

# AUTOMOTIVE CURRENT TRANSDUCER HABT 100-V/SP1









#### Introduction

The HABT 100-V/SP1 current transducer is attached on the battery cable (or bus-bar) of a vehicle. It provides to a controller (ECU) the actual value of current flowing in the cable and the ambient temperature. The current value is provided by a voltage signal. Temperature is given by an NTC thermistor. The transducer is linked to the BCM (Body Control Module) with the car harness. The electrical connection is made with a waterproof connector. The output voltage  $\mathbf{V}_{\text{OUT}}$  is fully ratiometric with the supply voltage  $\mathbf{V}_{\text{d}}$ .

#### **Features**

- · Open Loop transducer using the Hall effect
- Unipolar + 5 V DC power supply
- Primary current measuring range up to ± 100 A
- Maximum RMS primary current limited by the cable, the magnetic core or the ASIC temperature T° < + 150°C</li>
- Operating temperature range: 30°C < T° < 90°C
- Output voltage: full ratiometric (in sensitivity and offset)
- Temperature measurement by embedded NTC.

#### **Advantages**

- Excellent accuracy
- Very good linearity
- Very low thermal offset drift
- · Very low thermal sensitivity drift
- Current & Temperature measurement
- No insertion losses.

### **Automotive applications**

- Battery monitoring
- HEV application
- EV application.

# **Principle of HABT Family**

The open loop transducers uses a Hall effect integrated circuit.

The magnetic flux density  ${\bf B}$ , contributing to the rise of the Hall voltage, is generated by the primary current  ${\bf I}_{\rm P}$  to be measured.

The current to be measured  $I_p$  is supplied by a current source i.e. battery or generator (Fig. 1).

Within the linear region of the hysteresis cycle, **B** is proportional to:

$$\mathbf{B} (\mathbf{I}_{p}) = \text{constant (a) } \mathbf{X} \mathbf{I}_{p}$$

The Hall voltage is thus expressed by:

$$V_{H} = (R_{H}/d) \times I \times constant (a) \times I_{P}$$

Except for  $\mathbf{I}_{\mathrm{p}},$  all terms of this equation are constant. Therefore:

$$V_{H}$$
 = constant (b) x  $I_{P}$ 

The measurement signal  $\mathbf{V}_{\rm H}$  amplified to supply the user output voltage or current.

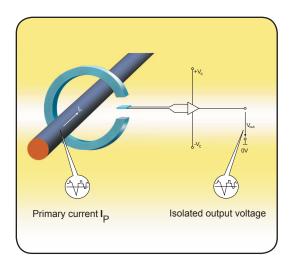
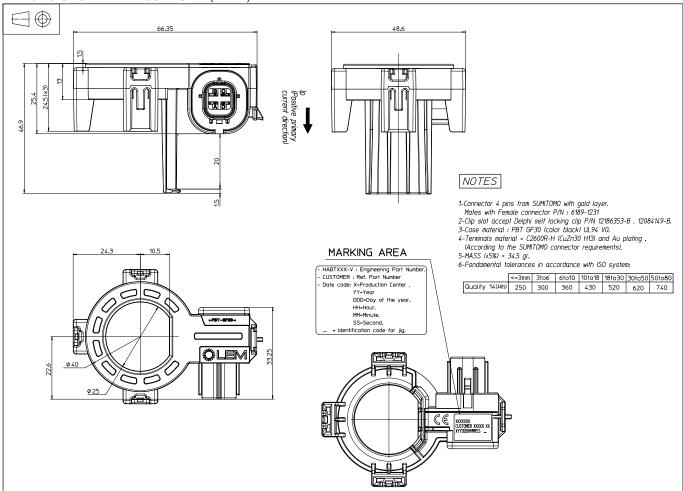


Fig. 1: Principle of the open loop transducer



## Dimensions HABT 100-V/SP1 (in mm)



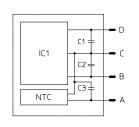
#### **Bill of materials**

Plastic case
 Magnetic core
 Pins
 Mass
 PBT GF 30
 Iron silicon alloy
 Gold plated
 35 g

#### Remark

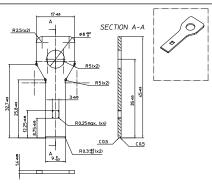
 $V_{\text{\tiny OUT}} > \frac{V_c}{2}$  when  $I_{\text{\tiny P}}$  flows in the direction of the arrow.

