



A25L040A Series

4Mbit Low Voltage, Serial Flash Memory With 100MHz Uniform 4KB Sectors

Document Title

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Revision History

<u>Rev. No.</u>	<u>History</u>	<u>Issue Date</u>	<u>Remark</u>
0.0	Initial issue	July 5, 2012	Preliminary
1.0	Change t_{BE} from 0.65s to 0.5s (typ.)	August 17, 2012	Final
1.1	Remove -U grade	October 11, 2012	
1.2	Add small sector protect function	January 11, 2013	



A25L040A Series

4Mbit Low Voltage, Serial Flash Memory With 100MHz Uniform 4KB Sectors

FEATURES

- Family of Serial Flash Memories
 - A25L040A: 4M-bit /512K-byte
- Flexible Sector Architecture with 4KB sectors
 - Sector Erase (4K-bytes) in 200ms (typical)
 - Block Erase (64K-bytes) in 0.5s (typical)
- Page Program (up to 256 Bytes) in 1.5ms (typical)
- 2.7 to 3.6V Single Supply Voltage
- SPI Bus Compatible Serial Interface
- 100MHz Clock Rate (maximum)
- Advanced Protection Features
 - Software and Hardware Write-Protect
 - Top/Bottom, Block/Sector Array Protection
- Electronic Signatures
 - JEDEC Standard Two-Byte Signature
A25L040A: (3013h)
 - RES Instruction, One-Byte, Signature, for backward compatibility
A25L040A (12h)
- Package options
 - 8-pin SOP (150/209mil), 8-pin DIP (300mil) or 8-pin WSON (6*5mm)
 - All Pb-free (Lead-free) products are RoHS compliant

GENERAL DESCRIPTION

The A25L040A is a 4M bit Serial Flash Memory, with advanced write protection mechanisms, accessed by a high speed SPI-compatible bus.

The memory can be programmed 1 to 256 bytes at a time, using the Page Program instruction.

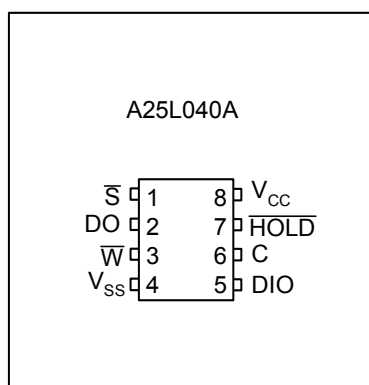
The memory is organized as 8 blocks, each containing 16

sectors. Each sector is composed of 16 pages. Each page is 256 bytes wide. Thus, the whole memory can be viewed as consisting of 2048 pages, or 524,288 bytes.

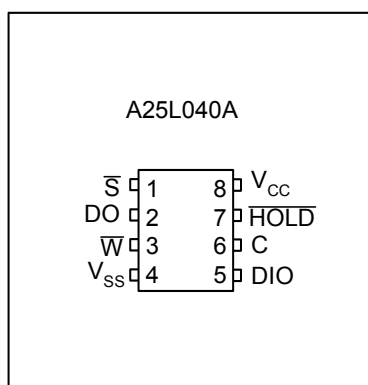
The whole memory can be erased using the Chip Erase instruction, a block at a time, using Block Erase instruction, or a sector at a time, using the Sector Erase instruction.

Pin Configurations

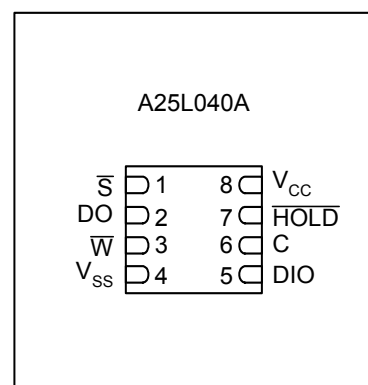
■ SOP8 Connections



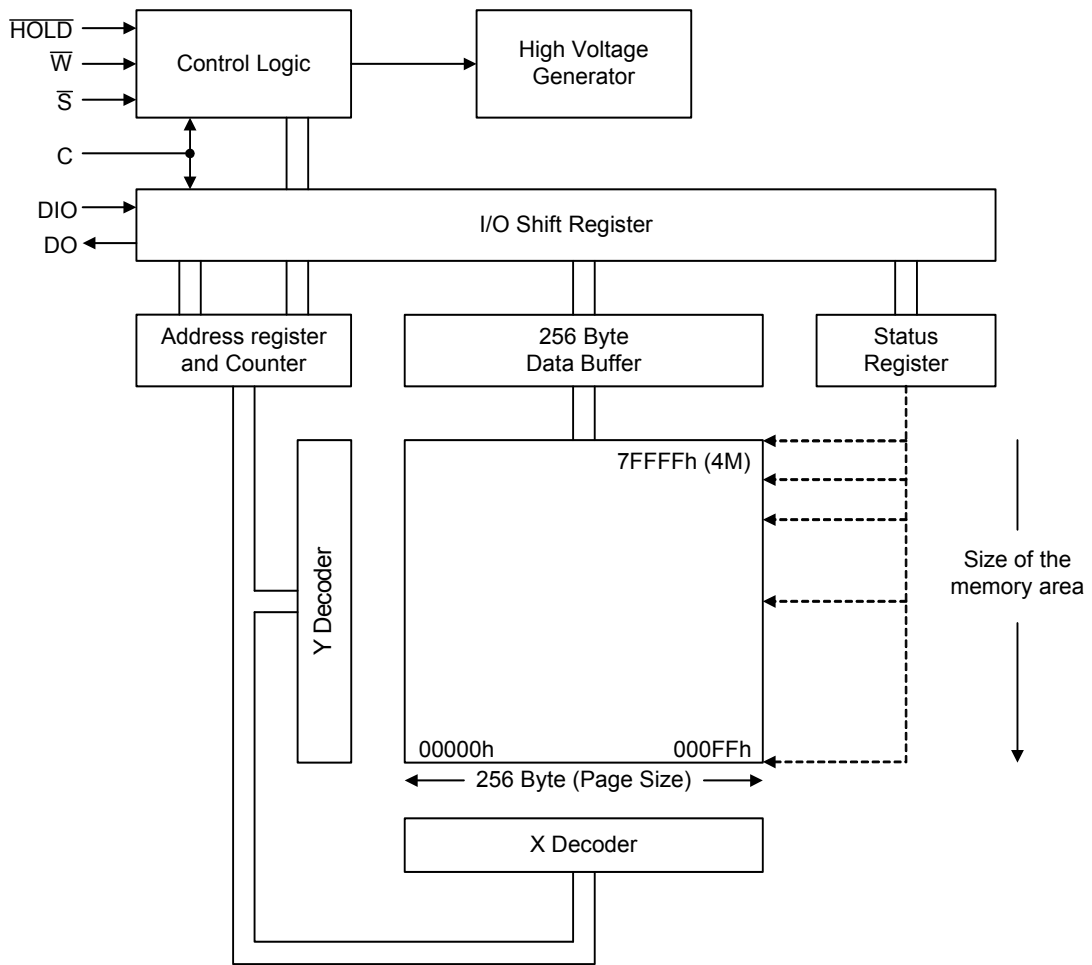
■ DIP8 Connections



■ WSON8 Connections



Block Diagram



Pin Descriptions

Pin No.	Description
C	Serial Clock
DIO	Serial Data Input ¹
DO	Serial Data Output ²
\bar{S}	Chip Select
\bar{W}	Write Protect
\bar{HOLD}	Hold
Vcc	Supply Voltage
Vss	Ground

Notes:

1. The DIO is also used as an output pin when the Fast Read Dual Output instruction and the Fast Read Dual Input-Output instruction are executed.
2. The DO is also used as an input pin when the Fast Read Dual Input-Output instruction is executed.

SIGNAL DESCRIPTION

Serial Data Output (DO). This output signal is used to transfer data serially out of the device. Data is shifted out on the falling edge of Serial Clock (C).

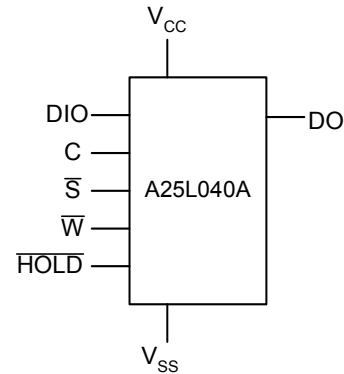
The DO pin is also used as an input pin when the Fast Read Dual Input-Output instruction is executed.

Serial Data Input (DIO). This input signal is used to transfer data serially into the device. It receives instructions, addresses, and the data to be programmed. Values are latched on the rising edge of Serial Clock (C).

The DIO pin is also used as an output pin when the Fast Read Dual Output instruction and the Fast Read Dual Input-Output instruction are executed.

Serial Clock (C). This input signal provides the timing of the serial interface. Instructions, addresses, or data present at Serial Data Input (DIO) are latched on the rising edge of Serial Clock (C). Data on Serial Data Output (DO) changes after the falling edge of Serial Clock (C).

Chip Select (\bar{S}). When this input signal is High, the device is deselected and Serial Data Output (DO) is at high

Logic Symbol


impedance. Unless an internal Program, Erase or Write Status Register cycle is in progress, the device will be in the Standby mode (this is not the Deep Power-down mode). Driving Chip Select (\bar{S}) Low enables the device, placing it in the active power mode.

After Power-up, a falling edge on Chip Select (\bar{S}) is required prior to the start of any instruction.

Hold (\bar{HOLD}). The Hold (\bar{HOLD}) signal is used to pause any serial communications with the device without deselecting the device.

During the Hold condition, the Serial Data Output (DO) is high impedance, and Serial Data Input (DIO) and Serial Clock (C) are Don't Care. To start the Hold condition, the device must be selected, with Chip Select (\bar{S}) driven Low.

Write Protect (\bar{W}). The main purpose of this input signal is to freeze the size of the area of memory that is protected against program or erase instructions (as specified by the values in the BP2, BP1, and BP0 bits of the Status Register).

SPI MODES

These devices can be driven by a microcontroller with its SPI peripheral running in either of the two following modes:

- CPOL=0, CPHA=0
- CPOL=1, CPHA=1

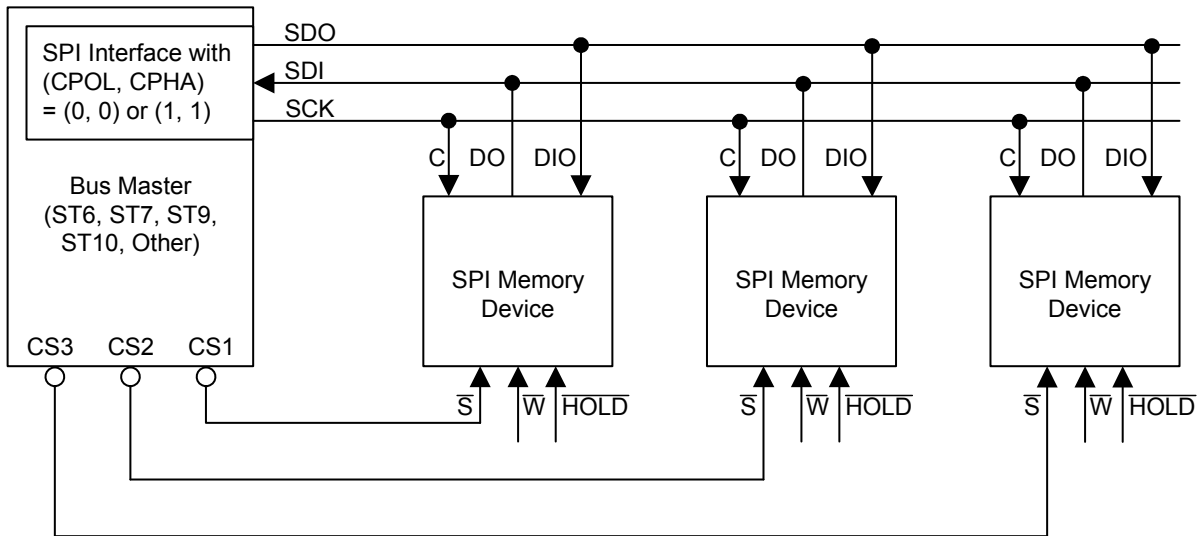
For these two modes, input data is latched in on the rising edge of Serial Clock (C), and output data is available from the

falling edge of Serial Clock (C).

