.

MB89670AR Series

■ BLOCK DIAGRAM

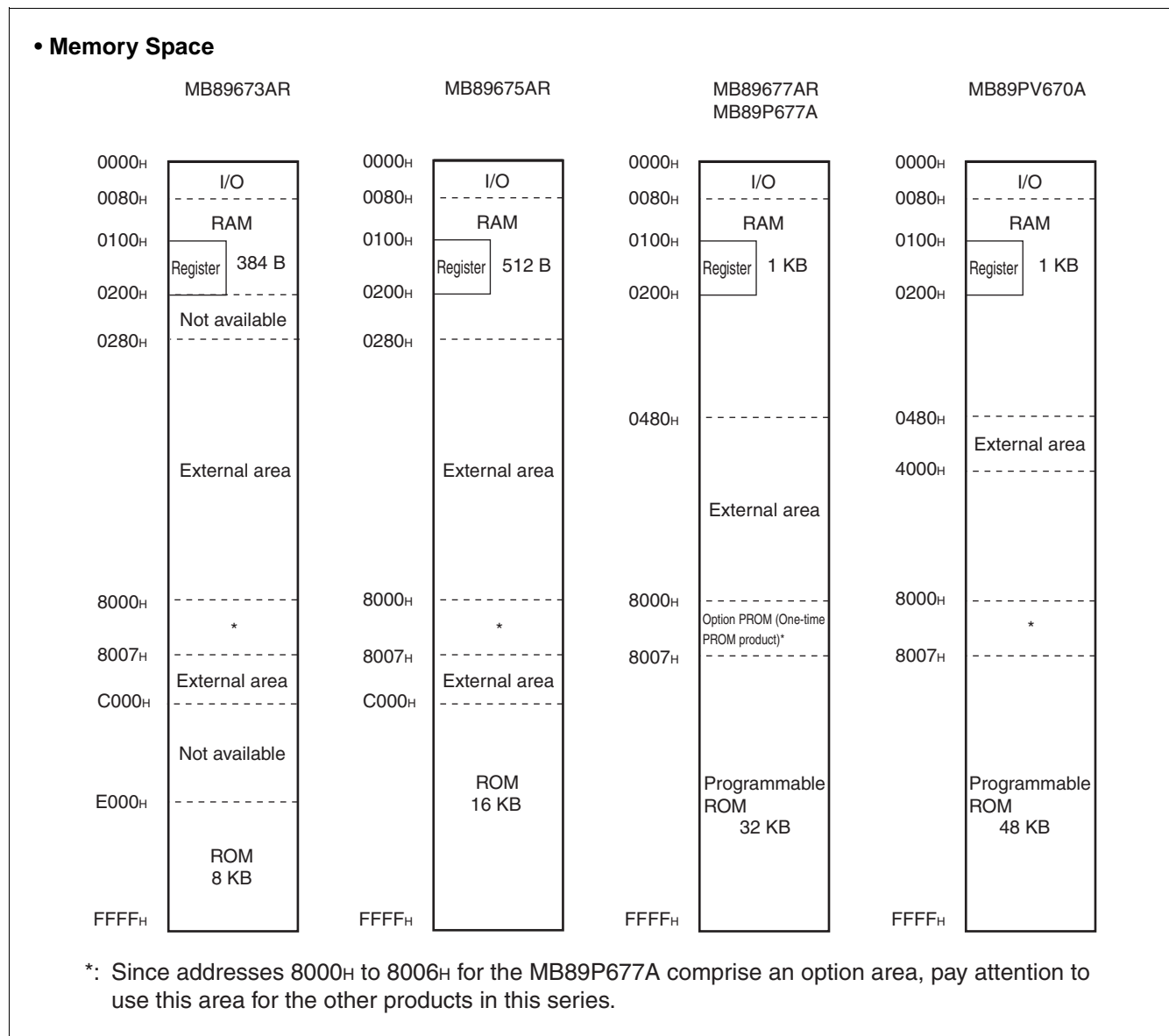
• Block Diagram of MB89673AR /89675AR/89677AR/89P677A/89PV670A



■ CPU CORE

1. Memory Space

The microcontrollers of the MB89670AR series offer 64 Kbytes of memory for storing all of I/O, data, and program areas. The I/O area is allocated at the lowest address. The data area is allocated immediately above the I/O area. The data area can be divided into register, stack, and direct areas according to the application. The program area is allocated from exactly the opposite end of I/O area, that is, near the highest address. The tables of interrupt reset vectors and vector call instructions are allocated from the highest address within the program area. The memory space of the MB89670AR series is structured as illustrated below.

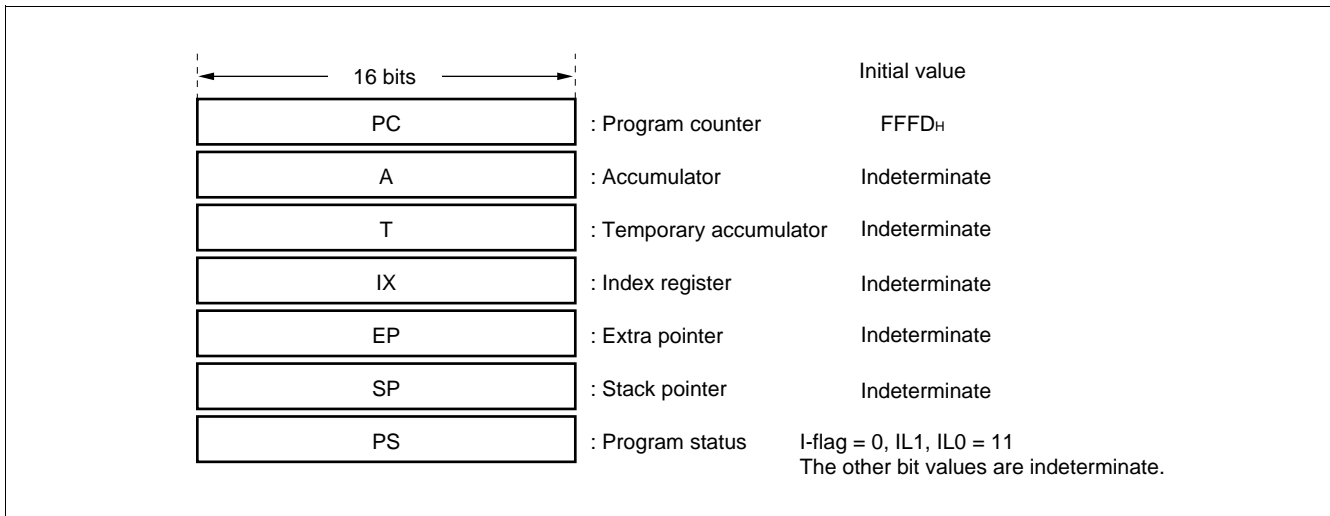


MB89670AR Series

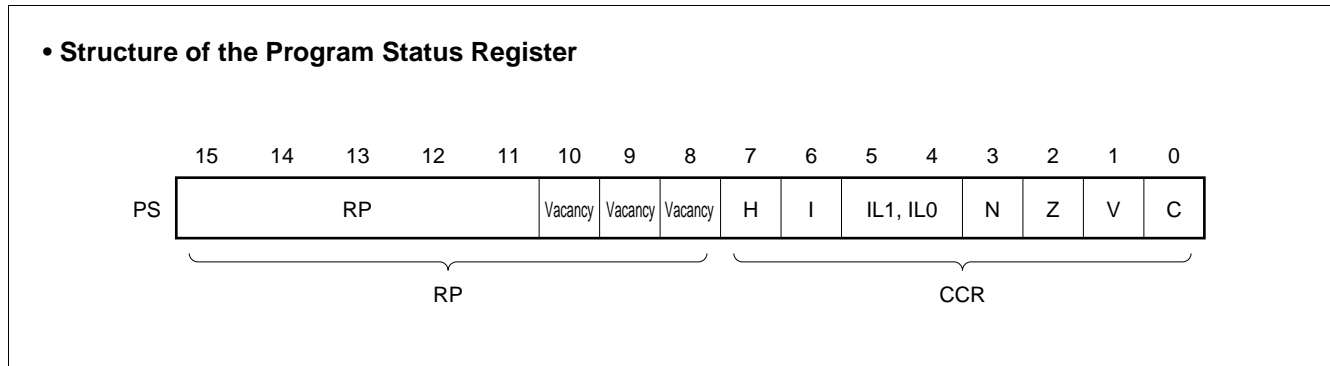
2. Registers

The F²MC-8L family has two types of registers; dedicated hardware registers in the CPU and general-purpose registers in the memory. The following dedicated registers are provided:

- Program counter (PC): A 16-bit register for indicating the instruction storage positions
- Accumulator (A): A 16-bit temporary register for storing arithmetic operations, etc. When the instruction is an 8-bit data processing instruction, the lower byte is used.
- Temporary accumulator (T): A 16-bit register which performs arithmetic operations with the accumulator. When the instruction is an 8-bit data processing instruction, the lower byte is used.
- Index register (IX): A 16-bit register for index modification
- Extra pointer (EP): A 16-bit pointer for indicating a memory address
- Stack pointer (SP): A 16-bit register for indicating a stack area
- Program status (PS): A 16-bit register for storing a register pointer, a condition code

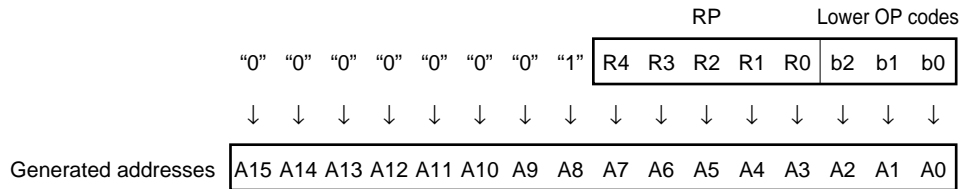


The PS can further be divided into higher 8 bits for use as a register bank pointer (RP) and the lower 8 bits for use as a condition code register (CCR). (See the diagram below.)



The RP indicates the address of the register bank currently in use. The relationship between the pointer contents and the actual address is based on the conversion rule illustrated below.

• **Rule for Conversion of Actual Addresses of the General-purpose Register Area**



The CCR consists of bits indicating the results of arithmetic operations and the contents of transfer data and bits for control of CPU operations at the time of an interrupt.

H-flag: Set to '1' when a carry or a borrow from bit 3 to bit 4 occurs as a result of an arithmetic operation. Cleared to '0' otherwise. This flag is for decimal adjustment instructions.

I-flag: Interrupt is enabled when this flag is set to '1'. Interrupt is disabled when the flag is cleared to '0'. Cleared to '0' at the reset.

IL1, ILO: Indicates the level of the interrupt currently allowed. Processes an interrupt only if its request level is higher than the value indicated by this bit.

IL1	ILO	Interrupt level	High-low
0	0	1	High
0	1		↑
1	0	2	↓
1	1	3	

N-flag: Set to '1' if the MSB becomes '1' as the result of an arithmetic operation. Cleared to '0' when the bit is cleared to '0'.

Z-flag: Set to '1' when an arithmetic operation results in 0. Cleared to '0' otherwise.

V-flag: Set to '1' if the complement on 2 overflows as a result of an arithmetic operation. Cleared to '0' if the overflow does not occur.

C-flag: Set to '1' when a carry or a borrow from bit 7 occurs as a result of an arithmetic operation. Cleared to '0' otherwise. Set to the shift-out value in the case of a shift instruction.

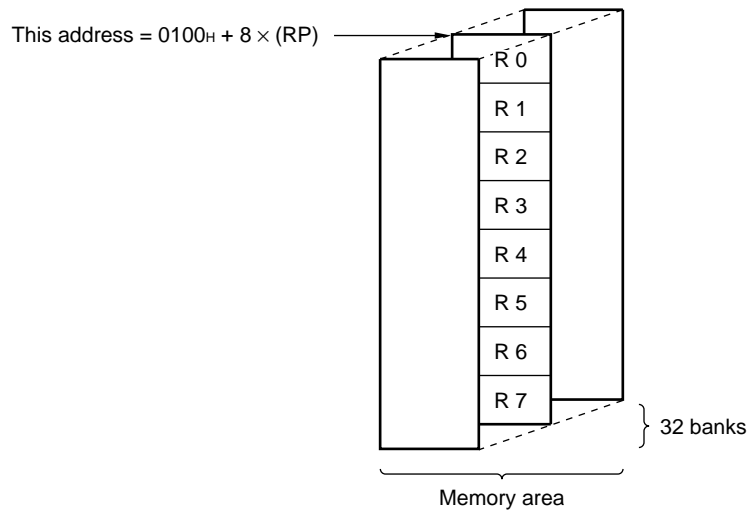
MB89670AR Series

The following general-purpose registers are provided:

General-purpose registers: An 8-bit register for storing data

The general-purpose registers are of 8 bits each and allocated in the register banks of the memory. One bank contains eight registers and up to 32 banks can be used on every product of the MB89670AR series. The bank currently in use is indicated by the register bank pointer (RP).