## System architecture

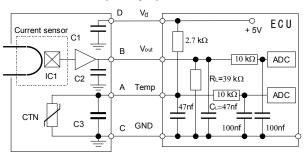


Components list							
IC1	Hall sensor ASIC						
C1	Capacitor						
C2, C3	Capacitors						
NTC	Thermistor						

Pin out							
D	DC supply voltage (5V)						
C	Ground						
В	Output signal						
Δ	Temperature signal						



#### System architecture (example)



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# **Absolute maximum ratings**

Parameter.	0	Unit	Specification			O and distance
Parameter	Symbol		Min	Тур	Max	Conditions
Electrical Data						
Nominal supply voltage		V	4.5	5	5.5	
Supply continuous over voltage	v				8.5	
Reverse voltage	■ V <sub>d</sub>		-14			1 min @ <b>T</b> <sub>A</sub> = 25°C
Over voltage					14	2 min
Continuous output voltage	V <sub>out</sub>	V			14	1 min @ <b>T</b> <sub>A</sub> = 25°C
Continuous output current	I <sub>OUT</sub>	mA	-10		10	
Output short-circuit duration	T <sub>c</sub>	min			2	
Isolation resistance	R <sub>IS</sub>	MΩ	10			DC 500 V
Ambient storage temperature	T <sub>s</sub>	°C	-40		100	