The difference between the two modes, as shown in Figure 2, is the clock polarity when the bus master is in Stand-by mode and not transferring data:

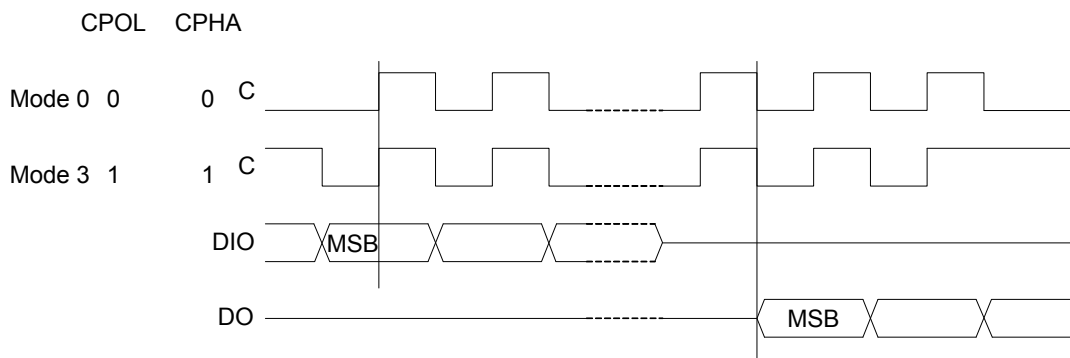
- C remains at 0 for (CPOL=0, CPHA=0) → Mode 0
- C remains at 1 for (CPOL=1, CPHA=1) → Mode 3

Figure 1. Bus Master and Memory Devices on the SPI Bus



Note: The Write Protect (\overline{W}) and Hold (\overline{HOLD}) signals should be driven, High or Low as appropriate.

Figure 2. SPI Modes Supported



OPERATING FEATURES

Page Programming

To program one data byte, two instructions are required: Write Enable (WREN), which is one byte, and a Page Program (PP) sequence, which consists of four bytes plus data. This is followed by the internal Program cycle (of duration t_{PP}).

To spread this overhead, the Page Program (PP) instruction allows up to 256 bytes be programming at a time (changing bits from 1 to 0), providing that they lie in consecutive addresses on the same page of memory.

Sector Erase, Block Erase, and Chip Erase

The Page Program (PP) instruction allows bits to be reset from 1 to 0. Before this can be applied, the bytes of memory need to have been erased to all 1s (FFh). This can be achieved, a sector at a time, using the Sector Erase (SE) instruction, a block at a time, using the Block Erase (BE) instruction, or throughout the entire memory, using the Chip Erase (CE) instruction. This starts an internal Erase cycle (of duration t_{SE} , t_{BE} , or t_{CE}).

The Erase instruction must be preceded by a Write Enable (WREN) instruction.

Polling During a Write, Program or Erase Cycle

A further improvement in the time to Write Status Register (WRSR), Program (PP) or Erase (SE, BE, or CE) can be achieved by not waiting for the worst case delay (t_w , t_{PP} , t_{SE} , t_{BE} , t_{CE}). The Write In Progress (WIP) bit is provided in the Status Register so that the application program can monitor its value, polling it to establish when the previous Write cycle, Program cycle or Erase cycle is complete.

Active Power, Stand-by Power and Deep Power-Down Modes

When Chip Select (\bar{S}) is Low, the device is enabled, and in the Active Power mode.

When Chip Select (\bar{S}) is High, the device is disabled, but could remain in the Active Power mode until all internal cycles have completed (Program, Erase, Write Status Register). The device then goes in to the Stand-by Power mode. The device consumption drops to I_{cc1} .

The Deep Power-down mode is entered when the specific instruction (the Deep Power-down Mode (DP) instruction) is executed. The device consumption drops further to I_{cc2} . The device remains in this mode until another specific instruction (the Release from Deep Power-down Mode and Read Electronic Signature (RES) instruction) is executed.

All other instructions are ignored while the device is in the Deep Power-down mode. This can be used as an extra software protection mechanism, when the device is not in active use, to protect the device from inadvertent Write, Program or Erase instructions.

Status Register

The Status Register contains a number of status and control bits that can be read or set (as appropriate) by specific instructions. See Read Status Register (RDSR) for a detailed description of the Status Register bits.

Protection Modes

The environments where non-volatile memory devices are used can be very noisy. No SPI device can operate correctly in the presence of excessive noise. To help combat this, the A25L040A boasts the following data protection mechanisms:

- Power-On Reset and an internal timer (t_{PUW}) can provide protection against inadvertent changes while the power supply is outside the operating specification.
- Program, Erase and Write Status Register instructions are checked that they consist of a number of clock pulses that is a multiple of eight, before they are accepted for execution.
- All instructions that modify data must be preceded by a Write Enable (WREN) instruction to set the Write Enable Latch (WEL) bit. This bit is returned to its reset state by the following events:
 - Power-up
 - Write Disable (WRDI) instruction completion
 - Write Status Register (WRSR) instruction completion
 - Page Program (PP) instruction completion
 - Sector Erase (SE) instruction completion
 - Block Erase (BE) instruction completion
 - Chip Erase (CE) instruction completion
- The Sector/Block Protect (SEC, BP2, BP1, BP0) bits allow part of the memory to be configured as read-only. This is the Software Protected Mode (SPM).
- The Write Protect (\bar{W}) signal allows the Sector/Block Protect (SEC, BP2, BP1, BP0) bits and Status Register Write Disable (SRWD) bit to be protected. This is the Hardware Protected Mode (HPM).
- In addition to the low power consumption feature, the Deep Power-down mode offers extra software protection from inadvertent Write, Program and Erase instructions, as all instructions are ignored except one particular instruction (the Release from Deep Power-down instruction).

Table 1. Protected Area Sizes
A25L040A

	SEC	TB	BP2	BP1	BP0	Protected Area	Unprotected Area
Block Protect	0	X	0	0	0	None	All Blocks
	0	0	0	0	1	Block 7	Block 0 - 6
	0	0	0	1	0	Block 6 - 7	Block 0 - 5
	0	0	0	1	1	Block 4 - 7	Block 0 - 3
	0	1	0	0	1	Block 0	Block 1 - 7
	0	1	0	1	0	Block 0 - 1	Block 2 - 7
	0	1	0	1	1	Block 0 - 3	Block 4 - 7
	0	X	1	X	X	All Blocks	None
Sector Protect	1	0	0	0	0	Sector 2 - 127	Sector 0 - 1
	1	0	0	0	1	Sector 4 - 127	Sector 0 - 3
	1	0	0	1	0	Sector 6 - 127	Sector 0 - 5
	1	0	0	1	1	Sector 8 - 127	Sector 0 - 7
	1	1	0	0	0	Sector 0 - 125	Sector 126 - 127
	1	1	0	0	1	Sector 0 - 123	Sector 124 - 127
	1	1	0	1	0	Sector 0 - 121	Sector 122 - 127
	1	1	0	1	1	Sector 0 - 119	Sector 120 - 127
	1	0	1	0	0	Sector 0 - 1	Sector 2 - 127
	1	0	1	0	1	Sector 0 - 3	Sector 4 - 127
	1	0	1	1	0	Sector 0 - 5	Sector 6 - 127
	1	0	1	1	1	Sector 0 - 7	Sector 8 - 127
	1	1	1	0	0	Sector 126 - 127	Sector 0 - 125
	1	1	1	0	1	Sector 124 - 127	Sector 0 - 123
	1	1	1	1	0	Sector 122 - 127	Sector 0 - 121
	1	1	1	1	1	Sector 120 - 127	Sector 0 - 119

Notes:

1. X = don't care
2. If any Program or Erase command specifies a memory region that contains protected data portion, this command will be ignored.
3. The definition of block here is for 64K byte area.

Hold Condition

The Hold ($\overline{\text{HOLD}}$) signal is used to pause any serial communications with the device without resetting the clocking sequence. However, taking this signal Low does not terminate any Write Status Register, Program or Erase cycle that is currently in progress.

To enter the Hold condition, the device must be selected, with Chip Select ($\overline{\text{S}}$) Low.

The Hold condition starts on the falling edge of the Hold ($\overline{\text{HOLD}}$) signal, provided that this coincides with Serial Clock (C) being Low (as shown in Figure 3.).

The Hold condition ends on the rising edge of the Hold ($\overline{\text{HOLD}}$) signal, provided that this coincides with Serial Clock (C) being Low.

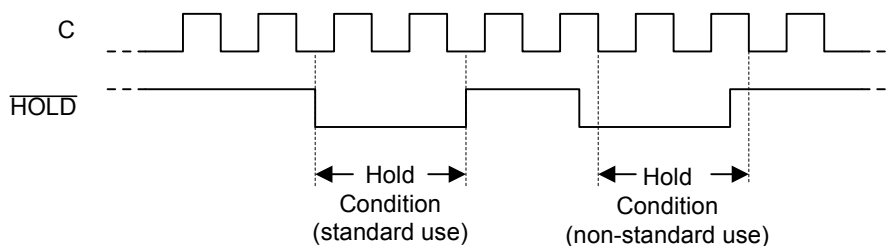
If the falling edge does not coincide with Serial Clock (C) being Low, the Hold condition starts after Serial Clock (C) next goes Low. Similarly, if the rising edge does not coincide with Serial Clock (C) being Low, the Hold condition ends after

Serial Clock (C) next goes Low. This is shown in Figure 3. During the Hold condition, the Serial Data Output (DO) is high impedance, and Serial Data Input (DIO) and Serial Clock (C) are Don't Care.

Normally, the device is kept selected, with Chip Select ($\overline{\text{S}}$) driven Low, for the whole duration of the Hold condition. This is to ensure that the state of the internal logic remains unchanged from the moment of entering the Hold condition.

If Chip Select ($\overline{\text{S}}$) goes High while the device is in the Hold condition, this has the effect of resetting the internal logic of the device. To restart communication with the device, it is necessary to drive Hold ($\overline{\text{HOLD}}$) High, and then to drive Chip Select ($\overline{\text{S}}$) Low. This prevents the device from going back to the Hold condition.

Figure 3. Hold Condition Activation



A25L040A MEMORY ORGANIZATION

The memory is organized as:

- 524,288 bytes (8 bits each)
- 8 64-Kbytes block
- 128 4-Kbytes sector
- 2048 pages (256 bytes each).

Each page can be individually programmed (bits are programmed from 1 to 0). The device is Sector, Block, or Chip Erasable (bits are erased from 0 to 1) but not Page Erasable.

Table 2. Memory Organization
A25L040A Address Table

Block	Sector	Address Range	
7	127	7F000h	7FFFFh
	⋮	⋮	⋮
	120	78000h	78FFFh
	119	77000h	77FFFh
	⋮	⋮	⋮
	112	70000h	70FFFh
⋮			
0	15	0F000h	0FFFFh
	⋮	⋮	⋮
	8	08000h	08FFFh
	7	07000h	07FFFh
	⋮	⋮	⋮
	0	00000h	00FFFh

INSTRUCTIONS

All instructions, addresses and data are shifted in and out of the device, most significant bit first.