• Register Bank Configuration



MB89670AR Series

■ I/O MAP

Address	Read/Write	Register abbreviation	Register name
00 _H	(R/W)	PDR0	Port 0 data register
01 _H	(W)	DDR0	Port 0 data direction register
02 _H	(R/W)	PDR1	Port 1 data register
03 _H	(W)	DDR1	Port 1 data direction register
04 _H	(R/W)	PDR2	Port 2 data register
05 _H	(W)	BCTR	External bus pin control register
06 _H	(Vacancy)		
07 _H	(R/W)	SYCC	System clock control register
08 _H	(R/W)	STBC	Standby control register
09 _H	(R/W)	WDTC	Watchdog timer control register
0A _H	(R/W)	TBTC	Timebase timer control register
0B _H	(Vacancy)		
0C _H	(R/W)	PDR3	Port 3 data register
0D _H	(W)	DDR3	Port 3 data direction register
0E _H	(R/W)	PDR4	Port 4 data register
0F _H	(W)	DDR4	Port 4 data direction register
10 _H	(R/W)	PDR5	Port 5 data register
11 _H	(R)	PDR6	Port 6 data register
12 _H	(R/W)	PPCR	Port 6 pull-up control register
13 _H	(R/W)	PDR7	Port 7 data register
14 _H	(R/W)	PDR8	Port 8 data/port 7 swiching register
15 _H	(R/W)	BZCR	Buzzer register
16 _H	(R/W)	CNTR #3	PWM control register #3
17 _H	(R/W)	COMP #3	PWM compare register #3
18 _H	(R/W)	TMCR	16-bit timer control register
19 _H	(R/W)	TCHR	16-bit timer count register (H)
1A _H	(R/W)	TCLR	16-bit timer count register (L)
1B _H	(Vacancy)		
1C _H	(R/W)	SMR	Serial mode register
1D _H	(R/W)	SDR	Serial data register
1E _H , 1F _H	(Vacancy)		

(Continued)

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Address	Read/Write	Register abbreviation	Register name
20 _H	(R/W)	ADC1	A/D converter control register 1
21 _H	(R/W)	ADC2	A/D converter control register 2
22 _H	(R/W)	ADCH	A/D converter data register H
23 _H	(R/W)	ADCL	A/D converter data register L
24 _H	(R/W)	T2CR	Timer 2 control register
25 _H	(R/W)	T1CR	Timer 1 control register
26 _H	(R/W)	T2DR	Timer 2 data register
27 _H	(R/W)	T1DR	Timer 1 data register
28 _H	(R/W)	CNTR1	PWM 1 control register
29 _H	(R/W)	CNTR2	PWM 2 control register
2A _H	(R/W)	CNTR3	PWM 3 control register
2B _H	(W)	COMR2	PWM 2 compare register
2C _H	(W)	COMR1	PWM 1 compare register
2D _H to 2F _H	(Vacancy)		
30 _H	(R) (W)	UDCR1 RCR1	Up/down counter register 1 Reload compare register1
31 _H	(R) (W)	UDCR2 RCR2	Up/down counter register 2 Reload compare register2
32 _H	(R/W)	CCRA1	Counter control register A1
33 _H	(R/W)	CCRA2	Counter control register A2
34 _H	(R/W)	CCRB1	Counter control register B1
35 _H	(R/W)	CCRB2	Counter control register B2
36 _H	(R/W)	CSR1	Counter status register 1
37 _H	(R/W)	CSR2	Counter status register 2
38 _H	(R/W)	EIC1	External interrupt 1 control register 1
39 _H	(R/W)	EIC2	External interrupt 1 control register 2
3A _H	(R/W)	EIE2	External interrupt 2 control register
3B _H	(R/W)	EIF2	External interrupt 2 flag register
3C _H to 3F _H	(Vacancy)		

(Continued)

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(Continued)

Address	Read/Write	Register abbreviation	Register name
40 _H	(R/W)	USMR	UART serial mode register
41 _H	(R/W)	USCR	UART serial rate control register
42 _H	(R/W)	USTR	UART status register
43 _H	(R) (W)	RXDR TXDR	UART receiving data register UART transmitting data register
44 _H	(Vacancy)		
45 _H	(R/W)	RRDR	Baud rate generator reload data register
46 _H , 47 _H	(Vacancy)		
48 _H	(R/W)	CNTR #4	PWM control register #4
49 _H	(R/W)	COMP #4	PWM compare register #4
4A _H	(R/W)	CNTR #5	PWM control register #5
4B _H	(R/W)	COMP #5	PWM compare register #5
4C _H	(R/W)	CNTR #6	PWM control register #6
4D _H	(R/W)	COMP #6	PWM compare register #6
4E to 7B _H	(Vacancy)		
7C _H	(W)	ILR1	Interrupt level setting register 1
7D _H	(W)	ILR2	Interrupt level setting register 2
7E _H	(W)	ILR3	Interrupt level setting register 3
7F _H	(Vacancy)		

Note: Do not use (vacancies).

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■ ELECTRICAL CHARACTERISTICS

1. Absolute Maximum Ratings

($AV_{SS} = V_{SS} = 0.0\text{ V}$)

Parameter	Symbol	Rated value		Unit	Remarks
		Min.	Max.		
Power supply voltage	V_{CC}	$V_{SS} - 0.3$	$V_{SS} + 7.0$	V	*
	AV_{CC}	$V_{SS} - 0.3$	$V_{CC} + 0.3$	V	*
A/D converter reference input voltage	AVR	$V_{SS} - 0.3$	$V_{CC} + 0.3$	V	AVR must not exceed " $AV_{CC} + 0.3\text{ V}$ ".
Input voltage	V_I	$V_{SS} - 0.3$	$V_{CC} + 0.3$	V	
Output voltage	V_{O1}	$V_{SS} - 0.3$	$V_{CC} + 0.3$	V	Except P80 to P85
	V_{O2}	$V_{SS} - 0.3$	$V_{SS} + 7.0$	V	P80 to P85
"L" level maximum output current	I_{OL}	—	20	mA	
"L" level average output current	I_{OLAV1}	—	4	mA	Average value (operating current × operating rate)
	I_{OLAV2}	—	8	mA	Average value (operating current × operating rate) P80 to P85
"L" level total maximum output current	ΣI_{OL}	—	100	mA	
"L" level total average output current	ΣI_{OLAV}	—	40	mA	Average value (operating current × operating rate)
"H" level maximum output current	I_{OH}	—	-20	mA	
"H" level average output current	I_{OHAV}	—	-4	mA	Average value (operating current × operating rate)
"H" level total maximum output current	ΣI_{OH}	—	-50	mA	
"H" level total average output current	ΣI_{OHAV}	—	-20	mA	Average value (operating current × operating rate)
Power consumption	P_D	—	300	mW	
Operating temperature	T_A	-40	+85	°C	
Storage temperature	T_{stg}	-55	+150	°C	

* : Use AV_{CC} and V_{CC} set at the same voltage.

Take care that AVR does not exceed " $AV_{CC} + 0.3\text{ V}$ " and AV_{CC} does not exceed V_{CC} , such as when power is turned on.

WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

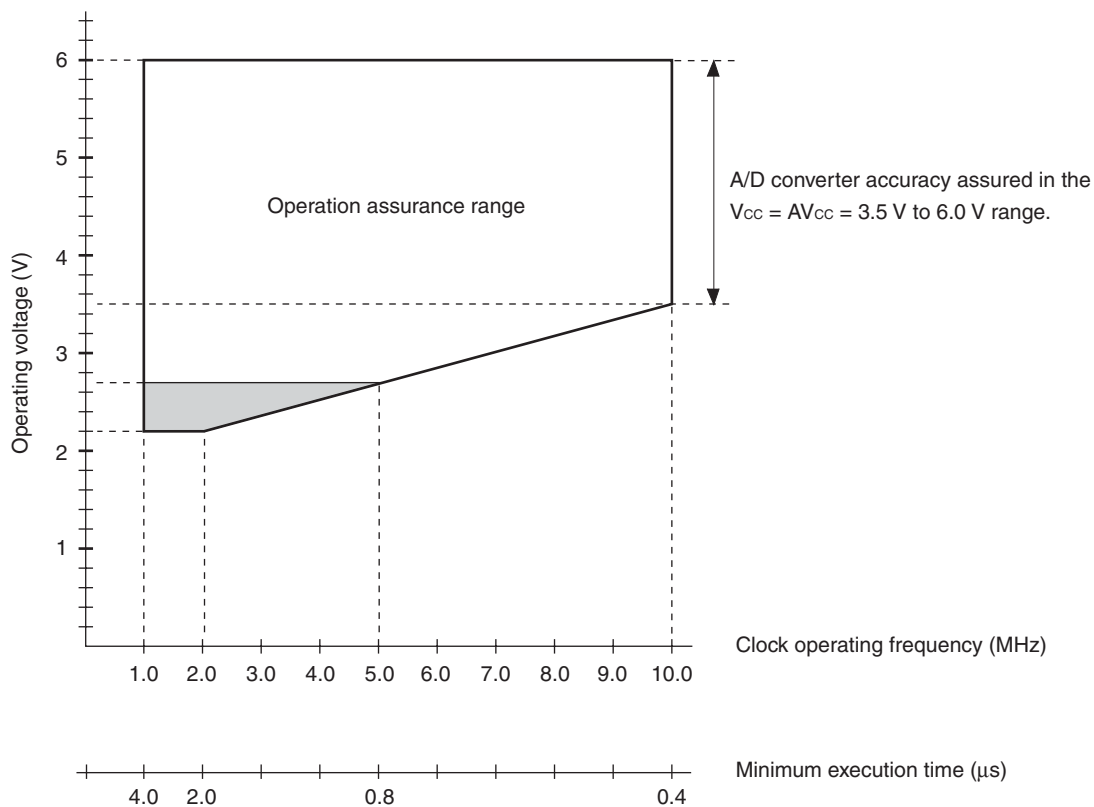
2. Recommended Operating Conditions

(AV_{SS} = V_{SS} = 0.0 V)

Parameter	Symbol	Rated value		Unit	Remarks
		Min.	Max.		
Power supply voltage	V _{CC}	2.2*	6.0	V	Normal operation assurance range MB89673AR/675AR/677AR
	AV _{CC}	2.7*	6.0	V	Normal operation assurance range MB89PV670A/P677A
		1.5	6.0	V	Retains the RAM state in the stop mode
A/D converter reference input voltage	AVR	0.0	AV _{CC}	V	
Operating temperature	T _A	-40	+85	°C	

* : These values vary with the operating frequency, and analog assurance range. See Figure 1 and "5. A/D Converter Electrical Characteristics".

Figure 1 Operating Voltage vs. Clock Operating Frequency



Note: The shaded area is additional operating assurance range only for the MB89673AR/675AR/677AR.

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The horizontal line of the graph in the figure 1 indicates the operating frequency of the external oscillator and the lower horizontal line indicates the min. instruction execution time = $4/F_c$.

In the case of changing the operating clock with the clock gear function, be sure to convert it into the min. instruction execution time on the lower horizontal line since the operating voltage range is dependent on the min. instruction execution time.

WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their representatives beforehand.

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3. DC Characteristics

($A_{V_{CC}} = V_{CC} = 5.0 \text{ V} \pm 10\%$, $A_{V_{SS}} = V_{SS} = 0.0 \text{ V}$, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$)

Parameter	Symbol	Pin name	Condition	Rated value			Unit	Remarks
				Min.	Typ.	Max.		
“H” level input voltage	V_{IH}	P00 to P07, P10 to P17, P30 to P37, P40 to P47	—	0.7 V_{CC}	—	$V_{CC} + 0.3$	V	P32 to P37, P44, and P47 are of a port input type.
	V_{IHS}	\overline{RST} , MOD0, MOD1, P32 to P37, P44, P47, P60 to P67, P70 to P76		0.8 V_{CC}	—	$V_{CC} + 0.3$	V	P32 to P37, P44, and P47 are of a peripheral input type.
“L” level input voltage	V_{IL}	P00 to P07, P10 to P17, P30 to P37, P40 to P47		$V_{SS} - 0.3$	—	0.3 V_{CC}	V	P32 to P37, P44, and P47 are of a port input type.
	V_{ILS}	\overline{RST} , MOD0, MOD1, P32 to P37, P44, P47, P60 to P67, P70 to P76		$V_{SS} - 0.3$	—	0.2 V_{CC}	V	P32 to P37, P44, and P47 are of a peripheral input type.
Open-drain output pin applied voltage	V_D	P80 to P85		$V_{SS} - 0.3$	—	$V_{SS} + 6.0$	V	
“H” level output voltage	V_{OH}	P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P71, P72, P74, P75	$I_{OH} = -2.0 \text{ mA}$	4.0	—	—	V	
“L” level output voltage	V_{OL1}	P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P50 to P57, P70 to P76	$I_{OL} = 4.0 \text{ mA}$	—	—	0.4	V	
	V_{OL2}	P80 to P85	$I_{OL} = 10 \text{ mA}$	—	—	0.5	V	
	V_{OL3}	\overline{RST}	$I_{OL} = 4.0 \text{ mA}$	—	—	0.4	V	
Input leakage current (Hi-z output leakage current)	I_{LI1}	P00 to P07, P10 to P17, P20 to P27, P30 to P37, P40 to P47, P50 to P57, P60 to P67, P70 to P76, MOD0, MOD1	$0.0 \text{ V} < V_i < V_{CC}$	—	—	± 5	μA	Without pull-up resistor option
	I_{LI2}	P80 to P85	$0.0 \text{ V} < V_i < V_{CC}$	—	—	± 1	μA	
Pull-up resistance	R_{PULL}	P00 to P07, P10 to P17, P30 to P37, P40 to P47, P60 to P67, P70 to P76, \overline{RST}	$V_i = 0.0 \text{ V}$	25	50	100	k Ω	With pull-up resistor option

(Continued)

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(Continued)

($AV_{CC} = V_{CC} = 5.0 \text{ V} \pm 10\%$, $AV_{SS} = V_{SS} = 0.0 \text{ V}$, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$)

Parameter	Symbol	Pin name	Condition	Rated value			Unit	Remarks	
				Min.	Typ.	Max.			
Power supply current*1	I_{CC1}	V_{CC}	$F_C = 10 \text{ MHz}$ $V_{CC} = 5.0 \text{ V}$ $t_{inst}^* = 0.4 \mu\text{s}$	—	12	20	mA		
	I_{CC2}		$F_C = 10 \text{ MHz}$ $V_{CC} = 3.0 \text{ V}$ $t_{inst}^* = 6.4 \mu\text{s}$	—	1	2	mA	MB89673AR/ 675AR/677AR/ PV670A	
				—	1.5	2.5	mA	MB89P677A	
	I_{CCS1}		I_{CCS2}	Sleep mode $F_C = 10 \text{ MHz}$ $V_{CC} = 5.0 \text{ V}$ $t_{inst}^* = 0.4 \mu\text{s}$	—	3	7	mA	
					$F_C = 10 \text{ MHz}$ $V_{CC} = 3.0 \text{ V}$ $t_{inst}^* = 6.4 \mu\text{s}$	—	1	1.5	mA
	I_{CCH}			$V_{CC} = 3.0 \text{ V}$ $T_A = +25^\circ\text{C}$ Stop mode	—	—	1	mA	
	I_A	AV_{CC}	$F_C = 10 \text{ MHz}$ When A/D converter starts	—	6	8	mA		
I_{AH}	$F_C = 10 \text{ MHz}$ $T_A = +25^\circ\text{C}$ When A/D converter is at a stop		—	—	1	μA			
Input capacitance	C_{IN}	Other than AV_{CC} , AV_{SS} , V_{CC} , and V_{SS}	$f = 1 \text{ MHz}$	—	10	—	pF		

*1: The measurement conditions of the power supply current are as follows.

