MAGNETIC FIELD SENSOR

DESCRIPTION

The ZMY20 is an extremely sensitive magnetic sensor employing the magneto-resistive effect of thin film permalloy. It allows the measurement of magnetic fields or the detection of magnetic parts. The highly sensitive and small size magnetoresistive sensors consist of a chip covered with thin film permalloy stripes. These stripes form a Wheatstone bridge, whose output voltage is proportional to the magnetic field component Hy. A perpendicular field Hx is necessary to stabilize sensor operation. This can be done by using a small permanent magnet.

FEATURES

- · Output voltage proportional to magnetic field Hy
- Adjustment of sensitivity and suppression of hysteresis by the auxiliary magnetic field Hx
- Magnetic fields vertical to the chip level are not effective

APPLICATIONS

- Linear position sensors for process control, door interlocks, proximity detectors, machine tool sensing
- Scalar measurement for compassing
- Automotive door switches, engine position & speed sensing
- · Metering of fluids by sensing rotation of impeller
- · Traffic counting & vehicle-type sensing

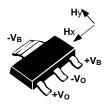
ORDERING INFORMATION

DEVICE	REEL SIZE	TAPE WIDTH	QUANTITY PER REEL
ZMY20TA	7″	12mm	1000 units
ZMY20TC	13"	12mm	4000 units

Measurement of current in a conductor without connection

DEVICE MARKING

ZMY20



SOT223S

PINOUT



 $V_B = SUPPLY VOLTAGE$ $V_O = OUTPUT VOLTAGE$

Top View



ABSOLUTE MAXIMUM RATINGS.

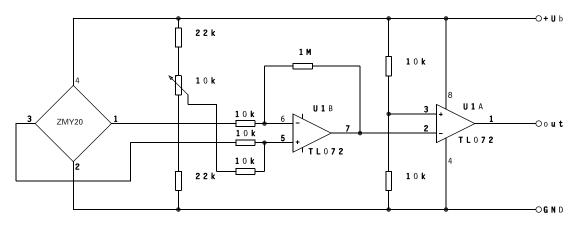
PARAMETER	SYMBOL	LIMIT	UNIT
Supply Voltage	V _B	12	V
Total power dissipation	P _{TOT}	120	mW
Operating Temperature Range	T _{amb}	-40 to +150	°C
Storage Temperature Range	T _{stg}	-65 to +150	°C

ELECTRICAL CHARACTERISTICS.(at T_{amb} =25°C and H_X =3 kA/m unless otherwise stated)

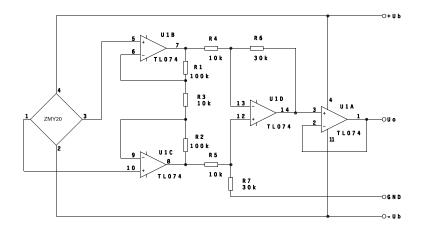
PARAMETER	SYMBOL	MIN	ТҮР	MAX	UNIT	TEST CONDITIONS
Bridge resistance	R _{br}	1.2	1.7	2.2	kΩ	
Output voltage range	V _O /V _B	16	20	24	mV/V	
Open circuit sensitivity	S	3.7	4.7	5.7	(mV/V)/ (kA/m)	No disturbing field H _d allowed
Hysteresis of output voltage	V _{OH} /V _B	-	-	50	μV/V	Hy≤ 2kA/m
Offset Voltage	V _{off} /V _B	-1.0	-	+1.0	mV/V	
Operating Frequency	f _{max}	0	-	1	MHz	
Temp. Coeff. of offset voltage	TCV _{off}	-3	-	+3	(μV/V)/K	T _{amb} = -25 to +125°C
Temp. Coeff. Of bridge resistance	TCR _{br}	0.25	0.3	0.35	%/K	T _{amb} = -25 to +125°C
Temp. Coeff. of open circuit sensitivity V _B =5V	TCS _V	-0.25	-0.3	-0.35	%/K	T _{amb} = -25 to +125°C
Temp. Coeff. of open circuit sensitivity I _B =3mA	TCS _I	-	-0.1	-	%/K	T _{amb} = -25 to +125°C