Serial Data Input (DIO) is sampled on the first rising edge of Serial Clock (C) after Chip Select (\bar{S}) is driven Low. Then, the one-byte instruction code must be shifted in to the device, most significant bit first, on Serial Data Input (DIO), each bit being latched on the rising edges of Serial Clock (C).

The instruction set is listed in Table 3.

Every instruction sequence starts with a one-byte instruction code. Depending on the instruction, this might be followed by address bytes, or by data bytes, or by both or none.

In the case of a Read Data Bytes (READ), Read Data Bytes at Higher Speed (Fast_Read), Read Status Register (RDSR) or Release from Deep Power-down, Read Device Identification and Read Electronic Signature (RES) instruction, the shifted-in instruction sequence is followed by a data-out sequence. Chip

Select (\bar{S}) can be driven High after any bit of the data-out sequence is being shifted out.

In the case of a Page Program (PP), Sector Erase (SE), Block Erase (BE), Chip Erase (CE), Write Status Register (WRSR), Write Enable (WREN), Write Disable (WRDI) or Deep Power-down (DP) instruction, Chip Select (\bar{S}) must be driven High exactly at a byte boundary, otherwise the instruction is rejected, and is not executed. That is, Chip Select (\bar{S}) must be driven High when the number of clock pulses after Chip Select (\bar{S}) being driven Low is an exact multiple of eight.

All attempts to access the memory array during a Write Status Register cycle, Program cycle or Erase cycle are ignored, and the internal Write Status Register cycle, Program cycle or Erase cycle continues unaffected.

Table 3. Instruction Set

Instruction	Description	One-byte Instruction Code		Address Bytes	Dummy Bytes	Data Bytes
		Binary	Hex			
WREN	Write Enable	0000 0110	06h	0	0	0
WRDI	Write Disable	0000 0100	04h	0	0	0
RDSR	Read Status Register	0000 0101	05h	0	0	1 to ∞
WRSR	Write Status Register	0000 0001	01h	0	0	1
READ	Read Data Bytes	0000 0011	03h	3	0	1 to ∞
FAST_READ	Read Data Bytes at Higher Speed	0000 1011	0Bh	3	1	1 to ∞
FAST_READ_DUAL_OUTPUT	Read Data Bytes at Higher Speed by Dual Output ⁽¹⁾	00111011	3Bh	3	1	1 to ∞
FAST_READ_DUAL_INPUT-OUTPUT	Read Data Bytes at Higher Speed by Dual Input and Dual Output ⁽¹⁾	10111011	BBh	3 ⁽²⁾	1 ⁽²⁾	1 to ∞
PP	Page Program	0000 0010	02h	3	0	1 to 256
SE	Sector Erase	0010 0000	20h	3	0	0
BE	Block Erase	1101 1000	D8h	3	0	0
		0101 0010	52h			
CE	Chip Erase	1100 0111	C7h	0	0	0
		0110 0000	60h			
DP	Deep Power-down	1011 1001	B9h	0	0	0
RDID	Read Device Identification	1001 1111	9Fh	0	0	1 to ∞
REMS	Read Electronic Manufacturer & Device Identification	1001 0000	90h	1 ⁽³⁾	2	1 to ∞
RES	Release from Deep Power-down, and Read Electronic Signature	1010 1011	ABh	0	3	1 to ∞
	Release from Deep Power-down			0	0	0
HPM	High Performance Mode	1010 0011	A3h	0	3	0

Note: (1) DIO = (D₆, D₄, D₂, D₀)

DO = (D₇, D₅, D₃, D₁)

(2) Dual Input, DIO = (A₂₂, A₂₀, A₁₈,, A₆, A₄, A₂, A₀)

DO = (A₂₃, A₂₁, A₁₉,, A₇, A₅, A₃, A₁)

(3) ADD= (00h) will output manufacturer's ID first and ADD=(01h) will output device ID first

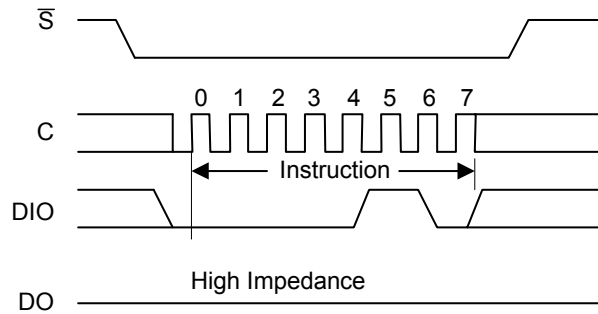
Write Enable (WREN)

The Write Enable (WREN) instruction (Figure 4.) sets the Write Enable Latch (WEL) bit.

The Write Enable Latch (WEL) bit must be set prior to every Page Program (PP), Sector Erase (SE), Bulk Erase (BE) and Write Status Register (WRSR) instruction.

The Write Enable (WREN) instruction is entered by driving Chip Select (\bar{S}) Low, sending the instruction code, and then driving Chip Select (\bar{S}) High.

Figure 4. Write Enable (WREN) Instruction Sequence



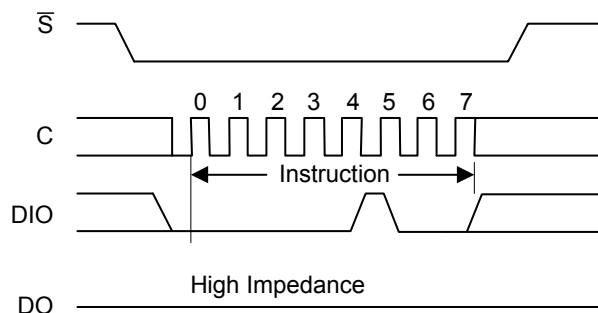
Write Disable (WRDI)

The Write Disable (WRDI) instruction (Figure 5.) resets the Write Enable Latch (WEL) bit.

The Write Disable (WRDI) instruction is entered by driving Chip Select (\bar{S}) Low, sending the instruction code, and then driving Chip Select (\bar{S}) High. The Write Enable Latch (WEL) bit is reset under the following conditions:

- Power-up
- Write Disable (WRDI) instruction completion
- Write Status Register (WRSR) instruction completion
- Page Program (PP) instruction completion
- Sector Erase (SE) instruction completion
- Bulk Erase (BE) instruction completion

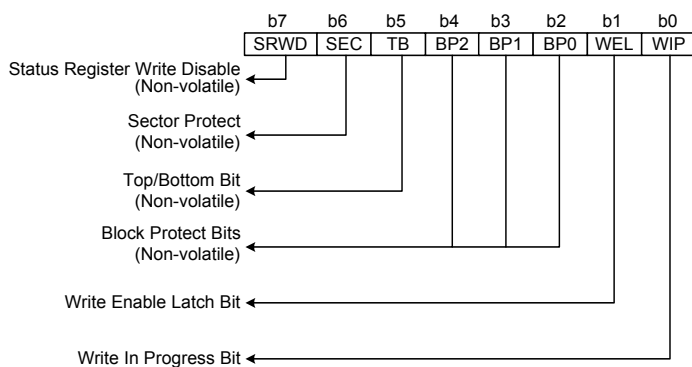
Figure 5. Write Disable (WRDI) Instruction Sequence



Read Status Register (RDSR)

The Read Status Register (RDSR) instruction allows the Status Register to be read. The instruction code of "05h" is for Status Register-1 and "35h" is for Status Register-2. The Status Register may be read at any time, even while a Program, Erase or Write Status Register cycle is in progress. When one of these cycles is in progress, it is recommended to check the Write In Progress (WIP) bit before sending a new instruction to the device. It is also possible to read the Status Register continuously, as shown in Figure 6.

Table 4. Status Register- 1 Format



The status and control bits of the Status Register are as follows:

WIP bit. The Write In Progress (WIP) bit is a read only bit in the status register (b0) that is set to a 1 state when the device is busy with a Write Status Register, Program or Erase cycle. During this time the device will ignore further instructions except for the Read Status Register instructions (see t_W , t_{PP} , t_{SE} , t_{BE} , and t_{CE} in AC Characteristics). When the program, erase, write status register instruction has completed, the WIP bit will be cleared to a 0 state indicating the device is ready for further instructions.

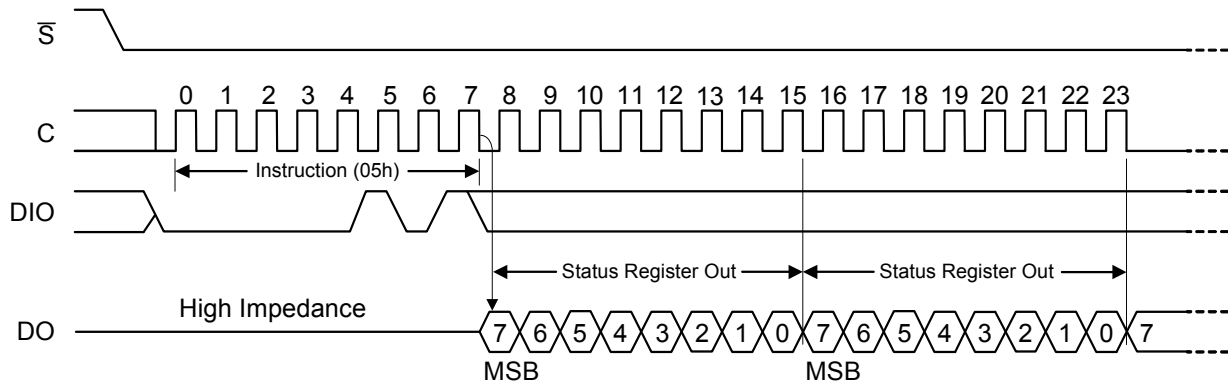
WEL bit. The Write Enable Latch (WEL) bit is a read only bit in the status register (b1) that is set to a 1 after executing a Write Enable Instruction. The WEL status bit is cleared to a 0 when the device is write disabled. A write disable state occurs upon power-up or after any completion of the following instructions: Write Disable, Page Program, Sector Erase, Block Erase, Chip Erase, and Write Status Register.

BP2, BP1, BP0 bits. The Block Protect (BP2, BP1, and BP0) bits are non-volatile read/write bits in the status register (b4, b3, and b2) that provide Write Protection control and status. Block Protect bits can be set using the Write Status Register Instruction (see t_W in AC characteristics). All, none or a portion of the memory array can be protected from Program and Erase instructions (see Table 1. Protected Area Sizes). These bits can be set with the Write Status Register Instruction depending on the state of the SRWD, and WEL bit. The factory default setting for the Block Protect Bits is 0 which means none of the array protected.

TB bit. The non-volatile Top/Bottom (TB) bit controls if the Block/Sector Protect Bits (BP2, BP1, BP0, SEC) protect from the Top or the Bottom of the array as shown in Table 1. Protected Area Sizes. The factory default setting is TB=0. The TB bit can be set with the Write Status Register Instruction depending on the state of the SRWD, and WEL bit.

SEC bit. The non-volatile Sector Protect (SEC) bit in the status register (b6) controls if the Block Protect Bits (BP2, BP1, BP0) protect 4KB Sectors (SEC=1) or 64KB Blocks (SEC=0) in the Top or the Bottom of the array as shown in Table 1. Protected Area Sizes. This bit can be set with the Write Status Register Instruction depending on the state of the SRWD, and WEL bit. The factory default setting for SEC is 0.

SRWD bit. The Status Register Write Disable bit SRWD is a non-volatile read/write bit in the status register (b7). The SRWD bit controls the method of write protection: software protection, hardware protection. The factory default setting for SRWD is 0.