The external clock is used.

The output pins are open.

V_{CC} is upon the condition above the table.

*2: For information on t_{inst} , see “(4) Instruction Cycle” in “4. AC Characteristics”.

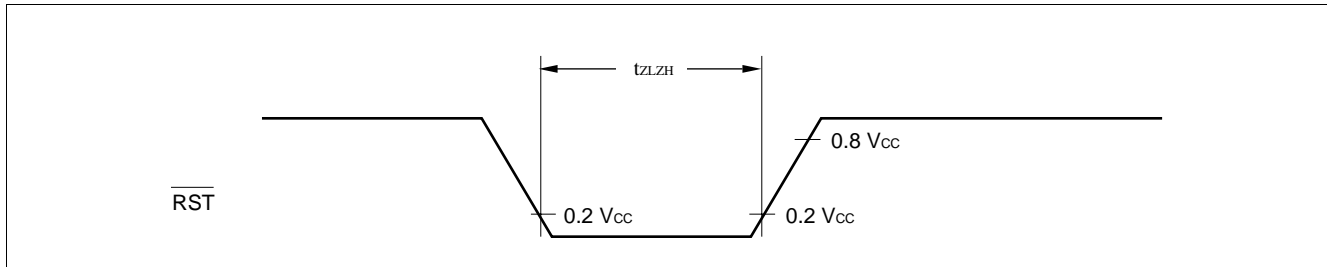
Note: The current consumption of connected EPROM and ICE is not considered on MB89PV670A.

4. AC Characteristics

(1) Reset Timing

($A_{V_{CC}} = V_{CC} = 5.0 \text{ V} \pm 10\%$, $A_{V_{SS}} = V_{SS} = 0.0 \text{ V}$, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$)

Parameter	Symbol	Condition	Rated value		Unit	Remarks
			Min.	Max.		
$\overline{\text{RST}}$ "L" pulse width	t_{ZLZH}	—	48 t_{HCYL}	—	ns	



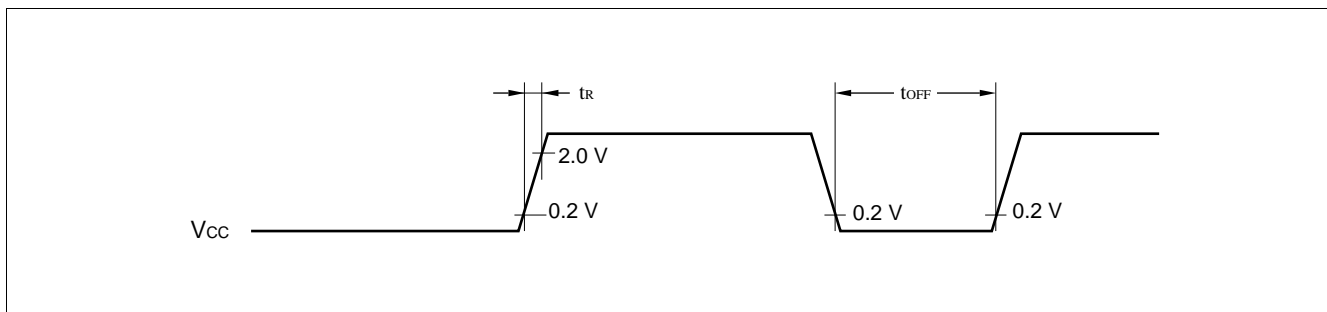
(2) Specifications for Power-on Reset

($A_{V_{SS}} = V_{SS} = 0.0 \text{ V}$, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$)

Parameter	Symbol	Condition	Rated value		Unit	Remarks
			Min.	Max.		
Power supply rising time	t_{r}	—	—	50	ms	Power-on reset function only
Power supply cut-off time	t_{OFF}		1	—	ms	Min. interval time to next power-on reset

Note: Make sure that power supply rises within the selected oscillation stabilization time.

If power supply voltage needs to be varied in the course of operation, a smooth voltage rise is recommended.



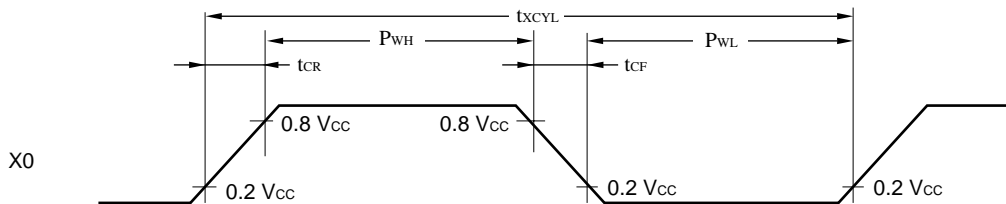
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(3) Clock Timing

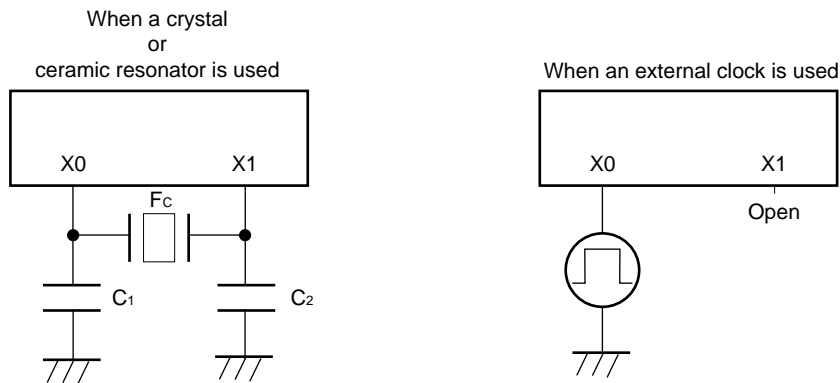
($A_{V_{SS}} = V_{SS} = 0.0 \text{ V}$, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$)

Parameter	Symbol	Pin name	Condition	Rated value		Unit	Remarks
				Min.	Max.		
Clock frequency	F_C	X0, X1	—	1	10	MHz	
Clock cycle time	t_{XCYL}	X0, X1		100	1000	ns	
Input clock pulse width	P_{WH} P_{WL}	X0		20	—	ns	External clock
Input clock rising/falling time	t_{CR} t_{CF}	X0		—	10	ns	External clock

• Clock Timing Conditions



• Clock Configurations



(4) Instruction Cycle

($A_{V_{SS}} = V_{SS} = 0.0 \text{ V}$, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$)

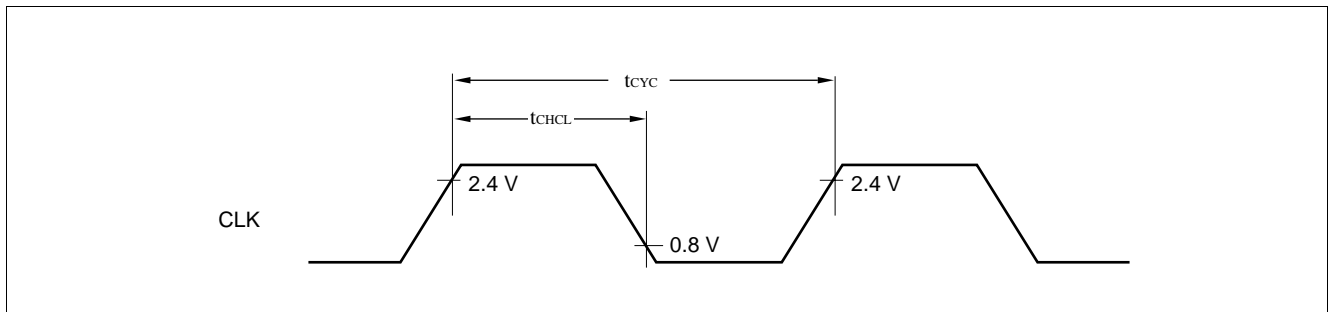
Parameter	Symbol	Rated value (typical)	Unit	Remarks
Instruction cycle (minimum execution time)	t_{inst}	$4/F_C$, $8/F_C$, $16/F_C$, $64/F_C$	μS	$(4/F_C) t_{inst} = 0.4 \mu\text{S}$ when operating at $F_C = 10 \text{ MHz}$

(5) Clock Output Timing

($A_{V_{CC}} = V_{CC} = 5.0 \text{ V} \pm 10\%$, $A_{V_{SS}} = V_{SS} = 0.0 \text{ V}$, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$)

Parameter	Symbol	Pin name	Condition	Rated value		Unit	Remarks
				Min.	Max.		
Cycle time	t_{CYC}	CLK	—	$1/2 t_{inst}^*$	—	μs	
CLK $\uparrow \rightarrow$ CLK \downarrow	t_{CHCL}	CLK		$1/4 t_{inst} - 0.07$	$1/4 t_{inst}$	μs	

* : For information on t_{inst} , see “(4) Instruction Cycle.”



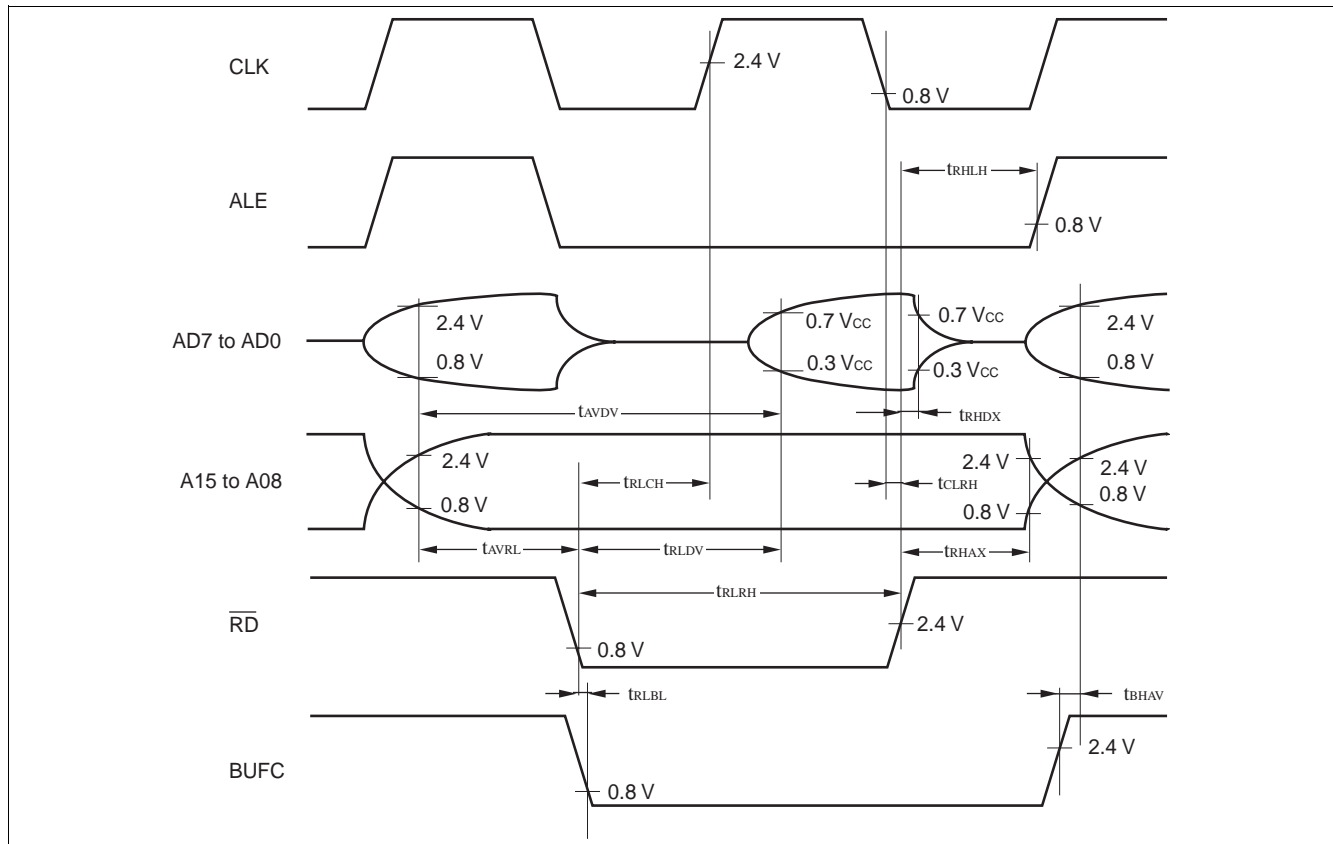
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(6) Bus Read Timing

($V_{CC} = V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = V_{SS} = 0.0 \text{ V}$, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$)

Parameter	Symbol	Pin name	Condition	Rated value		Unit	Remarks
				Min.	Max.		
Valid address $\rightarrow \overline{\text{RD}}$ \downarrow time	t_{AVRL}	$\overline{\text{RD}}$, A15 to A08, AD7 to AD0	—	$1/4 t_{\text{inst}}^* - 0.06$	—	μs	
$\overline{\text{RD}}$ pulse width	t_{RLRH}	$\overline{\text{RD}}$		$1/2 t_{\text{inst}}^* - 0.02$	—	μs	
Valid address \rightarrow Data read time	t_{AVDV}	AD7 to AD0, A15 to A08		—	$1/2 t_{\text{inst}}^*$	μs	No wait
$\overline{\text{RD}}$ $\downarrow \rightarrow$ Data read time	t_{RLDV}	$\overline{\text{RD}}$, AD7 to AD0		—	$1/2 t_{\text{inst}}^* - 0.08$	μs	No wait
$\overline{\text{RD}}$ $\uparrow \rightarrow$ Data hold time	t_{RHDX}	AD7 to AD0, $\overline{\text{RD}}$		0	—	ns	
$\overline{\text{RD}}$ $\uparrow \rightarrow$ ALE \uparrow time	t_{RHLH}	$\overline{\text{RD}}$, ALE		$1/4 t_{\text{inst}}^* - 0.04$	—	μs	
$\overline{\text{RD}}$ $\uparrow \rightarrow$ Address loss time	t_{RHAX}	$\overline{\text{RD}}$, A15 to A08		$1/4 t_{\text{inst}}^* - 0.04$	—	μs	
$\overline{\text{RD}}$ $\downarrow \rightarrow$ CLK \uparrow time	t_{RLCH}	$\overline{\text{RD}}$, CLK		$1/4 t_{\text{inst}}^* - 0.04$	—	μs	
CLK $\downarrow \rightarrow \overline{\text{RD}}$ \uparrow time	$t_{\text{CLR H}}$	$\overline{\text{RD}}$, CLK		0	—	ns	
$\overline{\text{RD}}$ $\downarrow \rightarrow$ BUFC \downarrow time	t_{RLBL}	$\overline{\text{RD}}$, BUFC		-5	—	ns	
BUFC $\uparrow \rightarrow$ Valid address time	t_{BHAV}	A15 to A08, AD7 to AD0, BUFC	5	—	ns		

* : For information on t_{inst} , see “(4) Instruction Cycle.”