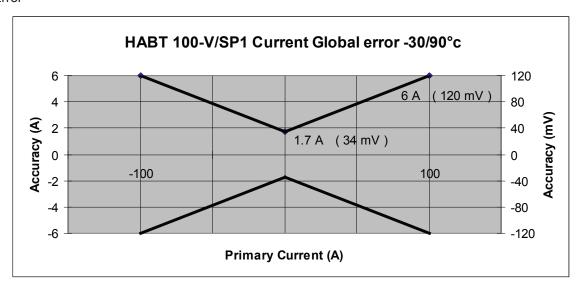
Operating characteristics

Parameter	Symbol	bol Unit		Specificati	on	Conditions
Farameter	Symbol	Unit	Min	Тур	Max	Conditions
			Electrica	l Data		
Supply voltage	$\mathbf{V}_{\mathrm{d}}$	V	4.5	5	5.5	
Continuous output current	<b>I</b> <sub>OUT</sub>	mA	-1		1	
Sensitivity error	$\epsilon_{_{ m G}}$	%		± 0.5		
Load resistance (pull down)	$R_{\scriptscriptstyle L}$	ΚΩ	9	10	100	Pull down resistance only
Capacitive loading	C <sub>∟</sub>	nF		10	100	
Ambient operating temperature	T <sub>A</sub>	°C	-30		90	
Output voltage (diagnostic detection open ground)	$\mathbf{V}_{\mathrm{OUT}}$	V			0.15	
Output voltage (diagnostic detection open $\mathbf{V}_{\mathrm{d}}$ )	<b>V</b> <sub>OUT</sub>	V			0.15	
		F	erforman	ce Data		
Current consumption			5	7		@ <b>T</b> <sub>A</sub> = 25°C
(High output impedance)	I <sub>C</sub>	mA			10	Over temperature
			-0.5		0.5	Up to 80 A <sup>2)</sup>
Linearity error	$\mathcal{E}_{\scriptscriptstyle L}$	%	-2		2	Up to 100 A <sup>2)</sup>
verall accuracy @ I = 0 A @ - 30 to 90°C		٨	-1.7		1.7	$V_{OUT} = \pm 34 \text{ mV}$ @ $V_{d} = 5 \text{ V} \pm 0.05 \text{ V}$
Overall accuracy @ I = 100 A @ - 30 to 90°C	$\mathbf{X}_{\scriptscriptstyle{\mathrm{G}}}$	Α	-6		6	<b>V</b> <sub>OUT</sub> = ± 120 mV @ <b>V</b> <sub>d</sub> = 5 V ± 0.05 V
Sensitivity	G	mV/A		20		
Global offset current	I <sub>o</sub>	mA	-300		300	@ <b>T</b> <sub>A</sub> = 25°C
Electrical offset current	I <sub>OE</sub>	mA	-250		250	@ <b>T</b> <sub>A</sub> = 25°C
Magnetic offset current	I <sub>OM</sub>	mA		110		@ <b>T</b> <sub>A</sub> = 25°C
Primary current, measuring range	I <sub>PM</sub>	Α	-100		100	
Output voltage @ I <sub>P</sub> = 0	<b>V</b> <sub>OUT</sub>	V		<b>V</b> <sub>d</sub> /2		
Resolution		mV		2.5		
Output internal resistance	<b>R</b> <sub>out</sub> Ω	1		@ <b>T</b> <sub>A</sub> = 25°C		
Output internal resistance	R <sub>OUT</sub>	32			10	Over temperature
Response time to 90 % of I <sub>PN</sub> step <sup>1)</sup>					1.1	
Power up time	t <sub>r</sub>	ms		25	200	
Setlling time after overload					25	
Negative temperature coefficient resistance	R <sub>NTC</sub>	ΚΩ	2.178	2.2	2.222	Accuracy ± 1 % @ T <sub>A</sub> = 25°C
B 25/85 constant			3485	3520	3555	Accuracy ± 1 %
Output clamping voltage low	.,	% <b>V</b> <sub>d</sub>	5.1	6	6.9	
Output clamping voltage high	$\mathbf{V}_{\mathrm{sz}}$		92.1	93	93.9	
Temperature accuracy		°C	-2		2	- 40/90°C power off

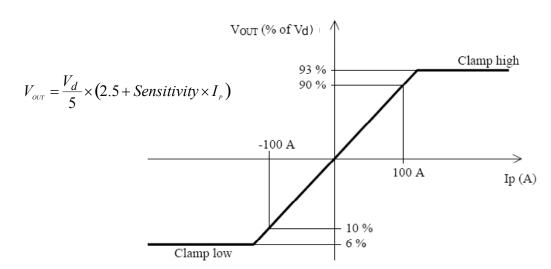
 $\underline{Notes}{:}\ ^{1)} With internal filter adjusted at 500 Hz.\ ^{2)} LEM standard 98.20.00.370.0 method 2.$ 



#### Global Error



### Output and clamping



### Temperature output

#### Simplified formula:

 $T^{\circ}C = 3520/ (Ln (R_{NTC}/2200) + 3520/298.15) - 273.15$   $R_{NTC} = R \times V_{NTC} / (V_{d} - V_{NTC})$ 