Figure 6. Read Status Register (RDSR) Instruction Sequence and Data-Out Sequence


Write Status Register

The Write Status Register (WRSR) instruction allows new values to be written to the Status Register. Before it can be accepted, a Write Enable (WREN) instruction must previously have been executed. After the Write Enable (WREN) instruction has been decoded and executed, the device sets the Write Enable Latch (WEL).

The Write Status Register (WRSR) instruction is entered by driving Chip Select (\overline{S}) Low, followed by the instruction code and the data byte on Serial Data Input (DIO).

The instruction sequence is shown in Figure 7. The Write Status Register (WRSR) instruction has no effect on b6, b5, b1 and b0 of the Status Register. b6 and b5 are always read as 0.

Chip Select (\overline{S}) must be driven High after the eighth bit of the data byte has been latched in. If not, the Write Status Register (WRSR) instruction is not executed. As soon as

Chip Select (\overline{S}) is driven High, the self-timed Write Status Register cycle (whose duration is t_w) is initiated. While the

Write Status Register cycle is in progress, the Status Register may still be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Write Status Register cycle, and is 0 when it is completed. When the cycle is completed, the Write Enable Latch (WEL) is reset.

The Write Status Register (WRSR) instruction allows the user to change the values of the Sector/Block Protect (SEC, TB, BP2, BP1, BP0) bits, to define the size of the area that is to be treated as read-only, as defined in Table 1. The Write Status Register (WRSR) instruction also allows the user to set or reset the Status Register Write Disable (SRWD) bit in accordance with the Write Protect (\overline{W}) signal. The Status Register Write Disable (SRWD) bit and Write Protect (\overline{W}) signal allow the device to be put in the Hardware Protected Mode (HPM). The Write Status Register (WRSR) instruction is not executed once the Hardware Protected Mode (HPM) is entered.

Figure 7. Write Status Register (WRSR) Instruction Sequence

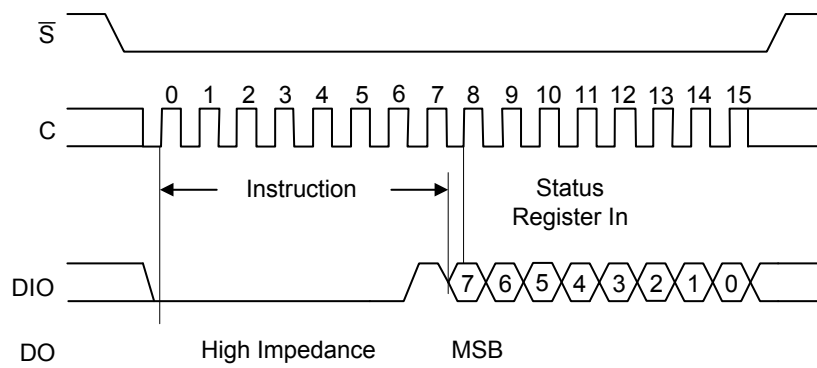


Table 5. Protection Modes

\overline{W} Signal	SRWD Bit	Mode	Write Protection of the Status Register	Memory Content	
				Protected Area ¹	Unprotected Area ¹
1	0	Software Protected (SPM)	Status Register is Writable (if the WREN instruction has set the WEL bit). The values in the SRWD, SEC, TB, BP2, BP1, and BP0 bits can be changed	Protected against Page Program, Sector Erase, Block Erase, and Chip Erase	Ready to accept Page Program, Sector Erase, and Block Erase instructions
0	0				
1	1				
0	1	Hardware Protected (HPM)	Status Register is Hardware write protected. The values in the SRWD, SEC, TB, BP2, BP1, and BP0 bits cannot be changed	Protected against Page Program, Sector Erase, Block Erase, and Chip Erase	Ready to accept Page Program, Sector Erase, and Block Erase instructions

Note: 1. See Table 1 for more details.

The protection features of the device are summarized in Table 5.

When the Status Register Write Disable (SRWD) bit of the Status Register is 0 (its initial delivery state), it is possible to write to the Status Register provided that the Write Enable Latch (WEL) bit has previously been set by a Write Enable (WREN) instruction, regardless of the whether Write Protect (\overline{W}) is driven High or Low.

When the Status Register Write Disable (SRWD) bit of the Status Register is set to 1, two cases need to be considered, depending on the state of Write Protect (\overline{W}):

- If Write Protect (\overline{W}) is driven High, it is possible to write to the Status Register provided that the Write Enable Latch (WEL) bit has previously been set by a Write Enable (WREN) instruction.
- If Write Protect (\overline{W}) is driven Low, it is *not* possible to write to the Status Register *even* if the Write Enable Latch (WEL) bit has previously been set by a Write Enable (WREN) instruction. (Attempts to write to the Status Register are rejected, and are not accepted for execution).

As a consequence, all the data bytes in the memory area that are software protected (SPM) by the Sector/Block Protect (SEC, TB, BP2, BP1, BP0) bits of the Status Register, are also hardware protected against data modification.

Regardless of the order of the two events, the Hardware Protected Mode (HPM) can be entered:

- by setting the Status Register Write Disable (SRWD) bit after driving Write Protect (\overline{W}) Low
- or by driving Write Protect (\overline{W}) Low after setting the Status Register Write Disable (SRWD) bit.

The only way to exit the Hardware Protected Mode (HPM) once entered is to pull Write Protect (\overline{W}) High.

If Write Protect (\overline{W}) is permanently tied High, the Hardware Protected Mode (HPM) can never be activated, and only the Software Protected Mode (SPM), using the Sector/Block Protect (SEC, TB, BP2, BP1, BP0) bits of the Status Register, can be used.

Read Data Bytes (READ)

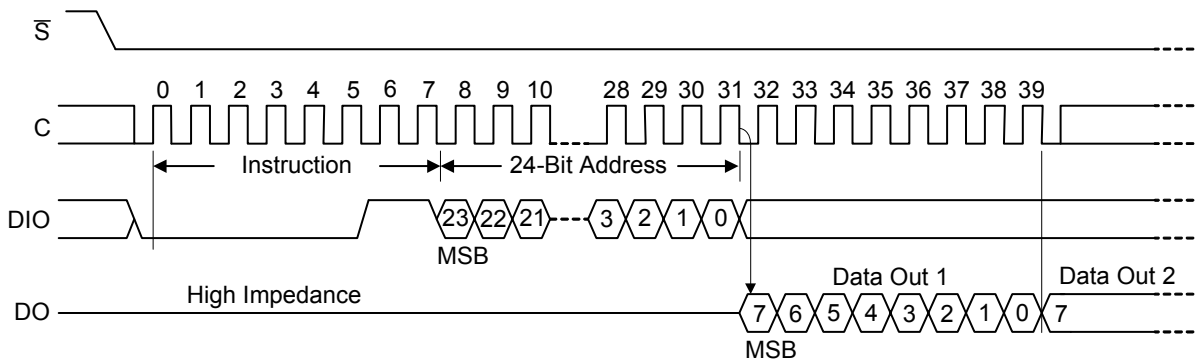
The device is first selected by driving Chip Select (\overline{S}) Low. The instruction code for the Read Data Bytes (READ) instruction is followed by a 3-byte address (A23-A0), each bit being latched-in during the rising edge of Serial Clock (C). Then the memory contents, at that address, is shifted out on Serial Data Output (DO), each bit being shifted out, at a maximum frequency f_R , during the falling edge of Serial Clock (C).

The instruction sequence is shown in Figure 8. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out. The whole memory can,

therefore, be read with a single Read Data Bytes (READ) instruction. When the highest address is reached, the address counter rolls over to 000000h, allowing the read sequence to be continued indefinitely.

The Read Data Bytes (READ) instruction is terminated by driving Chip Select (\overline{S}) High. Chip Select (\overline{S}) can be driven High at any time during data output. Any Read Data Bytes (READ) instruction, while an Erase, Program or Write cycle is in progress, is rejected without having any effects on the cycle that is in progress.

Figure 8. Read Data Bytes (READ) Instruction Sequence and Data-Out Sequence



Note: Address bits A23 to A19 are Don't Care, for A25L040A.

Read Data Bytes at Higher Speed (FAST_READ)

The device is first selected by driving Chip Select (\overline{S}) Low. The instruction code for the Read Data Bytes at Higher Speed (FAST_READ) instruction is followed by a 3-byte address (A23-A0) and a dummy byte, each bit being latched-in during the rising edge of Serial Clock (C). Then the memory contents, at that address, is shifted out on Serial Data Output (DO), each bit being shifted out, at a maximum frequency f_c , during the falling edge of Serial Clock (C).

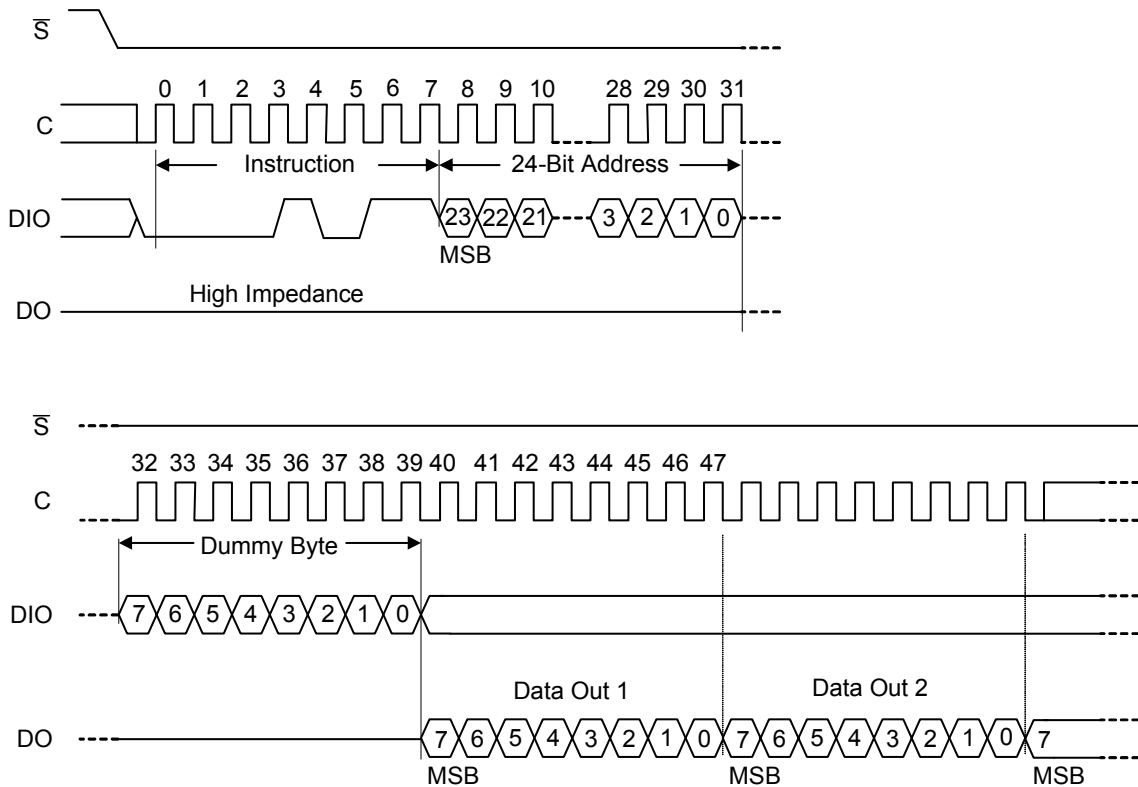
The instruction sequence is shown in Figure 9. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out. The whole memory can, therefore, be read with a single Read Data Bytes at Higher

Speed (FAST_READ) instruction. When the highest address is reached, the address counter rolls over to 000000h, allowing the read sequence to be continued indefinitely.