Application 1 (digital output)

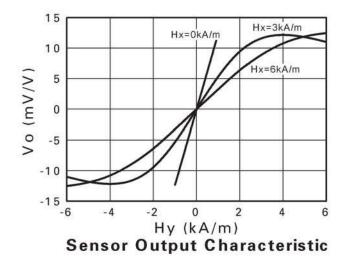


Application 2 (analog output)

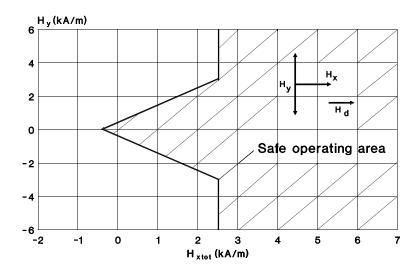




Sensor output characteristic $V_{O}=f(H_{y})$; H_{x} -parameter V_{b} =const; T_{amb} =25°C



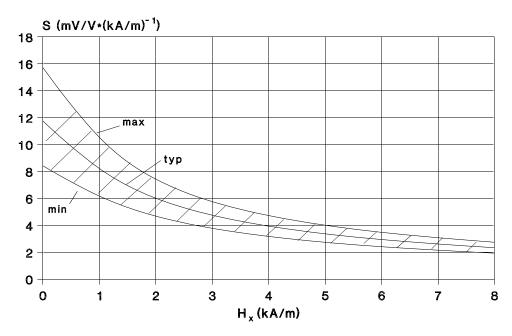
Safe operating area $H_{xtot}=H_x+H_d$; $T_{amb}=25^{\circ}C$; ($H_d=disturbing\ field$)



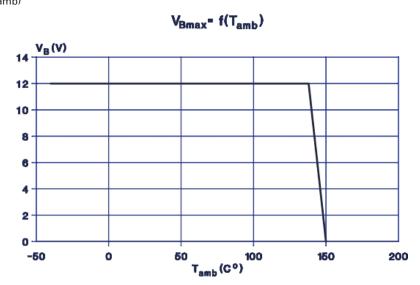
The sensor has to be reset after leaving the safe operating area by an auxiliary field of H_X=3kA/m



Sensor sensitivity characteristic $S=f(H_X)$ $V_b=const; T_{amb}=25^{\circ}C$



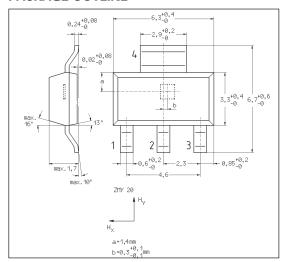
Supply voltage (maximum) derating curve $VBmax = f(T_{amb})$



Device mounted on 40 x 40 mm² board (copper area 600mm²)



PACKAGE OUTLINE



CONTROLLING DIMENSIONS IN MILLIMETRES APPROX CONVERSIONS INCHES.



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Europe

Zetex GmbH Kustermann-Park Balanstraße 59 D-81541 München Germany Telefon: (49) 89 45 49 49 0 Fax: (49) 89 45 49 49 49 europe.sales@zetex.com

Americas

Zetex Inc 700 Veterans Memorial Hwy Hauppauge, NY 11788 USA

Telephone: (1) 631 360 2222 Fax: (1) 631 360 8222 usa.sales@zetex.com

Asia Pacific

Zetex (Asia) Ltd 3701-04 Metroplaza Tower 1 Hing Fong Road, Kwai Fong Hong Kong

Telephone: (852) 26100 611 Fax: (852) 24250 494 asia.sales@zetex.com

Corporate Headquarters

Zetex Semiconductors plc Zetex Technology Park Chadderton, Oldham, OL9 9LL United Kingdom

Telephone (44) 161 622 4444 Fax: (44) 161 622 4446 hq@zetex.com



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