### Complete formula:

1/T°K=A1+B1\*Ln(Rntc/2200)+C1\*Ln(Rntc/2200)2+D1\*Ln(Rntc/2200)3

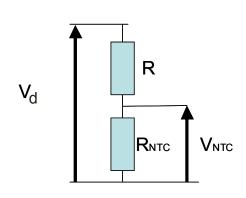
with A1 = 0.003354016

B1 = 0.0002866670

 $C1 = 1.563433 e^{-6}$ 

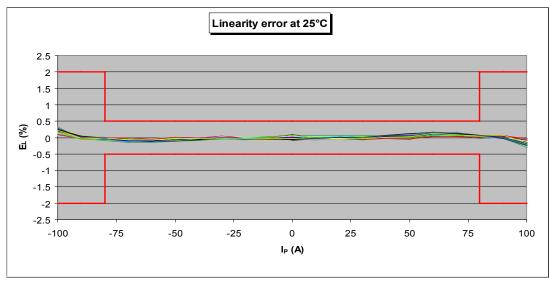
D1 =  $1.327213 e^{-7}$ 

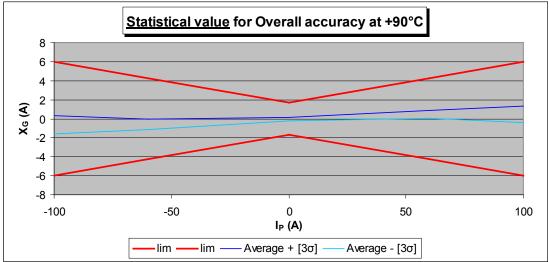
and  $T^{\circ}C = T^{\circ}K - 273.15$ 

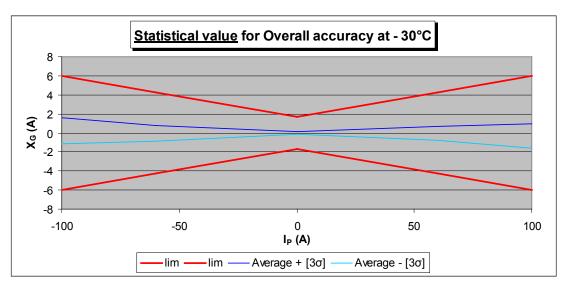


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## PERFORMANCES PARAMETERS DEFINITIONS

#### Output noise voltage:

The output voltage noise is the result of the noise floor of the Hall elements and the linear  $\mathbf{I}_{\rm c}$  amplifier gain.

#### **Magnetic offset:**

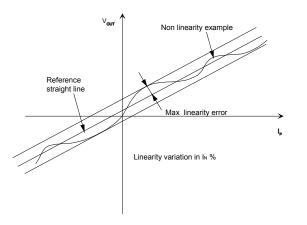
The magnetic offset is the consequence of an over-current on the primary side. It's defined after an excursion of  $I_{\rm P\,max}$ .

#### Linearity:

The maximum positive or negative discrepancy with a reference straight line  $\mathbf{V}_{\text{OUT}} = f(\mathbf{I}_{\text{p}})$ .

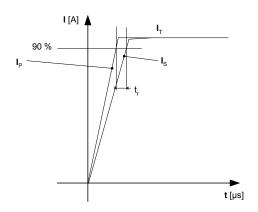
Unit: linearity (%) expressed with full scale of I<sub>P max</sub>.

Linearity is measured on cycle +  $I_p$ , O, -  $I_p$ , O, +  $I_p$  without magnetic offset (average values used).



#### Response time (delay time) t.:

The time between the primary current signal and the output signal reach at 90 % of its final value.



#### Typical:

Theorical value or usual accuracy recorded during the production.

#### Sensitivity:

The Transducer's sensitivity **G** is the slope of the straight line  $V_{out} = f(I_p)$ , it must establish the relation:

 $V_{out}(I_{p}) = V_{d}/5 (G \times I_{p} + 2.5) (*)$ 

(\*) For all symetrics transducers.

#### Offset with temperature:

The error of the offset in the operating temperature is the variation of the offset in the temperature considered with the initial offset at  $25^{\circ}$ C.

The offset variation  $\mathbf{I}_{\text{OT}}$  is a maximum variation the offset in the temperature range:

 $I_{OT} = I_{OE} \max - I_{OE} \min$ 

The Offset drift  $\mathbf{TCI}_{\text{OEAV}}$  is the  $\mathbf{I}_{\text{OT}}$  value divided by the temperature range.

#### Sensitivity with temperature:

The error of the sensitivity in the operating temperature is the relative variation of sensitivity with the temperature considered with the initial offset at 25°C.

The sensitivity variation  $\mathbf{G}_{\mathsf{T}}$  is the maximum variation (in ppm or %) of the sensitivity in the temperature range:

 $\mathbf{G}_{\mathsf{T}}$  = (Sensitivity max - Sensitivity min) / Sensitivity at 25°C.

The sensitivity drift  $\mathbf{TCG}_{\text{AV}}$  is the  $\mathbf{G}_{\text{T}}$  value divided by the temperature range.