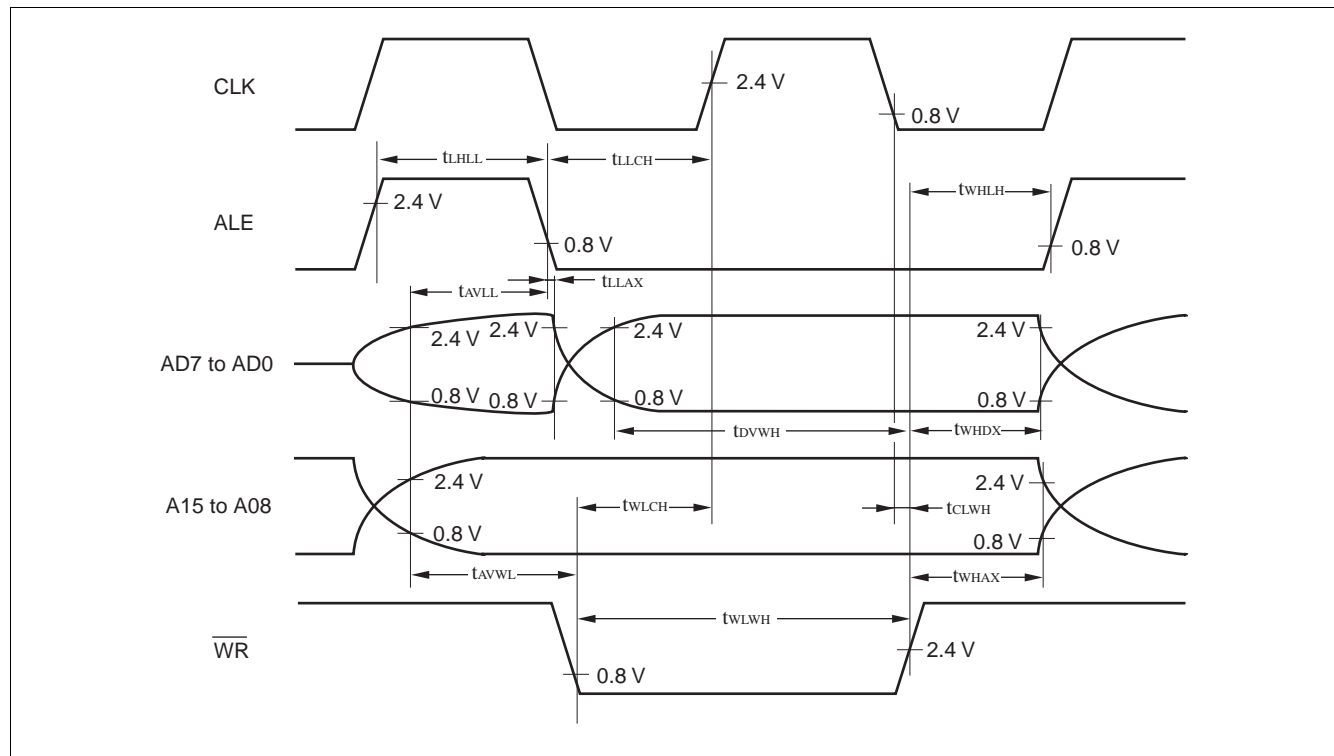
(7) Bus Write Timing

($V_{CC} = V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = V_{SS} = 0.0\text{ V}$, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$)

Parameter	Symbol	Pin name	Condition	Rated value		Unit	Remarks
				Min.	Max.		
Valid address → ALE ↓ time	t_{AVLL}	AD7 to AD0, ALE, A15 to A08	—	$1/4 t_{inst}^2 - 0.064$	—	μs	
ALE ↓ time → Address loss time	t_{LLAX}	AD7 to AD0, ALE, A15 to A08		5^{*1}	—	ns	
Valid address → $\overline{\text{WR}}$ ↓ time	t_{AVWL}	$\overline{\text{WR}}$, ALE		$1/4 t_{inst}^2 - 0.06$	—	μs	
$\overline{\text{WR}}$ pulse width	t_{WLWH}	$\overline{\text{WR}}$		$1/2 t_{inst}^2 - 0.02$	—	μs	
Writing data → $\overline{\text{WR}}$ ↑ time	t_{DVWL}	AD7 to AD0, $\overline{\text{WR}}$		$1/2 t_{inst}^2 - 0.06$	—	μs	
$\overline{\text{WR}}$ ↑ → Address loss time	t_{WHAX}	$\overline{\text{WR}}$, A15 to A08		$1/4 t_{inst}^2 - 0.04$	—	μs	
$\overline{\text{WR}}$ ↑ → Data hold time	t_{WHDX}	AD7 to AD0, $\overline{\text{WR}}$		$1/4 t_{inst}^2 - 0.04$	—	μs	
$\overline{\text{WR}}$ ↑ → ALE ↑ time	t_{WHLH}	$\overline{\text{WR}}$, ALE		$1/4 t_{inst}^* - 0.04$	—	μs	
$\overline{\text{WR}}$ ↓ → CLK ↑ time	t_{WLCH}	$\overline{\text{WR}}$, CLK		$1/4 t_{inst}^2 - 0.04$	—	μs	
CLK ↓ → $\overline{\text{WR}}$ ↑ time	t_{CLWH}	$\overline{\text{WR}}$, CLK		0	—	ns	
ALE pulse width	t_{LHLL}	ALE		$1/4 t_{inst}^2 - 0.035$	—	μs	
ALE ↓ → CLK ↑ time	t_{LLCH}	ALE, CLK		$1/4 t_{inst}^2 - 0.03$	—	μs	

*1: These characteristics are also applicable to the bus read timing.

*2: For information on t_{inst} , see "(4) Instruction Cycle."



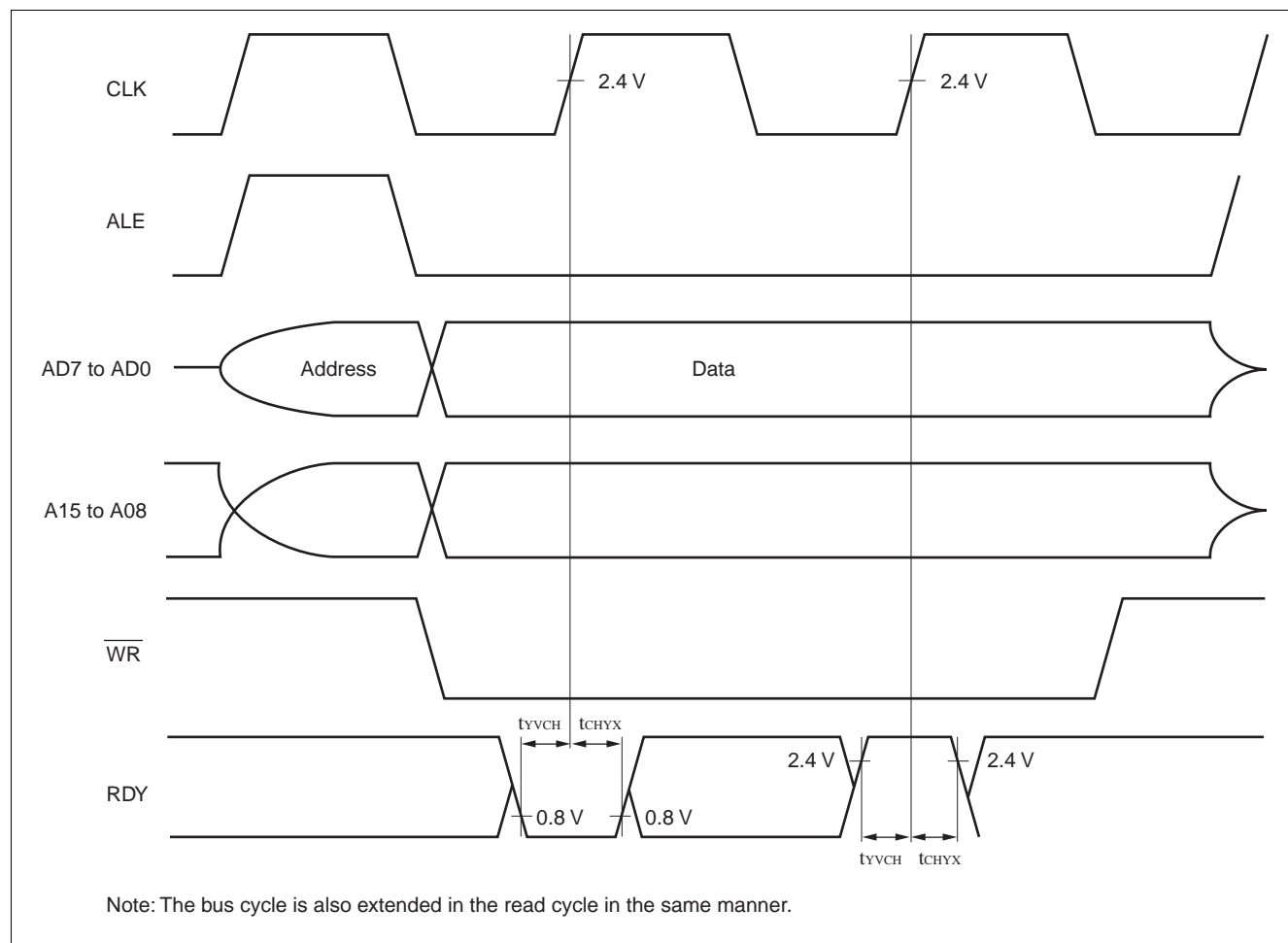
MB89670AR Series

(8) Ready Input Timing

($V_{CC} = V_{CC} = 5.0 \text{ V} \pm 10\%$, $V_{SS} = V_{SS} = 0.0 \text{ V}$, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$)

Parameter	Symbol	Pin name	Condition	Rated value		Unit	Remarks
				Min.	Max.		
RDY valid \rightarrow CLK \uparrow time	t_{VCH}	RDY, CLK	—	60	—	ns	*
CLK \uparrow \rightarrow RDY loss time	t_{CHYX}	RDY, CLK		0	—	ns	*

* : These characteristics are also applicable to the read cycle.

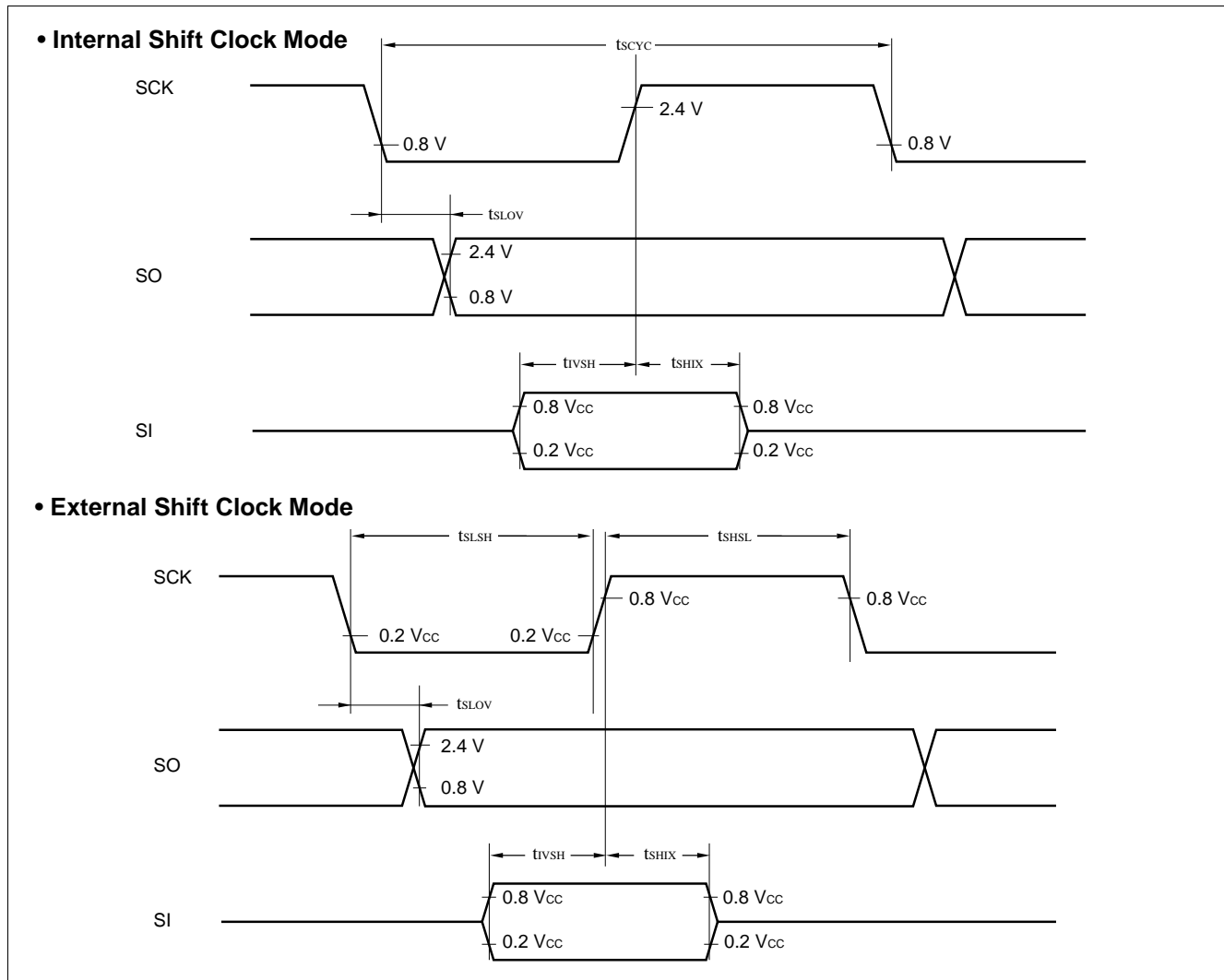


(9) Serial I/O Timing

($V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = V_{SS} = 0.0\text{ V}$, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$)