The Read Data Bytes at Higher Speed (FAST_READ) instruction is terminated by driving Chip Select (\overline{S}) High.

Chip Select (\overline{S}) can be driven High at any time during data output. Any Read Data Bytes at Higher Speed (FAST_READ) instruction, while an Erase, Program or Write cycle is in progress, is rejected without having any effects on the cycle that is in progress.

Figure 9. Read Data Bytes at Higher Speed (FAST_READ) Instruction Sequence and Data-Out Sequence



Note: Address bits A23 to A19 are Don't Care, for A25L040A.

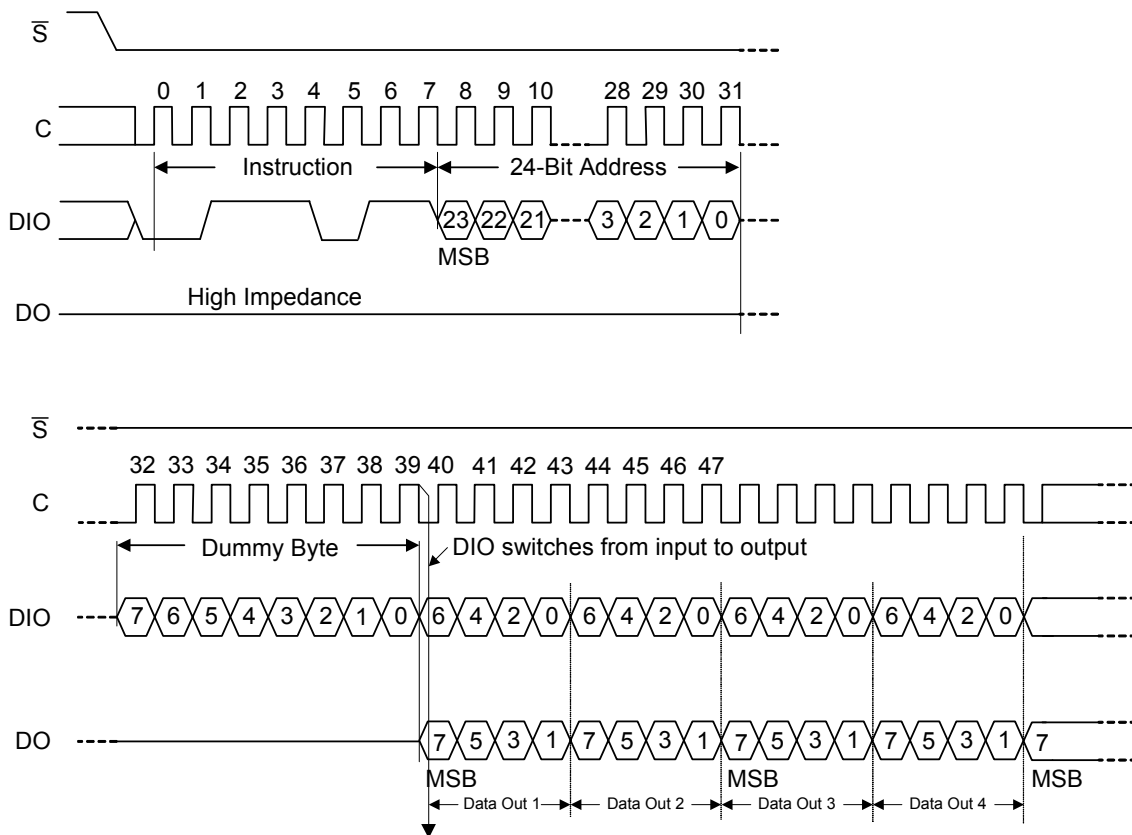
Fast Read Dual Output (3Bh)

The Fast Read Dual Output (3Bh) instruction is similar to the Fast_Read (0Bh) instruction except the data is output on two pins, DO and DIO, instead of just DO. This allows data to be transferred from the A25L040A at twice the rate of standard SPI devices.

Similar to the Fast Read instruction, the Fast Read Dual Output instruction can operate at the highest possible frequency of f_c (See AC Characteristics). This is

accomplished by adding eight “dummy” clocks after the 24-bit address as shown in figure 10. The dummy clocks allow the device’s internal circuits additional time for setting up the initial address. The input data during the dummy clocks is “don’t care”. However, the DIO pin should be high-impedance prior to the falling edge of the first data out clock.

Figure 10. FAST_READ_DUAL_OUTPUT Instruction Sequence and Data-Out Sequence



Note: Address bits A23 to A19 are Don't Care, for A25L040A.

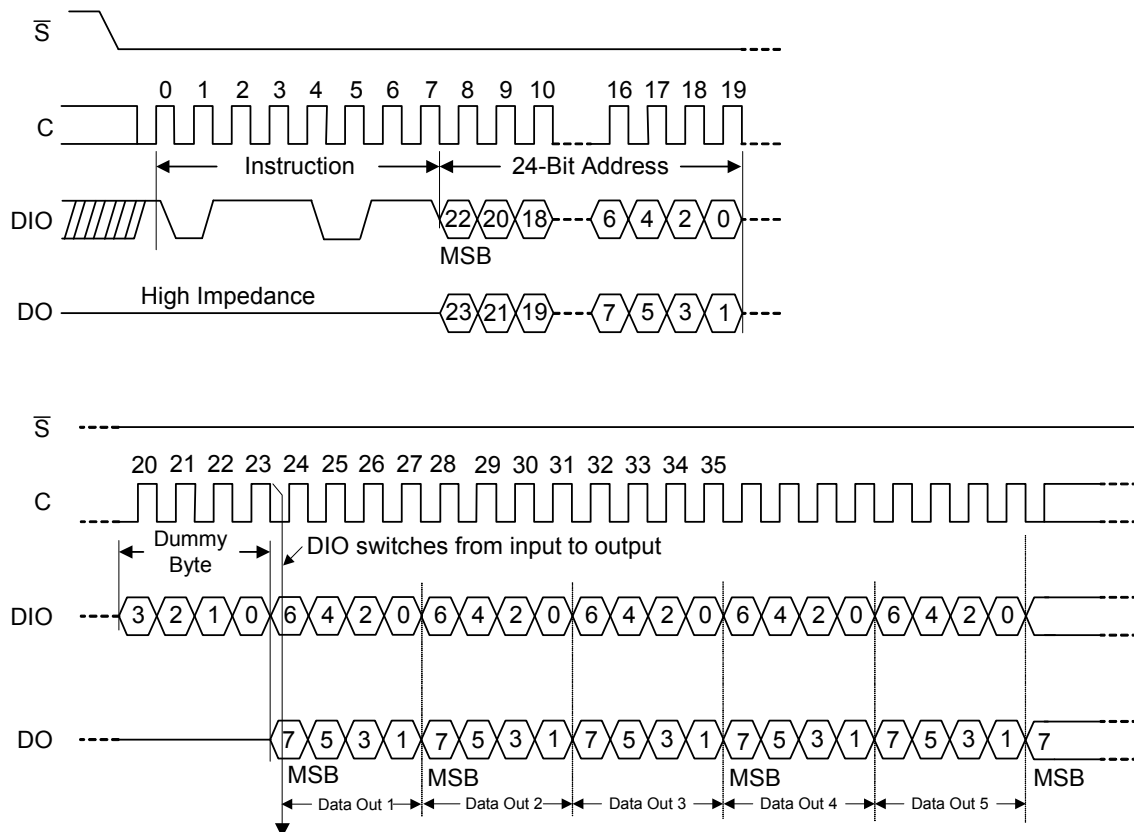
Fast Read Dual Input-Output (BBh)

The Fast Read Dual Input-Output (BBh) instruction is similar to the Fast_Read (0Bh) instruction except the data is input and output on two pins, DO and DIO, instead of just DO. This allows data to be transferred from the A25L040A at twice the rate of standard SPI devices.

Similar to the Fast Read instruction, the Fast Read Dual Output instruction can operate at the highest possible frequency of f_c (See AC Characteristics). This is

accomplished by adding four “dummy” clocks after the 24-bit address as shown in figure 11. The dummy clocks allow the device’s internal circuits additional time for setting up the initial address. The input data during the dummy clocks is “don’t care”. However, the DIO and DO pins should be high-impedance prior to the falling edge of the first data out clock.

Figure 11. FAST_READ_DUAL_INPUT-OUTPUT Instruction Sequence and Data-Out Sequence



Note: Address bits A23 to A19 are Don't Care, for A25L040A.

Page Program (PP)

The Page Program (PP) instruction allows bytes to be programmed in the memory (changing bits from 1 to 0). Before it can be accepted, a Write Enable (WREN) instruction must previously have been executed. After the Write Enable (WREN) instruction has been decoded, the device sets the Write Enable Latch (WEL).

The Page Program (PP) instruction is entered by driving Chip Select (\bar{S}) Low, followed by the instruction code, three address bytes and at least one data byte on Serial Data Input (DIO). If the 8 least significant address bits (A7-A0) are not all zero, all transmitted data that goes beyond the end of the current page are programmed from the start address of the same page (from the address whose 8 least significant bits (A7-A0) are all zero). Chip Select (\bar{S}) must be driven Low for the entire duration of the sequence.

The instruction sequence is shown in Figure 12. If more than 256 bytes are sent to the device, previously latched data are discarded and the last 256 data bytes are guaranteed to be

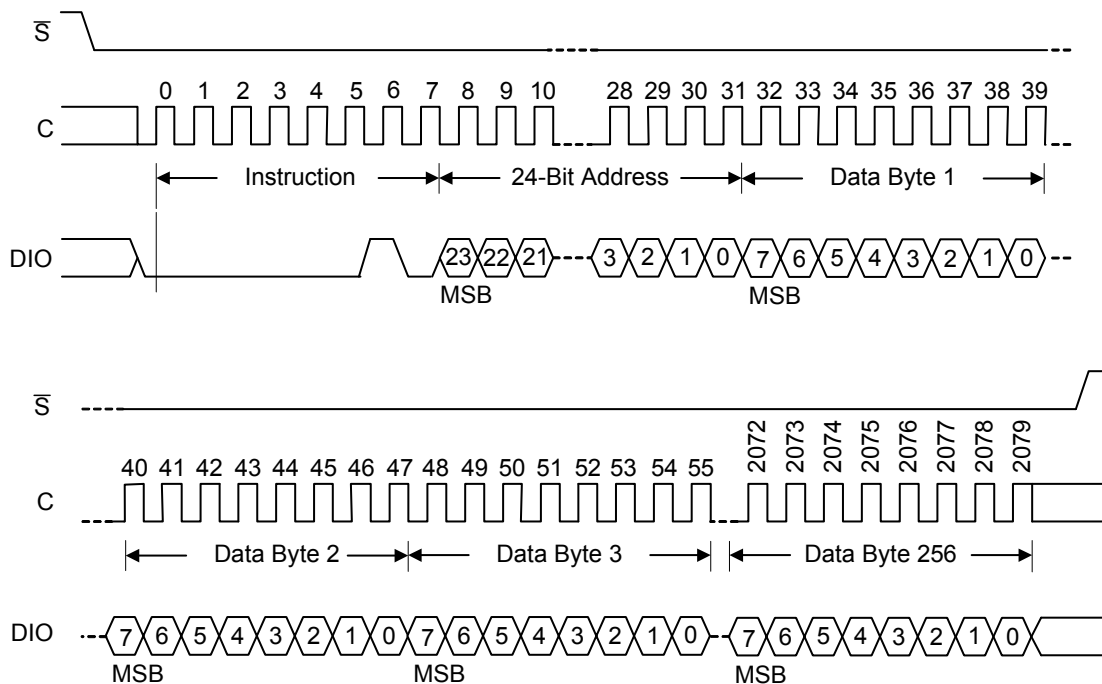
programmed correctly within the same page. If less than 256 Data bytes are sent to device, they are correctly programmed at the requested addresses without having any effects on the other bytes of the same page.