#### Offset voltage @ $I_p = 0$ A:

Is the output voltage when the primary current is null. The ideal value of  $\mathbf{V}_{\rm O}$  is  $\mathbf{V}_{\rm d}/2$  at  $\mathbf{V}_{\rm d}=5$  V. So, the difference of  $\mathbf{V}_{\rm O}$ - $\mathbf{V}_{\rm d}/2$  is called the total offset voltage error. This offset error can be attributed to the electrical offset (due to the resolution of the ASIC quiescent voltage trimming), the magnetic offset, the thermal drift and the thermal hysteresis.



	Immunity to conducted distur	rbance test		
Immunity to signal line transients	ISO 7637-3 (1995)	Operating Class C		
Immunity to bulk current injection (BCI)	ISO 11452-4 (2005)	60 mA Class C, 100 mA Class C, 200 mA Class C		
Resistance to impulse transient		Operating Class C		
Immunity to audio frequency magnetic field	Immunity to radiated disturb	ance tests Operating Class A		
inimumity to addio frequency magnetic field	` '			
	Resistance to electrostatic disc	charge tests		
Resistance to electrostatic discharges,	IEC 61000-4-2 (2001)	± 4 kV Contact discharge: Class A		
equipment not supplied	C = 150 pF; R = 330 Ohms	± 8 kV Contact discharge: Class B ± 15 kV Air discharge: Class B		
		± 4 kV Contact discharge: Class A		
Resistance to electrostatic discharges,		± 8 kV Contact discharge: Class B ± 4 kV Air discharge: Class A		
equipment supplied	ISO 10605 (2001)	± 8 kV Air discharge: Class A		
		± 15 kV Air discharge: Class B		
	Flootrical toota	± 25 kV Air discharge: Class D		
Engine starting voltage test	Electrical tests	6 to 8 V, 1 Hz		
Voltage dips tests		1, 5, 10, 15 and 20 ms		
Reversed power connection test		13 V/1 min		
·	Environmental tests	S		
Low T°C storage test		Not powered, - 40°C, 96 ± 2H		
Low T°C operation test		- 30°C, 192H, powered		
High T° storage test		No powered, 100°C ± 3.96H		
High T° operation test		+90°C ±3, 192H, powered		
Temperature cycle test		30 cycles, 90°C to -30°C, operational 5H and non operational 1 H (180H)		
Thermal shock		-40°C/+90°C with 2000H(30 min + 30 min) no powered		
Temperature humidity cycle test				
Constant humidity test		+60°C/90% rH, 96H, powered		
Vibration in temperature		Resonnance point detection 3g, 5 to 200 Hz, sweep 10 min, 4+2+2 H		
Impact test		Free fall @ 1 m, 3 times for each 5 planes, 15 times for connector plane on concrete		
Dew condensation test		2H @ -5°C and 10 Min @ 85% rH @ 35°C no operational		
Temperature humidity cycle		1000 H 85°C/ 85% HR		
Salt spray test	JIS Z 2371	Test according to JIS Z 2371.  Leave transducers for 300H at ambient temperature of 35 ± 3°C		
Dipping test		Storage temperature 80± 3°C, storage time 1H mini water temperature 25 ± 10°C Dip depth: 100 mm dipping time 1 min No water immersion into inside of connector		
Spray frost test	JIS D 0203 R2e	Spray frost Conform to JIS D 0203 R2e		
Vibration durability		Ambient temperature 80 ± 3°C, Frequency 20 to 200 Hz, Sweep time: 2 min, Acceleration 43.12m/s^2, Time: 3 hours for each directions (top/bottom, left/right front/back), Power voltage 5 ± 2 V, measured current: 50 to - 100 A		
Chemical proof test		Chemical temperature: 25±10°C Dipping time: 1 min Exposenal temperature: 80 ± 3°C exposal time: 1H min Chemical name: Gasoline, engine, oil, brake oil, antifreeze fluid. Torque converter oil. Washer fluid. Battery fluid. CRC. WÀX WAX remover. PS. Oil.  Page 77		