Parameter	Symbol	Pin name	Condition	Rated value		Unit	Remarks
				Min.	Max.		
Serial clock cycle time	t_{SCYC}	SCK	Internal shift clock mode	$2 t_{inst}^*$	—	μs	
SCK $\downarrow \rightarrow$ SO time	t_{SLOV}	SCK, SO		-200	200	ns	
Valid SI \rightarrow SCK \uparrow	t_{IVSH}	SI, SCK		$1/2 t_{inst}^*$	—	μs	
SCK $\uparrow \rightarrow$ valid SI hold time	t_{SHIX}	SCK, SI		$1/2 t_{inst}^*$	—	μs	
Serial clock "H" pulse width	t_{SHSL}	SCK	External shift clock mode	$1 t_{inst}^*$	—	μs	
Serial clock "L" pulse width	t_{LSLH}	SCK		$1 t_{inst}^*$	—	μs	
SCK $\downarrow \rightarrow$ SO time	t_{SLOV}	SCK, SO		0	200	ns	
Valid SI \rightarrow SCK \uparrow	t_{IVSH}	SI, SCK		$1/2 t_{inst}^*$	—	μs	
SCK $\uparrow \rightarrow$ valid SI hold time	t_{SHIX}	SCK, SI	$1/2 t_{inst}^*$	—	μs		

* : For information on t_{inst} , see "(4) Instruction Cycle".



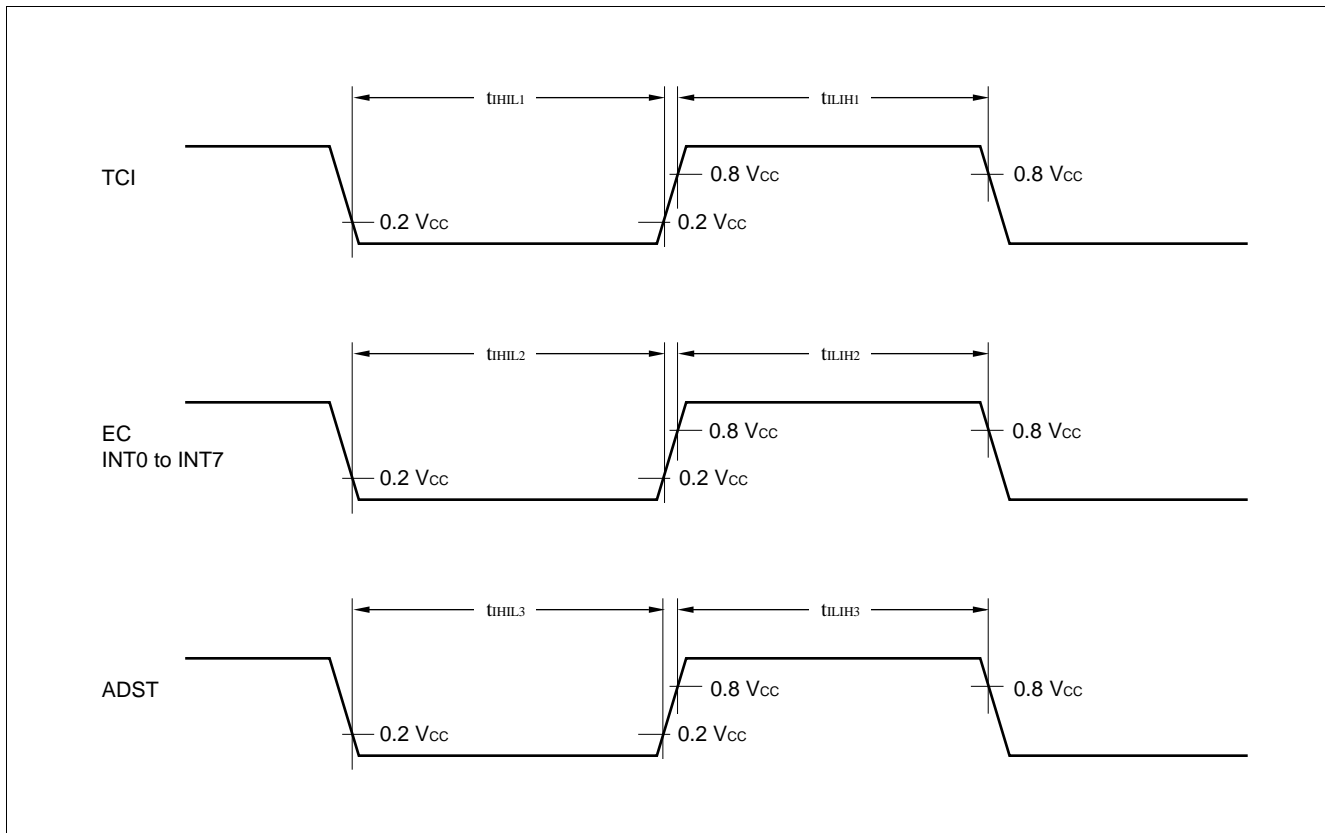
MB89670AR Series

(10) Peripheral Input Timing

($V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = 0.0\text{ V}$, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$)

Parameter	Symbol	Pin name	Condition	Rated value		Unit	Remarks
				Min.	Max.		
Peripheral input "H" pulse width 1	t_{LIH1}	TCI	—	1 t_{inst}^*	—	μS	
Peripheral input "L" pulse width 1	t_{HIL1}	TCI		1 t_{inst}^*	—	μS	
Peripheral input "H" pulse width 2	t_{LIH2}	EC, INT0 to INT7		2 t_{inst}^*	—	μS	
Peripheral input "L" pulse width 2	t_{HIL2}	EC, INT0 to INT7		2 t_{inst}^*	—	μS	
Peripheral input "H" pulse width 3	t_{LIH3}	ADST	A/D mode	64 t_{inst}^*	—	μS	
Peripheral input "L" pulse width 3	t_{HIL3}	ADST		64 t_{inst}^*	—	μS	
Peripheral input "H" pulse width 3	t_{LIH3}	ADST	Sense mode	64 t_{inst}^*	—	μS	
Peripheral input "L" pulse width 3	t_{HIL3}	ADST		64 t_{inst}^*	—	μS	

* : For information on t_{inst} , see "(4) Instruction Cycle".



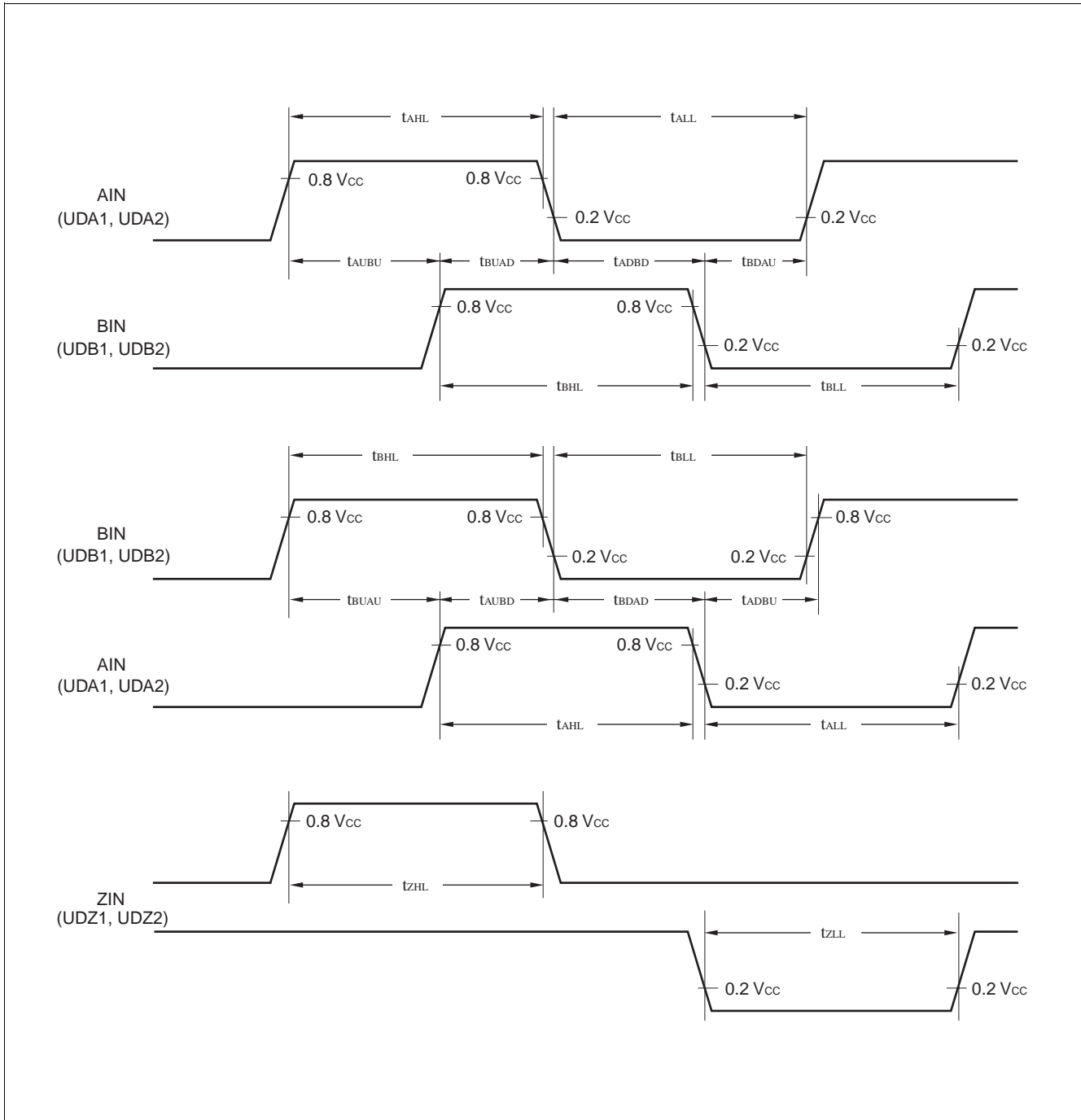
(11) Up/down Counter Input Timing

($V_{CC} = V_{CC} = 5.0\text{ V} \pm 10\%$, $V_{SS} = V_{SS} = 0.0\text{ V}$, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$)

Parameter	Symbol	Pin name	Condition	Rated value		Unit	Remarks
				Min.	Max.		
AIN input "1" pulse width	t _{AHL}	AIN = UDA1, UDA2 BIN = UDB1, UDB2	—	2 t _{inst} *	—	μs	
AIN input "0" pulse width	t _{ALL}			2 t _{inst} *	—	μs	
BIN input "1" pulse width	t _{BHL}			2 t _{inst} *	—	μs	
BIN input "0" pulse width	t _{BLL}			2 t _{inst} *	—	μs	
AIN ↑ → BIN ↑ time	t _{AUBU}			1 t _{inst} *	—	μs	
BIN ↑ → AIN ↓ time	t _{BUAD}			1 t _{inst} *	—	μs	
AIN ↓ → BIN ↓ time	t _{ADBD}			1 t _{inst} *	—	μs	
BIN ↓ → AIN ↑ time	t _{BDAU}			1 t _{inst} *	—	μs	
BIN ↑ → AIN ↑ time	t _{BUAU}			1 t _{inst} *	—	μs	
AIN ↑ → BIN ↓ time	t _{AUBD}			1 t _{inst} *	—	μs	
BIN ↓ → AIN ↓ time	t _{BDAD}			1 t _{inst} *	—	μs	
AIN ↓ → BIN ↑ time	t _{ADBU}			1 t _{inst} *	—	μs	
ZIN input "1" pulse width	t _{ZHL}	ZIN = UDZ1, UDZ2	—	1 t _{inst} *	—	μs	
ZIN input "0" pulse width	t _{ZLL}			1 t _{inst} *	—	μs	

* : For information on t_{inst}, see "(4) Instruction Cycle".