Chip Select (\bar{S}) must be driven High after the eighth bit of the last data byte has been latched in, otherwise the Page Program (PP) instruction is not executed.

As soon as Chip Select (\bar{S}) is driven High, the self-timed Page Program cycle (whose duration is t_{PP}) is initiated. While the Page Program cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Page Program cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset.

A Page Program (PP) instruction applied to a page which is protected by the Sector/Block Protect (SEC, TB, BP2, BP1, BP0) bits (see Table 1 and Table 2.) is not executed.

Figure 12. Page Program (PP) Instruction Sequence



Note: Address bits A23 to A19 are Don't Care, for A25L040A.

Sector Erase (SE)

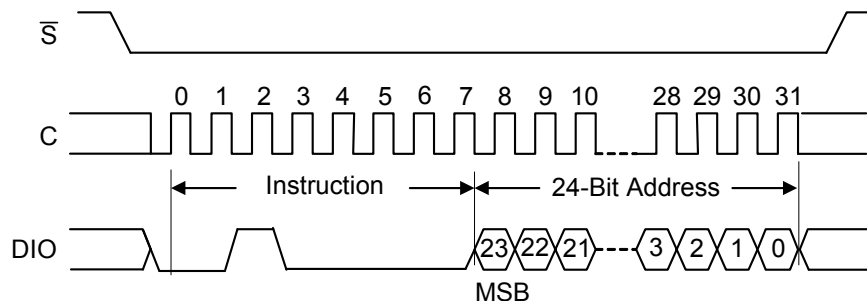
The Sector Erase (SE) instruction sets to 1 (FFh) all bits inside the chosen sector. Before it can be accepted, a Write Enable (WREN) instruction must previously have been executed. After the Write Enable (WREN) instruction has been decoded, the device sets the Write Enable Latch (WEL).

The Sector Erase (SE) instruction is entered by driving Chip Select (\bar{S}) Low, followed by the instruction code on Serial Data Input (DIO). Chip Select (\bar{S}) must be driven Low for the entire duration of the sequence.

The instruction sequence is shown in Figure 13. Chip Select (\bar{S}) must be driven High after the eighth bit of the instruction code has been latched in, otherwise the Sector Erase

instruction is not executed. As soon as Chip Select (\bar{S}) is driven High, the self-timed Sector Erase cycle (whose duration is t_{SE}) is initiated. While the Sector Erase cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Sector Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. A Sector Erase (SE) instruction applied to a page which is protected by the Sector/Block Protect (SEC, TB, BP2, BP1, BP0) bits (see table 1 and table 2.) is not executed.

Figure 13. Sector Erase (SE) Instruction Sequence



Note: Address bits A23 to A19 are Don't Care, for A25L040A.

Block Erase

The Block Erase (BE) instruction sets to 1 (FFh) all bits inside the chosen block. Before it can be accepted, a Write Enable (WREN) instruction must previously have been executed. After the Write Enable (WREN) instruction has been decoded, the device sets the Write Enable Latch (WEL).

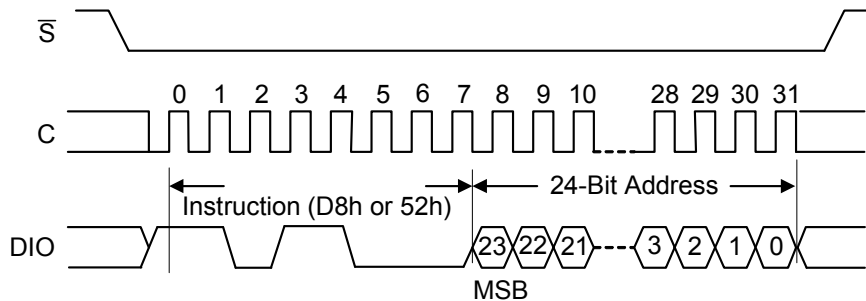
The Block Erase (BE) instruction is entered by driving Chip Select (\bar{S}) Low, followed by the instruction code on Serial Data Input (DIO). Chip Select (\bar{S}) must be driven Low for the entire duration of the sequence.

The instruction sequence is shown in Figure 14. Chip Select (\bar{S}) must be driven High after the eighth bit of the instruction code has been latched in, otherwise the Block Erase

instruction is not executed. As soon as Chip Select (\bar{S}) is driven High, the self-timed Block Erase cycle (whose duration is t_{BE}) is initiated. While the Block Erase cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Block Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset.

A Block Erase (BE) instruction applied to a page which is protected by the Sector/Block Protect (SEC, TB, BP2, BP1, BP0) bits (see table 1 and table 2.) is not executed.

Figure 14. Block Erase Instruction Sequence



Note: Address bits A23 to A19 are Don't Care, for A25L040A.

Chip Erase (CE)

The Chip Erase (CE) instruction sets all bits to 1 (FFh). Before it can be accepted, a Write Enable (WREN) instruction must previously have been executed. After the Write Enable (WREN) instruction has been decoded, the device sets the Write Enable Latch (WEL).

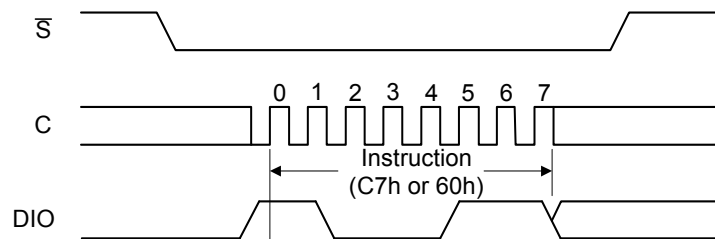
The Chip Erase (CE) instruction is entered by driving Chip Select (\bar{S}) Low, followed by the instruction code on Serial Data Input (DIO). Chip Select (\bar{S}) must be driven Low for the entire duration of the sequence.

The instruction sequence is shown in Figure 16. Chip Select (\bar{S}) must be driven High after the eighth bit of the instruction code has been latched in, otherwise the Bulk Erase instruction

is not executed. As soon as Chip Select (\bar{S}) is driven High, the self-timed Chip Erase cycle (whose duration is t_{CE}) is initiated. While the Chip Erase cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Chip Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset.

The Chip Erase (CE) instruction is executed only if all Block /Sector Protect (SEC, BP2, BP1, BP0) bits are 0. The Chip Erase (CE) instruction is ignored if one, or more, blocks are protected.

Figure 16. Chip Erase (CE) Instruction Sequence



Deep Power-down (DP)

Executing the Deep Power-down (DP) instruction is the only way to put the device in the lowest consumption mode (the Deep Power-down mode). It can also be used as an extra software protection mechanism, while the device is not in active use, since in this mode, the device ignores all Write, Program and Erase instructions.

Driving Chip Select (\bar{S}) High deselects the device, and puts the device in the Standby mode (if there is no internal cycle currently in progress). But this mode is not the Deep Power-down mode. The Deep Power-down mode can only be entered by executing the Deep Power-down (DP) instruction, to reduce the standby current (from I_{CC1} to I_{CC2} , as specified in DC Characteristics Table.).

Once the device has entered the Deep Power-down mode, all instructions are ignored except the Release from Deep Power-down and Read Electronic Signature (RES) instruction. This releases the device from this mode. The Release from Deep Power-down and Read Electronic Signature (RES) instruction also allows the Electronic Signature of the device to be output on Serial Data Output (DO).

The Deep Power-down mode automatically stops at Power-down, and the device always Powers-up in the Standby mode.

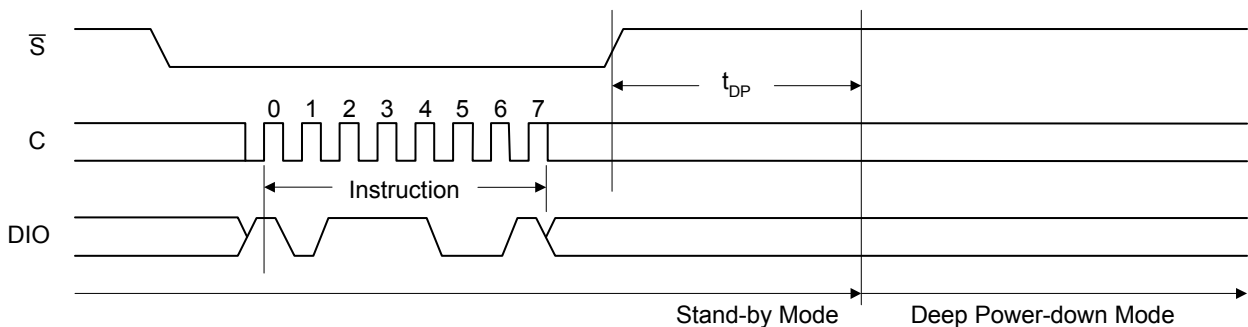
The Deep Power-down (DP) instruction is entered by driving Chip Select (\bar{S}) Low, followed by the instruction code on Serial Data Input (DIO). Chip Select (\bar{S}) must be driven Low for the entire duration of the sequence. The instruction sequence is shown in Figure 17.

Chip Select (\bar{S}) must be driven High after the eighth bit of the instruction code has been latched in, otherwise the Deep Power-down (DP) instruction is not executed. As soon as

Chip Select (\bar{S}) is driven High, it requires a delay of t_{DP} before the supply current is reduced to I_{CC2} and the Deep Power-down mode is entered.

Any Deep Power-down (DP) instruction, while an Erase, Program or Write cycle is in progress, is rejected without having any effects on the cycle that is in progress.

Figure 17. Deep Power-down (DP) Instruction Sequence



Read Device Identification (RDID)

The Read Identification (RDID) instruction allows the 8-bit manufacturer identification code to be read, followed by two bytes of device identification. The manufacturer identification is assigned by JEDEC, and has the value 37h. The device identification is assigned by the device manufacturer, and indicates the memory in the first bytes (30h), and the memory capacity of the device in the second byte.

Any Read Identification (RDID) instruction while an Erase, or Program cycle is in progress, is not decoded, and has no effect on the cycle that is in progress.

The device is first selected by driving Chip Select (\bar{S}) Low. Then, the 8-bit instruction code for the instruction is shifted in.

This is followed by the 24-bit device identification, stored in the memory, being shifted out on Serial Data Output (DO), each bit being shifted out during the falling edge of Serial Clock (C).

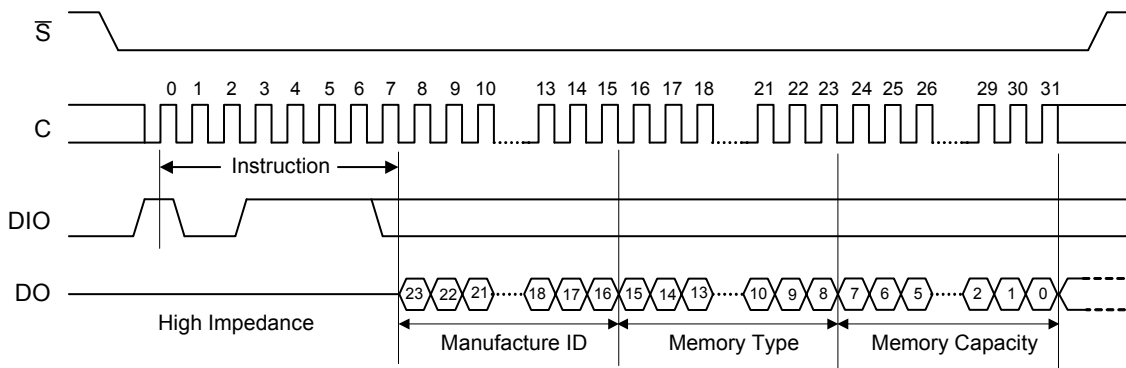
The instruction sequence is shown in Figure 18. The Read Identification (RDID) instruction is terminated by driving Chip Select (\bar{S}) High at any time during data output.

When Chip Select (\bar{S}) is driven High, the device is put in the Stand-by Power mode. Once in the Stand-by Power mode, the device waits to be selected, so that it can receive, decode and execute instructions.

Table 6. Read Identification (READ_ID) Data-Out Sequence

Manufacture Identification	Device Identification	
Manufacture ID	Memory Type	Memory Capacity
37h	30h	13h

Figure 18. Read Identification (RDID) Instruction Sequence and Data-Out Sequence



Read Electronic Manufacturer ID & Device ID (REMS)

The Read Electronic Manufacturer ID & Device ID (REMS) instruction allows the 8-bit manufacturer identification code to be read, followed by one byte of device identification. The manufacturer identification is assigned by JEDEC, and has the value 37h for AMIC. The device identification is assigned by the device manufacturer.

Any Read Electronic Manufacturer ID & Device ID (REMS) instruction while an Erase, or Program cycle is in progress, is not decoded, and has no effect on the cycle that is in progress.

The device is first selected by driving Chip Select (\bar{S}) Low. The 8-bit instruction code is followed by 2 dummy bytes and one byte address (A7~A0), each bit being latched-in on Serial Data Input (DIO) during the rising edge of Serial Clock (C).

If the one-byte address is set to 01h, then the device ID will be read first and then followed by the Manufacturer ID. On the other hand, if the one-byte address is set to 00h, then the Manufacturer ID will be read first and then followed by the device ID.

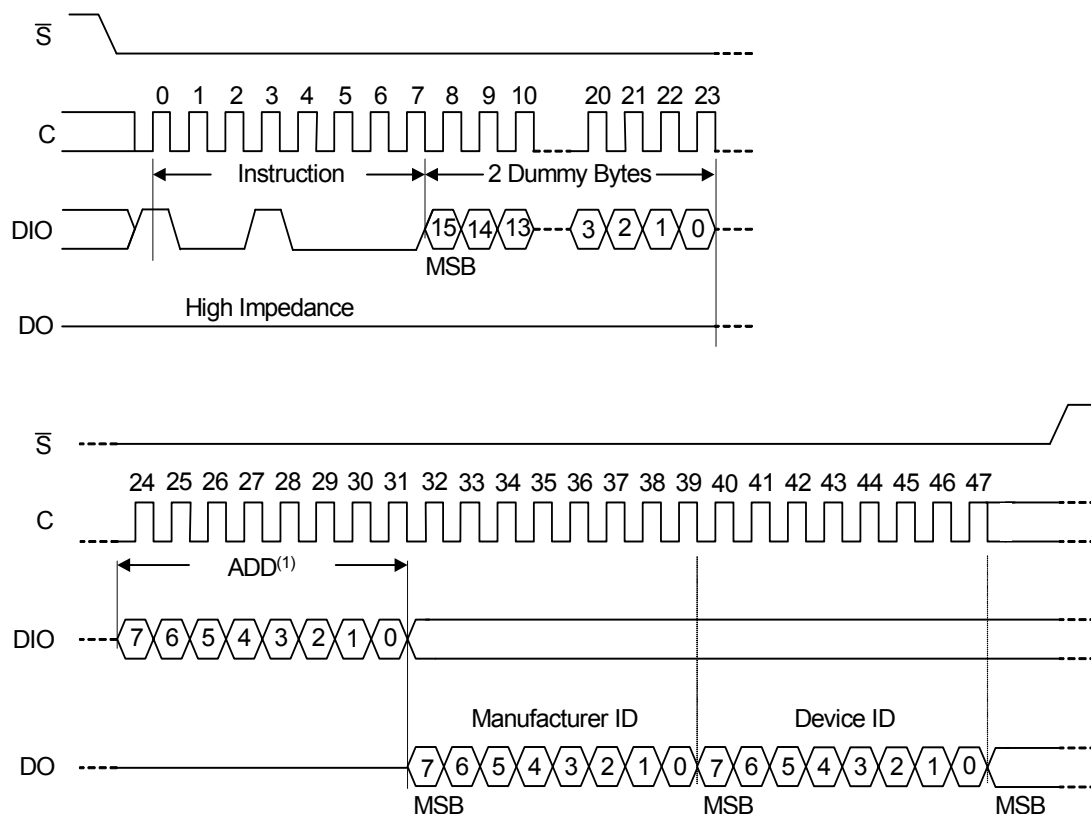
The instruction sequence is shown in Figure 19. The Read Electronic Manufacturer ID & Device ID (REMS) instruction is terminated by driving Chip Select (\bar{S}) High at any time during data output.

When Chip Select (\bar{S}) is driven High, the device is put in the Stand-by Power mode. Once in the Stand-by Power mode, the device waits to be selected, so that it can receive, decode and execute instructions.

Table 7. Read Electronic Manufacturer ID & Device ID (REMS) Data-Out Sequence

Manufacture Identification	Device Identification
37h	12h

Figure 19. Read Electronic Manufacturer ID & Device ID (REMS) Instruction Sequence and Data-Out Sequence



Notes:

(1) ADD=00h will output the manufacturer ID first and ADD=01h will output device ID first

Release from Deep Power-down and Read Electronic Signature (RES)

Once the device has entered the Deep Power-down mode, all instructions are ignored except the Release from Deep Power-down and Read Electronic Signature (RES) instruction. Executing this instruction takes the device out of the Deep Power-down mode.

The instruction can also be used to read, on Serial Data Output (DO), the 8-bit Electronic Signature, as shown below.

Except while an Erase, Program or Write Status Register cycle is in progress, the Release from Deep Power-down and Read Electronic Signature (RES) instruction always provides access to the 8-bit Electronic Signature of the device, and can be applied even if the Deep Power-down mode has not been entered.

Any Release from Deep Power-down and Read Electronic Signature (RES) instruction while an Erase, Program or Write Status Register cycle is in progress, is not decoded, and has no effect on the cycle that is in progress.

The device is first selected by driving Chip Select (\bar{S}) Low. The instruction code is followed by 3 dummy bytes, each bit being latched-in on Serial Data Input (DIO) during the rising

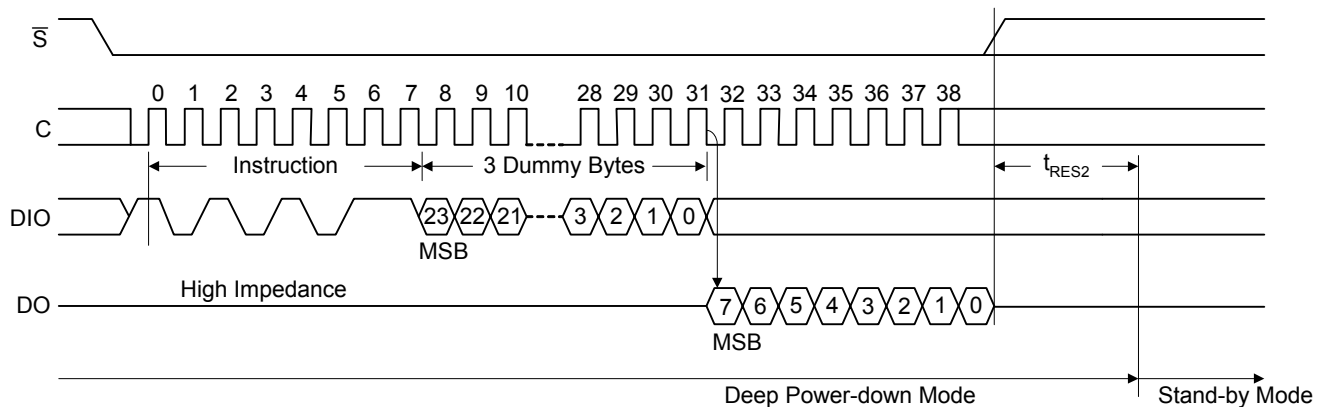
edge of Serial Clock (C). Then, the 8-bit Electronic Signature, stored in the memory, is shifted out on Serial Data Output (DO), each bit being shifted out during the falling edge of Serial Clock (C).

The instruction sequence is shown in Figure 20.

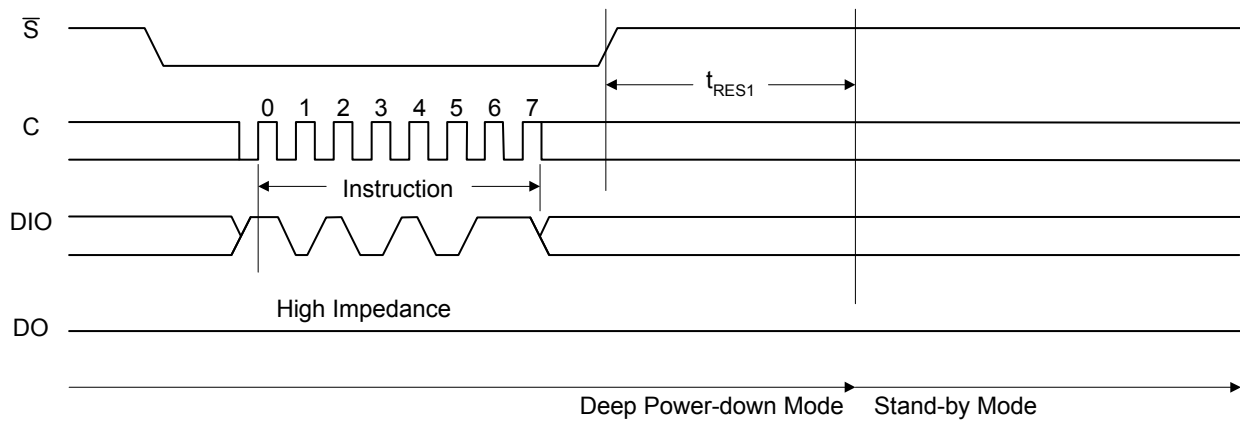
The Release from Deep Power-down and Read Electronic Signature (RES) instruction is terminated by driving Chip Select (\bar{S}) High after the Electronic Signature has been read at least once. Sending additional clock cycles on Serial Clock (C), while Chip Select (\bar{S}) is driven Low, cause the Electronic Signature to be output repeatedly.

When Chip Select (\bar{S}) is driven High, the device is put in the Stand-by Power mode. If the device was not previously in the Deep Power-down mode, the transition to the Stand-by Power mode is immediate. If the device was previously in the Deep Power-down mode, though, the transition to the Stand-by Power mode is delayed by t_{RES2} , and Chip Select (\bar{S}) must remain High for at least $t_{RES2}(\max)$, as specified in AC Characteristics Table . Once in the Stand-by Power mode, the device waits to be selected, so that it can receive, decode and execute instructions.

Figure 20. Release from Deep Power-down and Read Electronic Signature (RES) Instruction Sequence and Data-Out Sequence



Note: The value of the 8-bit Electronic Signature, for the A25L040A is 12h.