MB89670AR Series



5. A/D Converter Electrical Characteristics

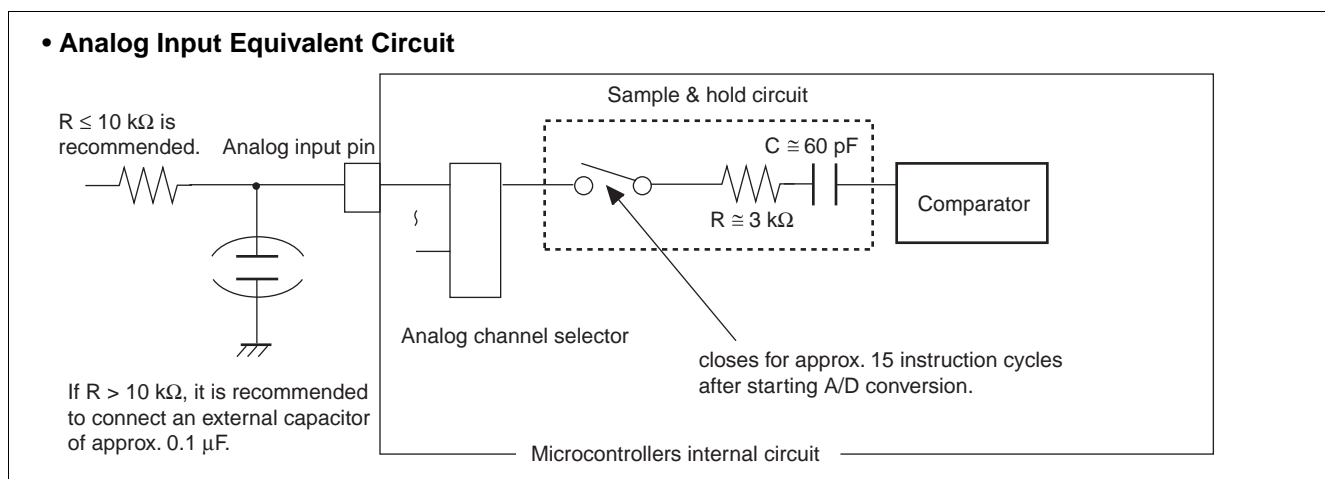
($AV_{CC} = V_{CC} = 3.5\text{ V to }6.0\text{ V}$, $F_C = 10\text{ MHz}$, $AV_{SS} = V_{SS} = 0.0\text{ V}$, $T_A = -40^\circ\text{C to }+85^\circ\text{C}$)

Parameter	Symbol	Pin name	Rated value			Unit	Remarks
			Min.	Typ.	Max.		
Resolution	—	—	—	—	10	bit	$AV_{CC} = AVR = V_{CC}$
Linearity error			—	—	± 2.0	LSB	
Differential linearity error			—	—	± 1.5	LSB	
Total error			—	—	± 3.0	LSB	
Zero transition voltage	V_{OT}	AN0 to AN7	$AV_{SS} - 1.5\text{ LSB}$	$AV_{SS} + 0.5\text{ LSB}$	$AV_{SS} + 2.5\text{ LSB}$	V	
Full-scale transition voltage	V_{FST}	AN0 to AN7	$AVR - 3.5\text{ LSB}$	$AVR - 1.5\text{ LSB}$	$AVR + 0.5\text{ LSB}$	V	
Interchannel disparity	—	—	—	—	4	LSB	
A/D mode conversion time			—	—	13.2	μs	At 10 MHz oscillation
Sense mode conversion time			—	—	7.2	μs	At 10 MHz oscillation
Analog port input current	I_{AIN}	AN0 to AN7	—	—	10	μA	
Analog input voltage	—	AN0 to AN7	0	—	AVR	V	
Reference voltage		AVR	0	—	AV_{CC}	V	
Reference voltage supply current	I_R	AVR	—	200	—	μA	AVR = 5.0 V

6. Notes on Using A/D Converter

- The smaller $|AVR - AV_{SS}|$, the greater the error would become relatively.
- The output impedance of the external circuit for the analog input must satisfy the following conditions:
Output impedance of the external circuit < Approx. 10 k Ω If the output impedance of the external circuit is too high, an analog voltage sampling time might be insufficient (sampling time = 6 μs at 10 MHz oscillation).

An analog input equivalent circuit is shown below.



MB89670AR Series

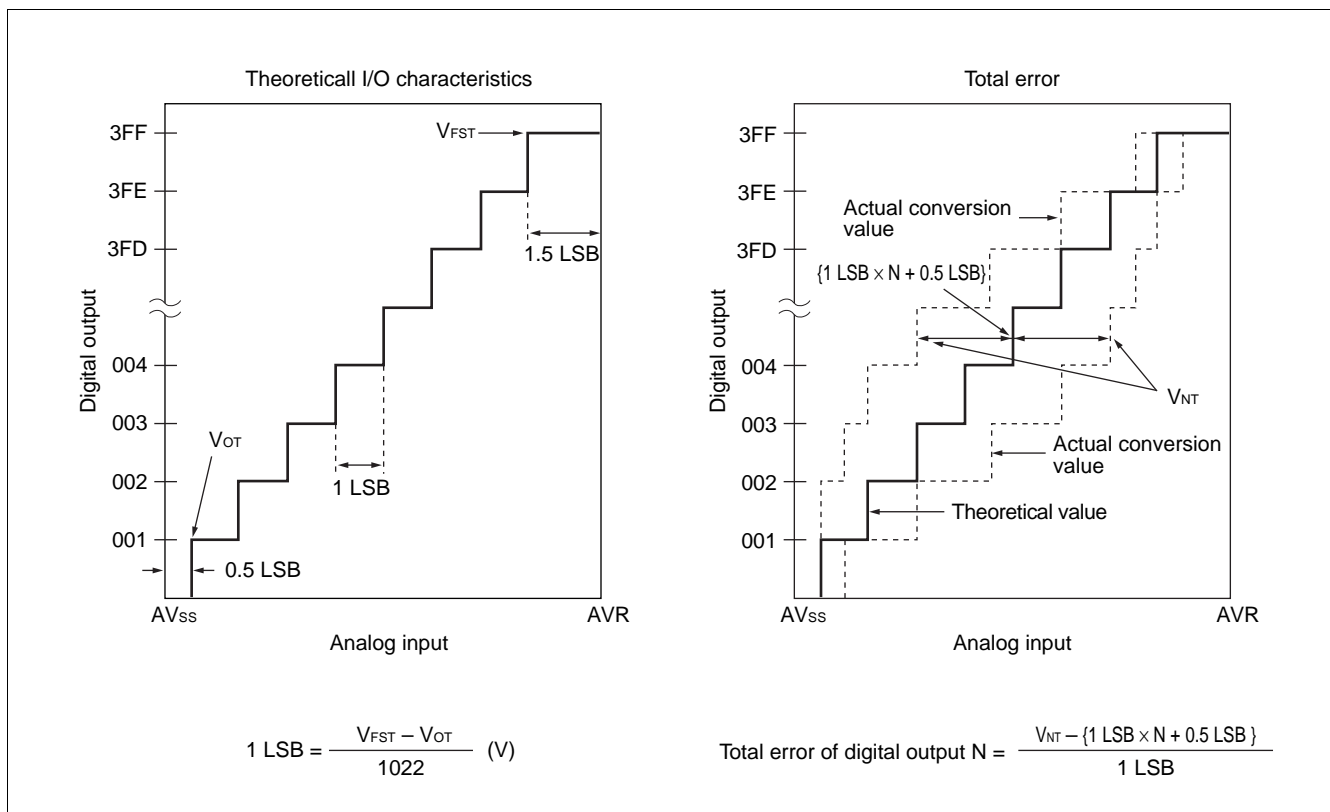
Since the A/D converter contains a sample & hold circuit, the level of the analog input pin might not stabilize within the sampling period after starting A/D, resulting in inaccurate A/D conversion values, if the input impedance to the analog pin is too high. Be sure to maintain an appropriate input impedance to the analog pin.

It is recommended to keep the input impedance to the analog pin from exceeding 10 kΩ. If it exceeds 10 kΩ, it is recommended to connect a capacitor of approx. 0.1 μF to the analog input pin.

Except for the sampling period after starting A/D, the input leakage current of the analog input pin is less than 10 μA.

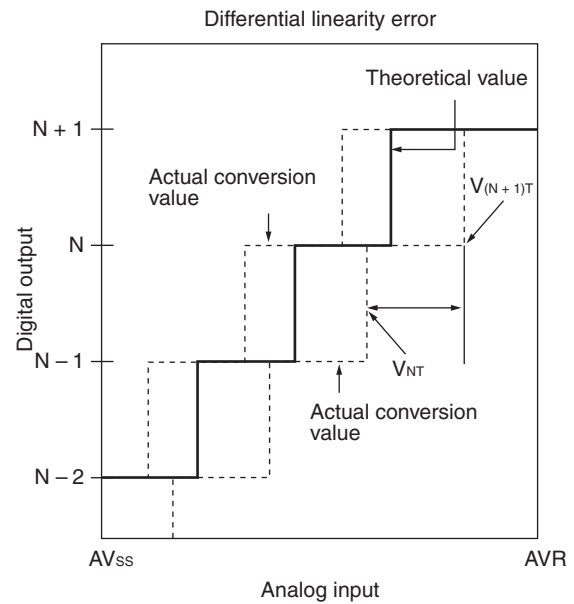
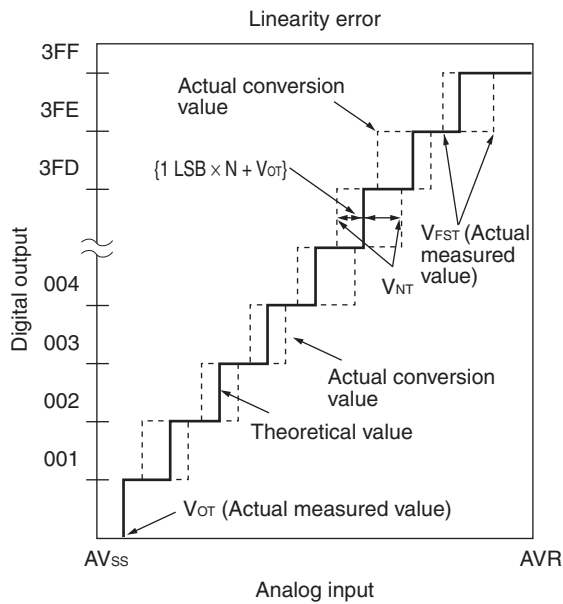
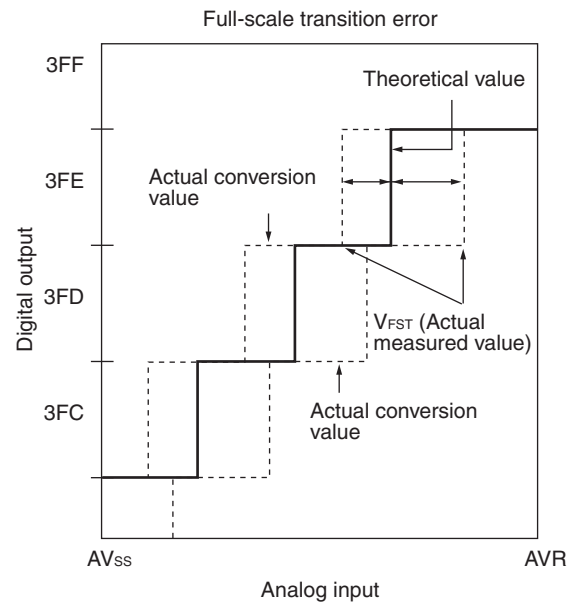
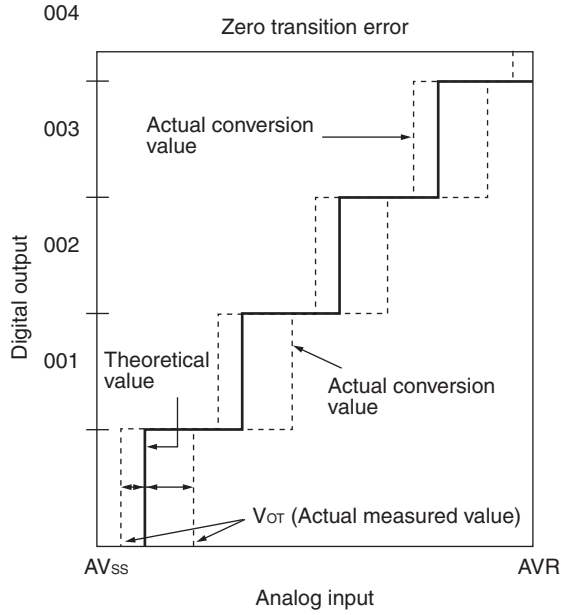
7. A/D Converter Glossary

- Resolution
Analog-change that are identifiable with the A/D converter.
- Linearity error
The deviation of the straight line connecting the zero transition point (“00 0000 0000” ↔ “00 0000 0001”) with the full-scale transition point (“11 1111 1111” ↔ “11 1111 1110”) from actual conversion characteristics
- Differential linearity error
The deviation of the input voltage needed to change the output code by 1 LSB from the theoretical voltage
- Total error
The difference between theoretical and actual conversion values, caused by the zero transition error, full-scale transition error, linearity error, quantization error, and noise.



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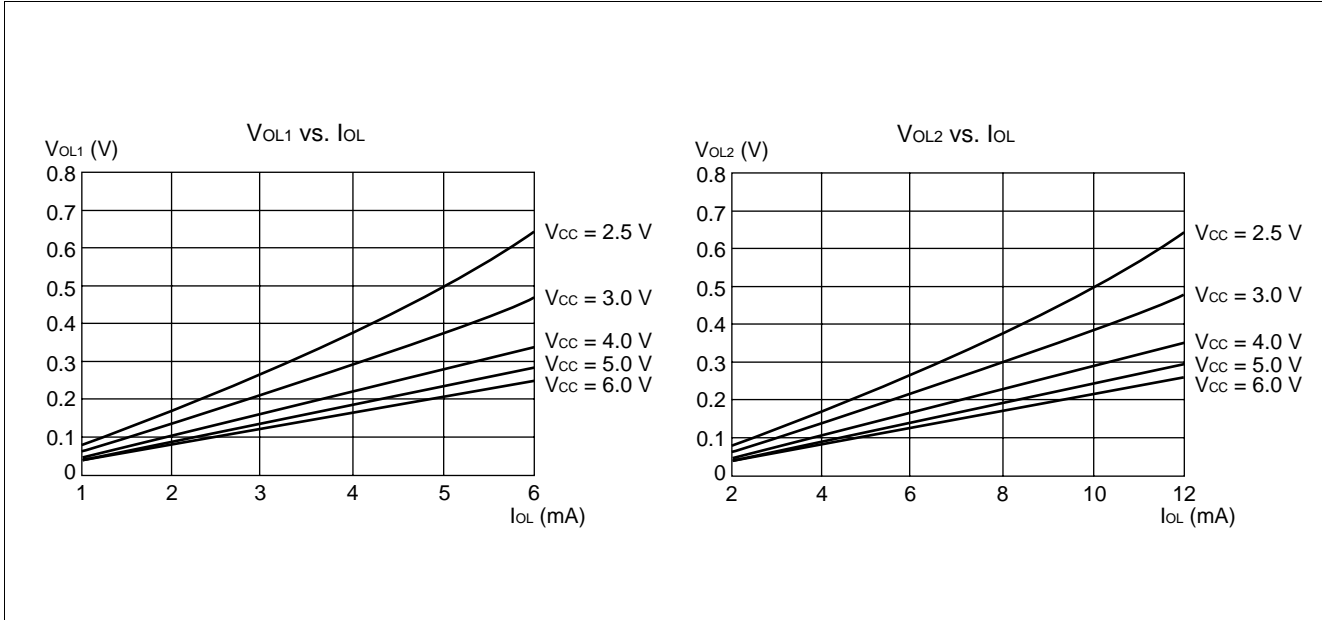
$$\text{Linearity error of digital output } N = \frac{V_{NT} - \{1 \text{ LSB} \times N + V_{OT}\}}{1 \text{ LSB}}$$

$$\text{Differential linearity error of digital output } N = \frac{V_{(N+1)T} - V_{NT}}{1 \text{ LSB}} - 1$$

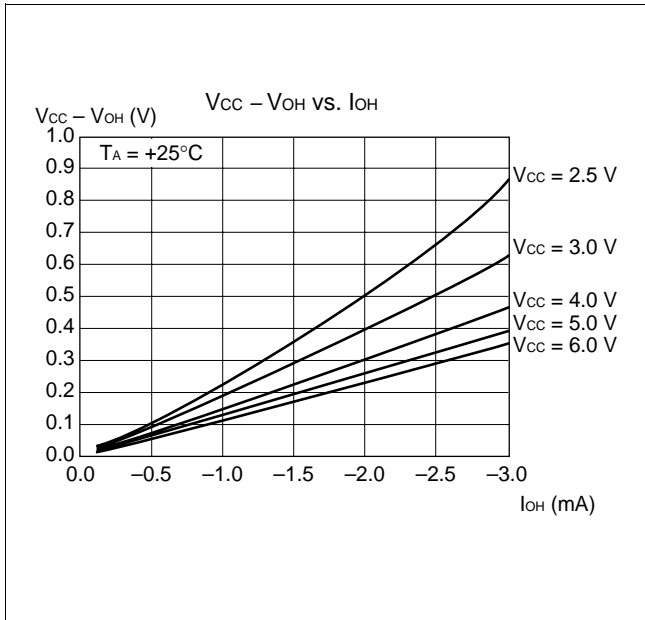
MB89670AR Series

EXAMPLE CHARACTERISTICS

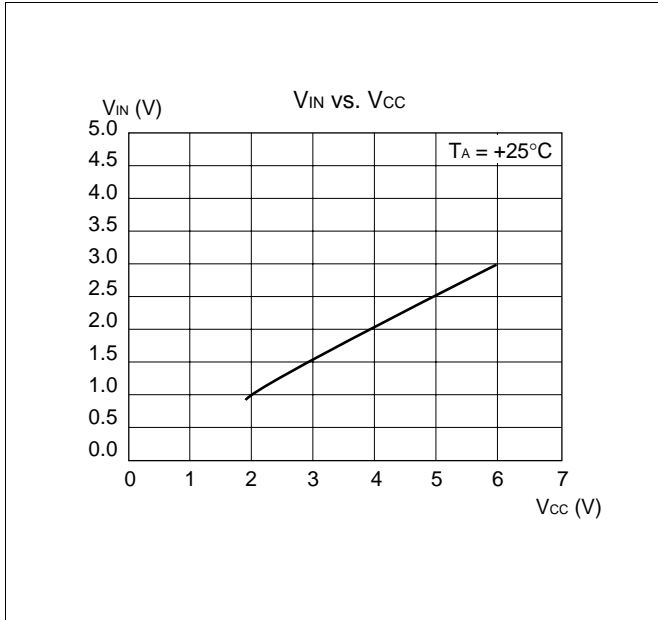
(1) "L" Level Output Voltage



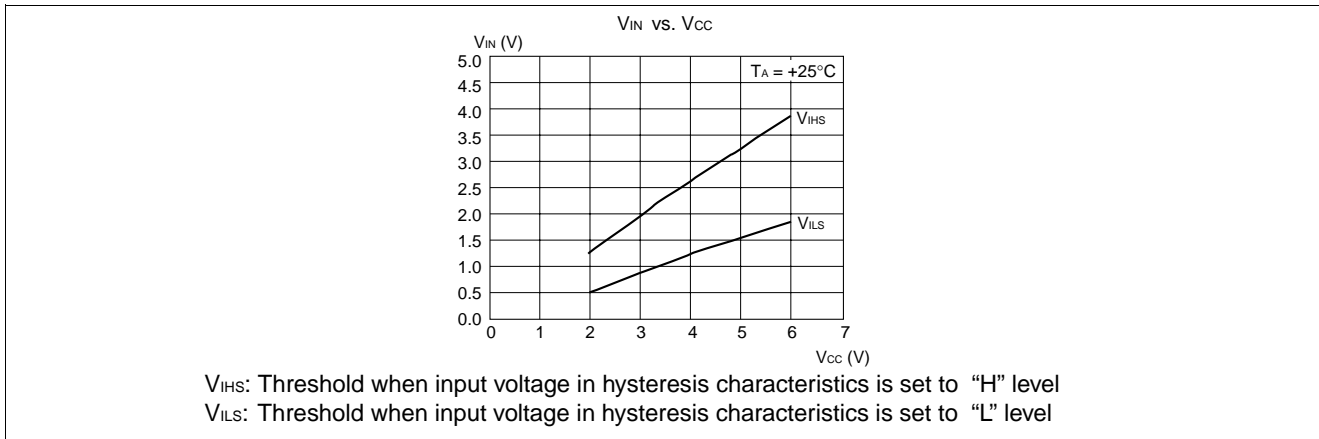
(2) "H" Level Output Voltage



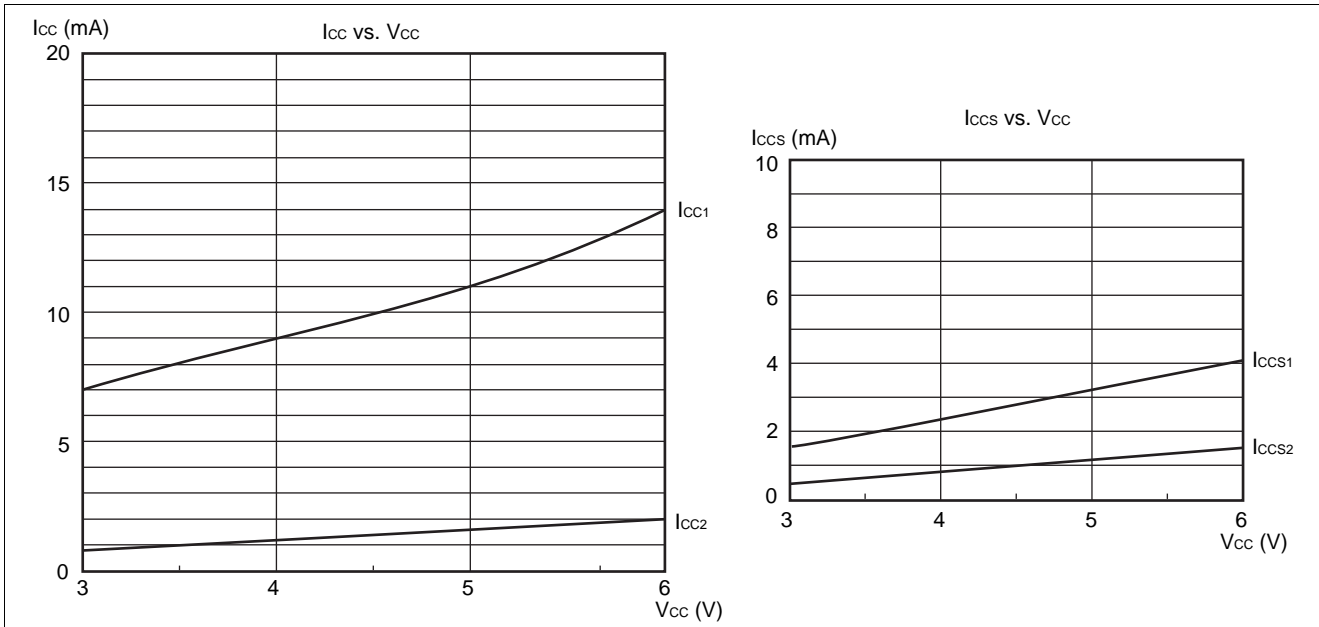
(3) "H" Level Input Voltage/"L" Level Input Voltage (CMOS Input)



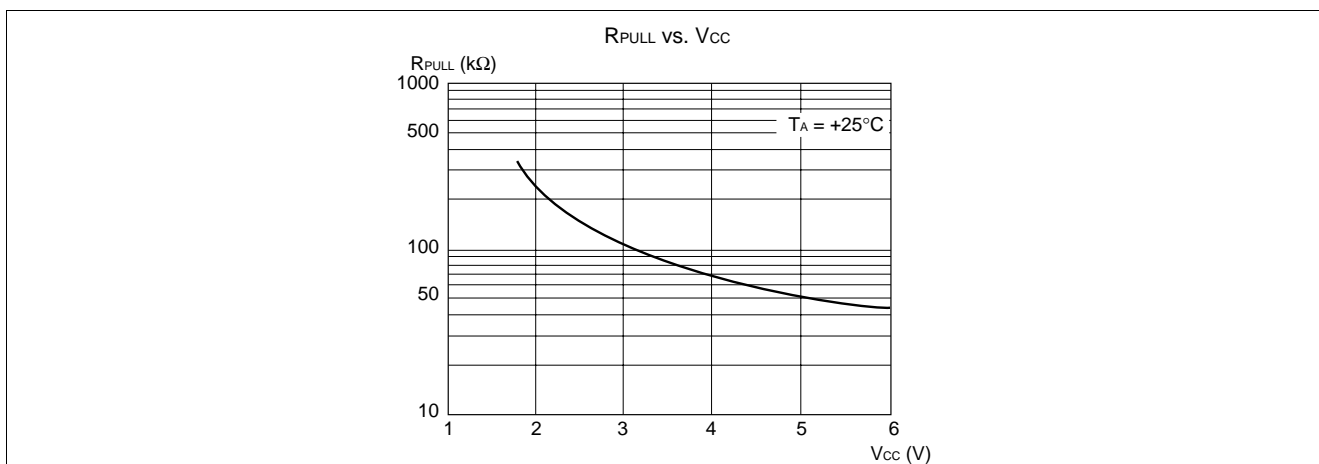
(4) "H" Level Input Voltage/"L" Level Input Voltage (Hysteresis Input)



(5) Power Supply Current (External Clock)



(6) Pull-up Resistance



MB89670AR Series

■ MASK OPTIONS

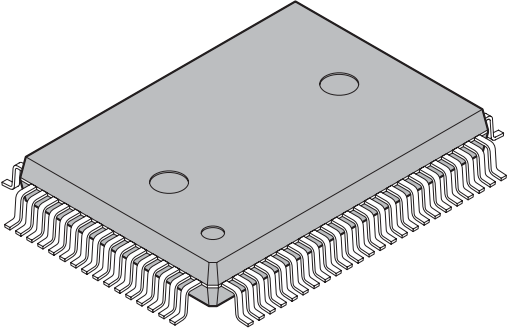
No.	Part number	MB89673AR MB89675AR MB89677AR	MB89P677A	MB89PV670A
	Specifying procedure	Specify when ordering masking	Set with EPROM programmer	Setting not possible
1	Pull-up resistors P10 to P17, P30 to P37, P40 to P47, P70 to P76	Selectable by pin	Selectable by pin	Fixed to "without pull-up resistor"
2		Selectable by pin	Selectable in 4-pin unit	
3		Selectable by pin	Selectable in 4-pin unit	
4	Power-on reset With power-on reset Without power-on reset	Selectable	Selectable	Fixed to "with power-on reset"
5	Oscillation stabilization time selection (at 10 MHz) Approx. $2^{18}/F_c$ (approx. 26.2 ms) Approx. $2^{17}/F_c$ (approx. 13.1 ms) Approx. $2^{14}/F_c$ (approx. 1.6 ms) Approx. $2^4/F_c$ (approx. 0 ms) F _c : Clock frequency	Selectable	Selectable	Fixed to Approx. $2^{18}/F_c$ (Approx. 26.2 ms)
6	Reset pin output With reset output Without reset output	Selectable	Selectable	Fixed to "with reset output"

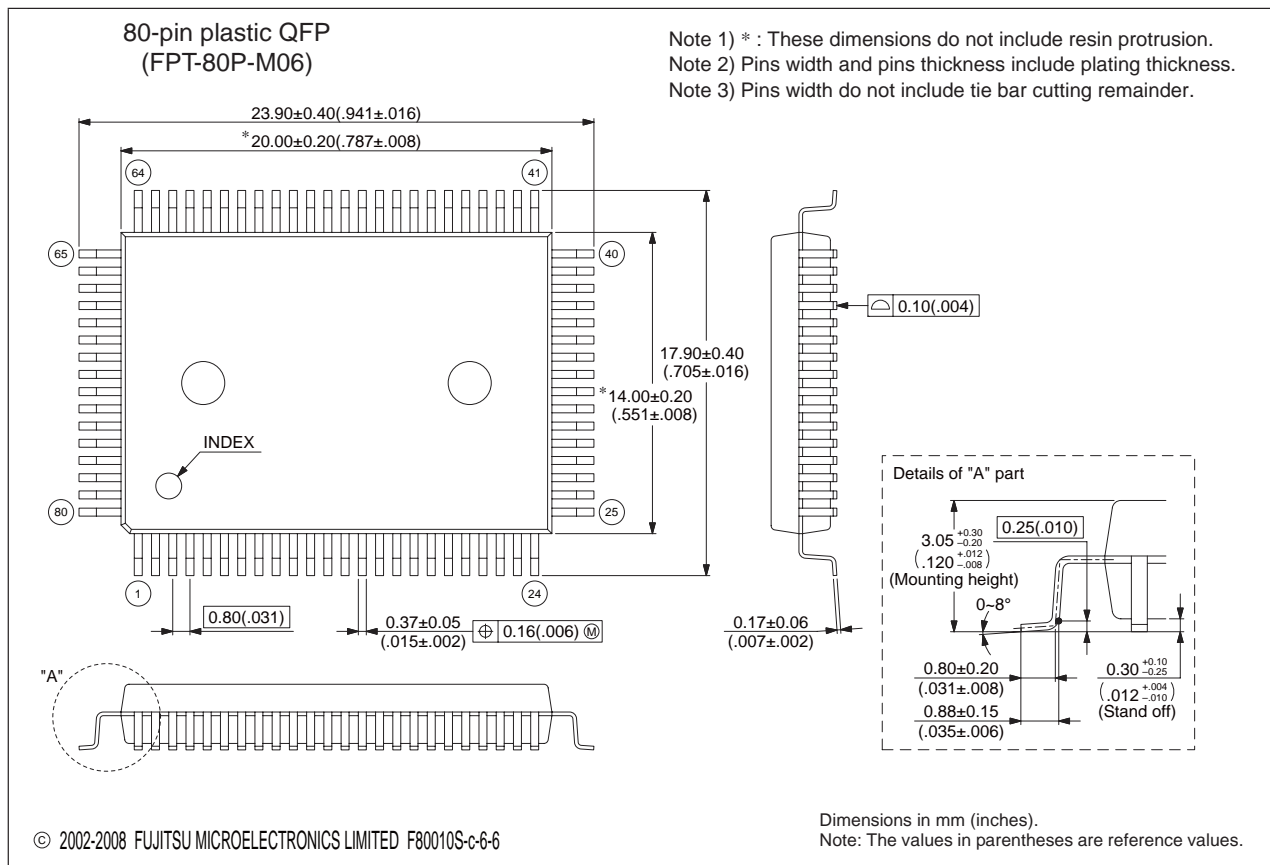
■ ORDERING INFORMATION

Part number	Package	Remarks
MB89673ARPF MB89675ARPF MB89677ARPF MB89P677APF	80-pin Plastic QFP (FPT-80P-M06)	
MB89673ARPMC1 MB89675ARPMC1 MB89677ARPMC1 MB89P677APMC1	80-pin Plastic LQFP (FPT-80P-M22)	
MB89PV670ACF	80-pin Ceramic MQFP (MQP-80C-P01)	

MB89670AR Series

PACKAGE DIMENSIONS

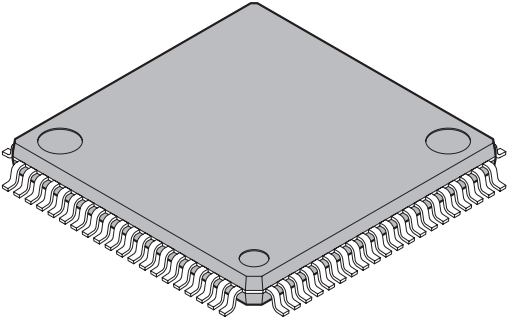
 <p>80-pin plastic QFP</p> <p>(FPT-80P-M06)</p>	Lead pitch	0.80 mm
	Package width × package length	14.00 × 20.00 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	3.35 mm MAX
	Code (Reference)	P-QFP80-14×20-0.80

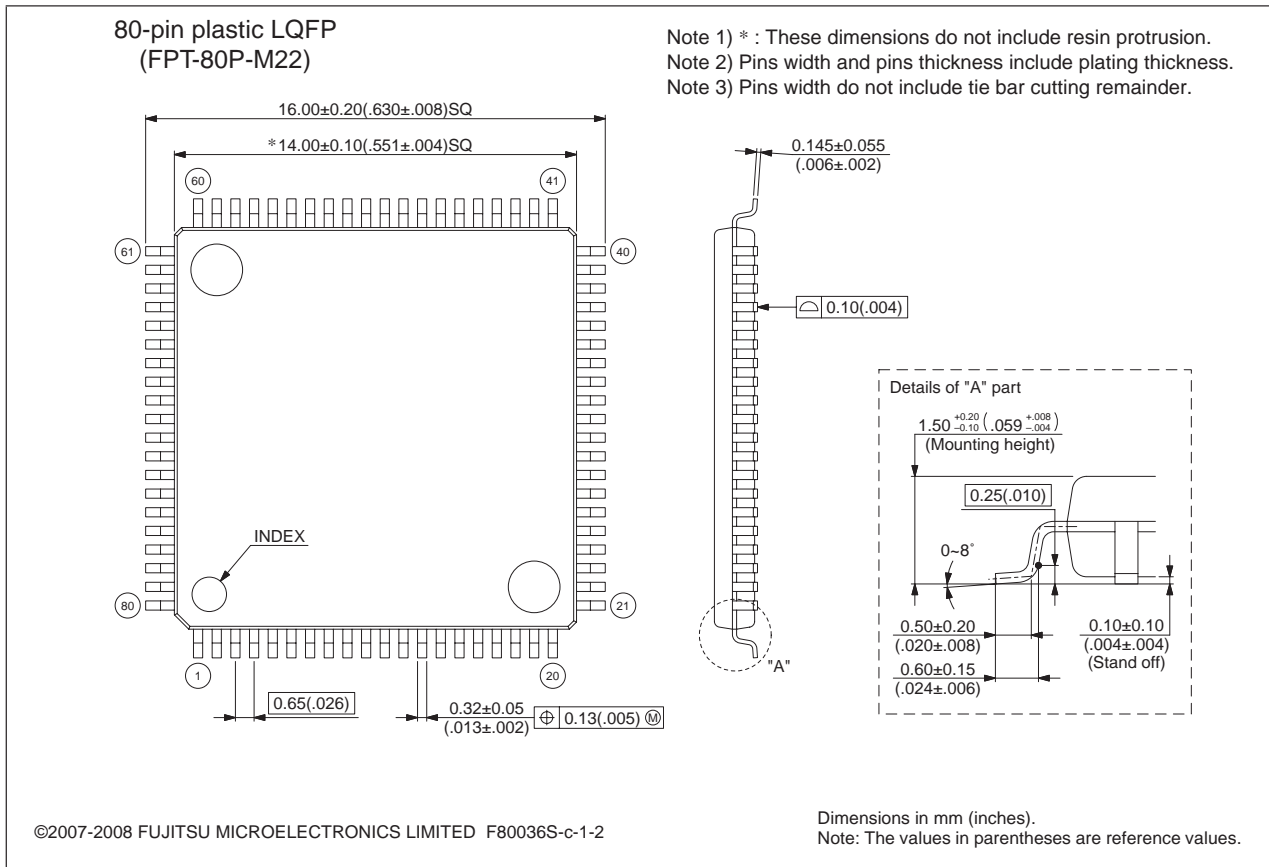


Please confirm the latest Package dimension by following URL.
<http://edevice.fujitsu.com/package/en-search/>

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MB89670AR Series

<p style="text-align: center;">80-pin plastic LQFP</p>  <p style="text-align: center;">(FPT-80P-M22)</p>	Lead pitch	0.65 mm
	Package width × package length	14.00 mm × 14.00 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm Max
	Weight	0.62 g
	Code (Reference)	P-LFQFP80-14×14-0.65

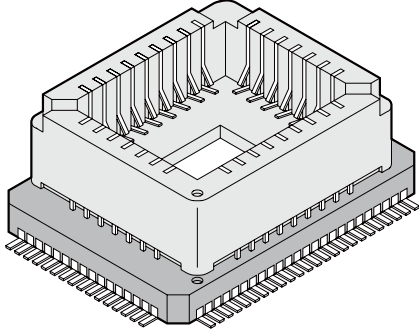


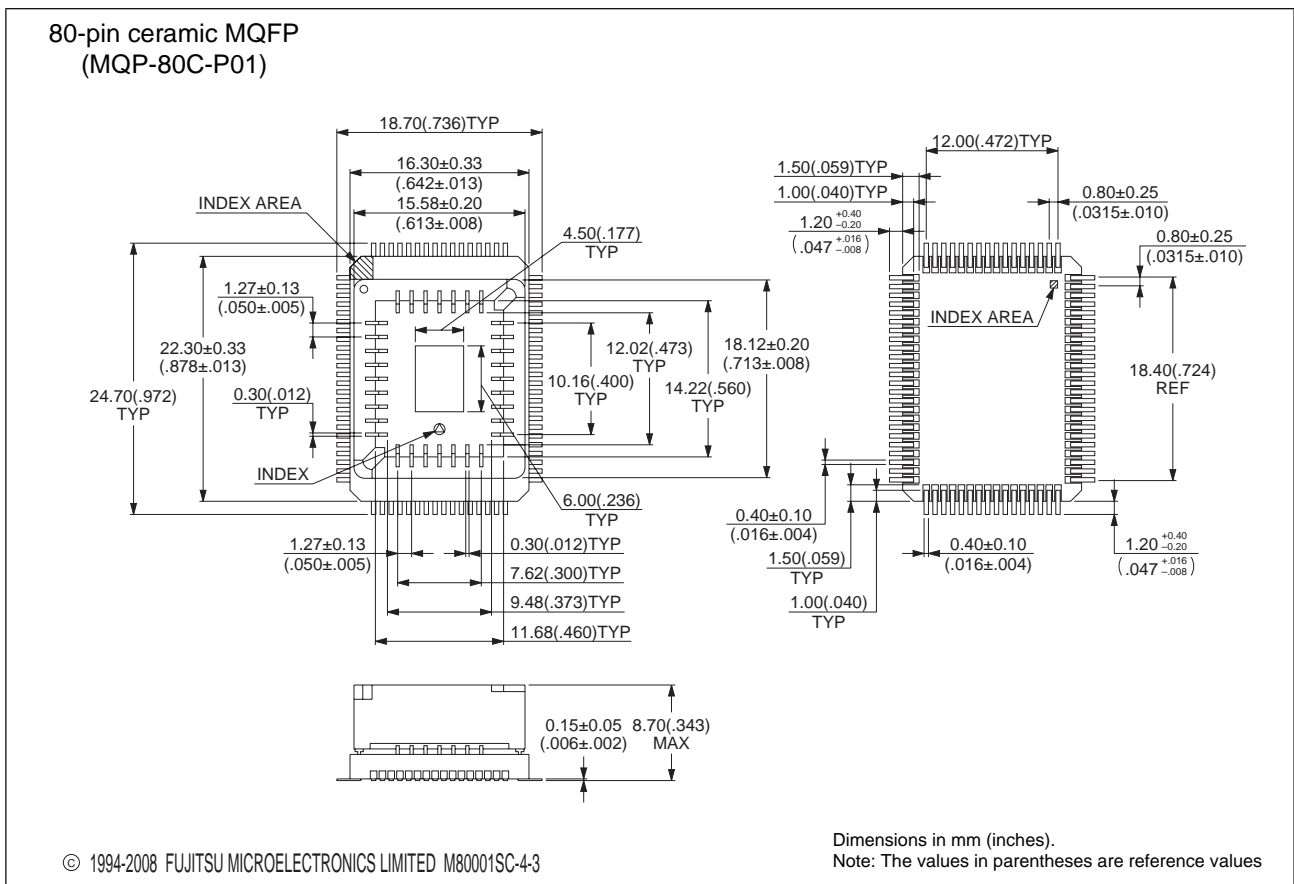
Please confirm the latest Package dimension by following URL.
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MB89670AR Series

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<p style="text-align: center;">80-pin ceramic MQFP</p>  <p style="text-align: center;">(MQP-80C-P01)</p>	Lead pitch	0.8 mm	
	Lead shape	Straight	
	Motherboard material	Ceramic	
	Mounted package material	Plastic	



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MB89670AR Series

■ MAIN CHANGES IN THIS EDITION

Page	Section	Change Results
—	—	Changed the series name; MB89670R/670AR Series → MB89670AR series
—	—	Deleted the part numbers. MB89673R, MB89675R
—	—	Changed the package code. FPT-80P-M11 → FPT-80P-M22
6	■ CORRESPONDENCE BETWEEN THE MB89670/670A SERIES AND MB89670R/670AR SERIES	Deleted the “■ CORRESPONDENCE BETWEEN THE MB89670/670A SERIES AND MB89670R/670AR SERIES”.
17	■ PROGRAMMING TO THE EPROM ON THE MB89P677A	Deleted the “6. EPROM Programmer Socket Adapter”.
19	■ PROGRAMMING TO THE EPROM WITH PIGGYBACK/EVALUATION DEVICE	Deleted the “2. Programming Socket Adapter”.
20	■ BLOCK DIAGRAM	Deleted the “1. Block Diagram of MB89673R/89675R”.
43	■ ELECTRICAL CHARACTERISTICS 5. A/D Converter Electrical Characteristics	Changed the items of “Zero transition voltage” and “Full-scale transition voltage”. mV → V
47	■ INSTRUCTIONS (136 instructions)	Deleted the “■ INSTRUCTIONS (136 instructions)”.
	■ INSTRUCTION MAP	Deleted the “■ INSTRUCTION MAP”.
48	■ ORDERING INFORMATION	Changed the order informations. MB89673ARPFM → MB89673ARPMC1 MB89675ARPFM → MB89675ARPMC1 MB89677ARPFM → MB89677ARPMC1 MB89P677APFM → MB89P677APMC1
50	■ PACKAGE DIMENSIONS	Changed the package figure. FPT-80P-M11 → FPT-80P-M22

The vertical lines marked in the left side of the page show the changes.

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MB89670AR Series

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