Figure 21. Release from Deep Power-down (RES) Instruction Sequence


Driving Chip Select (\overline{CS}) High after the 8-bit instruction byte has been received by the device, but before the whole of the 8-bit Electronic Signature has been transmitted for the first time (as shown in Figure 21.), still insures that the device is put into Stand-by Power mode. If the device was not previously in the Deep Power-down mode, the transition to the Stand-by Power mode is immediate. If the device was

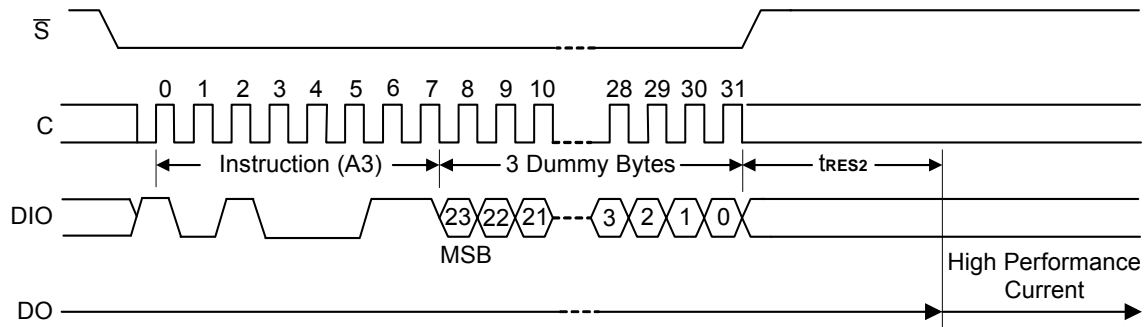
previously in the Deep Power-down mode, though, the transition to the Stand-by Power mode is delayed by t_{RES1} , and Chip Select (\overline{CS}) must remain High for at least $t_{RES1}(\max)$, as specified in AC Characteristics Table. Once in the Stand-by Power mode, the device waits to be selected, so that it can receive, decode and execute instructions.

High Performance Mode (HPM)

The High Performance Mode (HPM) instruction can be executed prior to Dual I/O instructions if chip is operated at high frequencies. This instruction allows pre-charging of internal charge pumps so the voltages required for accessing the Flash memory array are readily available. The instruction sequence includes the A3h instruction code followed by three dummy byte clocks shown in Fig.21. After the HPM

instruction is executed, the device will maintain a slightly higher standby current than standard SPI operation. The Release from Power-down (ABh) can be used to return to standard SPI standby current (I_{cc1}). In addition, Write Enable instruction (06h) and Power Down instruction (B9h) will also release the device from HPM mode back to standard SPI standby state.

Figure 22. High Performance Mode Instruction Sequence



POWER-UP AND POWER-DOWN

At Power-up and Power-down, the device must not be selected (that is Chip Select (\overline{S}) must follow the voltage applied on V_{CC}) until V_{CC} reaches the correct value:

- $V_{CC}(\text{min})$ at Power-up, and then for a further delay of t_{VSL}
- V_{SS} at Power-down

Usually a simple pull-up resistor on Chip Select (\overline{S}) can be used to insure safe and proper Power-up and Power-down.

To avoid data corruption and inadvertent write operations during power up, a Power On Reset (POR) circuit is included. The logic inside the device is held reset while V_{CC} is less than the POR threshold value, V_{WI} – all operations are disabled, and the device does not respond to any instruction.

Moreover, the device ignores all Write Enable (WREN), Page Program (PP), Sector Erase (SE), Block Erase (BE), Chip Erase (CE) and Write Status Register (WRSR) instructions until a time delay of t_{PUW} has elapsed after the moment that V_{CC} rises above the V_{WI} threshold. However, the correct operation of the device is not guaranteed if, by this time, V_{CC} is still below $V_{CC}(\text{min})$. No Write Status Register, Program or Erase instructions should be sent until the later of:

- t_{PUW} after V_{CC} passed the V_{WI} threshold
- t_{VSL} after V_{CC} passed the $V_{CC}(\text{min})$ level

These values are specified in Table 8.

If the delay, t_{VSL} , has elapsed, after V_{CC} has risen above $V_{CC}(\text{min})$, the device can be selected for Read instructions even if the t_{PUW} delay is not yet fully elapsed.

At Power-up, the device is in the following state:

- The device is in the Standby mode (not the Deep Power-down mode).
- The Write Enable Latch (WEL) bit is reset.

Normal precautions must be taken for supply rail decoupling, to stabilize the V_{CC} feed. Each device in a system should have the V_{CC} rail decoupled by a suitable capacitor close to the package pins. (Generally, this capacitor is of the order of $0.1\mu\text{F}$).

At Power-down, when V_{CC} drops from the operating voltage, to below the POR threshold value, V_{WI} , all operations are disabled and the device does not respond to any instruction. (The designer needs to be aware that if a Power-down occurs while a Write, Program or Erase cycle is in progress, some data corruption can result.)

Figure 23. Power-up Timing

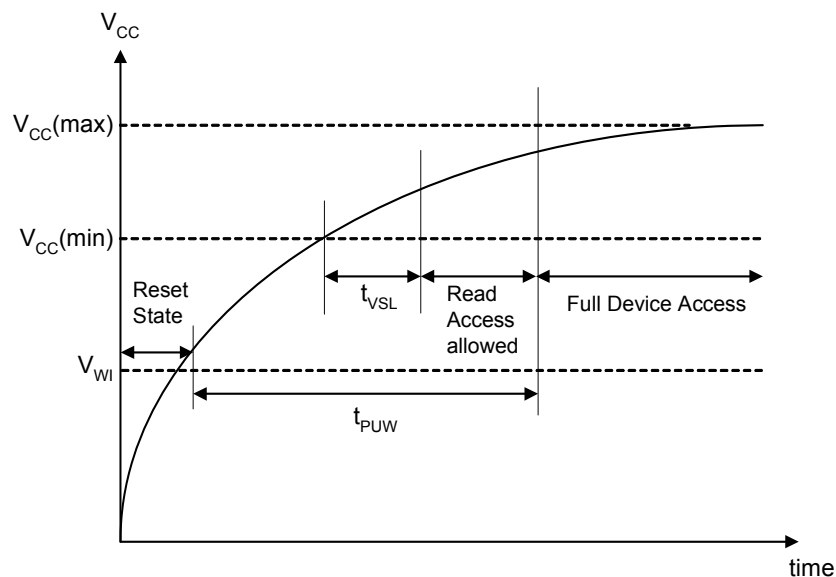


Table 8. Power-Up Timing

Symbol	Parameter	Min.	Max.	Unit
t _{vSL}	V _{CC(min)} to \bar{S} Low	10		μ s
t _{puw}	Time Delay Before Write Instruction	3		ms
V _{wi}	Write Inhibit Threshold Voltage	2.3	2.5	V

Note: These parameters are characterized only.

INITIAL DELIVERY STATE

The device is delivered with the memory array erased: all bits are set to 1 (each byte contains FFh). The Status Register contains 00h (all Status Register bits are 0).

Absolute Maximum Ratings*

Storage Temperature (TSTG)	-65°C to + 150°C
Lead Temperature during Soldering (Note 1)	
D.C. Voltage on Any Pin to Ground Potential	-0.6V to $V_{CC} + 0.6V$
Transient Voltage (<20ns) on Any Pin to Ground Potential	-2.0V to $V_{CC} + 2.0V$
Supply Voltage (V_{CC})	-0.6V to +4.0V
Electrostatic Discharge Voltage (Human Body model) (VESD) (Note 2)	-2000V to 2000V

Notes:

1. Compliant with JEDEC Std J-STD-020B (for small body, Sn-Pb or Pb assembly). For wave solder process, IC could meet 265°C, 5secs.
2. JEDEC Std JESD22-A114A (C1=100 pF, R1=1500 Ω, R2=500Ω)

***Comments**

Stressing the device above the rating listed in the Absolute Maximum Ratings" table may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the Operating sections of this specification is not implied. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability. Refer also to the AMIC SURE Program and other relevant quality documents.

DC AND AC PARAMETERS

This section summarizes the operating and measurement conditions, and the DC and AC characteristics of the device. The parameters in the DC and AC Characteristic tables that follow are derived from tests performed under the

Measurement Conditions summarized in the relevant tables. Designers should check that the operating conditions in their circuit match the measurement conditions when relying on the quoted parameters.

Table 9. Operating Conditions

Symbol	Parameter	Min.	Max.	Unit
V_{CC}	Supply Voltage	2.7	3.6	V
T_A	Ambient Operating Temperature	-40	85	°C

Table 10. Data Retention and Endurance

Parameter	Condition	Min.	Max.	Unit
Erase/Program Cycles	At 85°C	100,000		Cycles
Data Retention	At 85°C	20		Years

Table 11. Capacitance

Symbol	Parameter	Test Condition	Min.	Max.	Unit
C_{OUT}	Output Capacitance (DO)	$V_{OUT} = 0V$		8	pF
C_{IN}	Input Capacitance (other pins)	$V_{IN} = 0V$		6	pF

Note: Sampled only, not 100% tested, at $T_A=25^\circ C$ and a frequency of 33 MHz.

Table 12. DC Characteristics

Symbol	Parameter	Test Condition	Min.	Typ.	Max.	Unit
I _{LI}	Input Leakage Current				± 2	μA
I _{LO}	Output Leakage Current				± 2	μA
I _{CC1}	Standby Current	$\bar{S} = V_{CC}, V_{IN} = V_{SS} \text{ or } V_{CC}$		5	15	μA
I _{CC2}	Deep Power-down Current	$\bar{S} = V_{CC}, V_{IN} = V_{SS} \text{ or } V_{CC}$		5	15	μA
I _{CC3}	Operating Current (READ)	C= 0.1V _{CC} / 0.9.V _{CC} at 100MHz, DO = open		18	24	mA
		C= 0.1V _{CC} / 0.9.V _{CC} at 50MHz, DO = open		10	21	mA
		C= 0.1V _{CC} / 0.9.V _{CC} at 33MHz, DO = open		7	17	mA
I _{CC4}	Operating Current (PP)	$\bar{S} = V_{CC}$		10	15	mA
I _{CC5}	Operating Current (WRSR)	$\bar{S} = V_{CC}$			15	mA
I _{CC6}	Operating Current (SE)	$\bar{S} = V_{CC}$			25	mA
I _{CC7}	Operating Current (BE)	$\bar{S} = V_{CC}$			25	mA
V _{IL}	Input Low Voltage		-0.5		0.3V _{CC}	V
V _{IH}	Input High Voltage		0.7V _{CC}		V _{CC} +0.4	V
V _{OL}	Output Low Voltage	I _{OL} = 1.6mA			0.4	V
V _{OH}	Output High Voltage	I _{OH} = -100μA	V _{CC} -0.2			V

Note: 1. This is preliminary data at 85°C

Table 13. Instruction Times

Symbol	Alt.	Parameter	Min.	Typ.	Max.	Unit
t _W		Write Status Register Cycle Time		5	15	ms
t _{PP}		Page Program Cycle Time		2	3	ms
t _{SE}		Sector Erase Cycle Time		0.2	0.24	s
t _{BE}		Block Erase Cycle Time		0.5	1.3	s
t _{CE}		Chip Erase Cycle Time of A25L040A		4.5	10	s

Note: 1. Max is for 85°C

2. This is preliminary data

Table 14. AC Measurement Conditions

Symbol	Parameter	Min.	Max.	Unit
C _L	Load Capacitance	30		pF
	Input Rise and Fall Times		5	ns
	Input Pulse Voltages	0.2V _{CC} to 0.8V _{CC}		V
	Input Timing Reference Voltages	0.3V _{CC} to 0.7V _{CC}		V
	Output Timing Reference Voltages	V _{CC} / 2		V

Note: Output Hi-Z is defined as the point where data out is no longer driven.

Figure 24. AC Measurement I/O Waveform

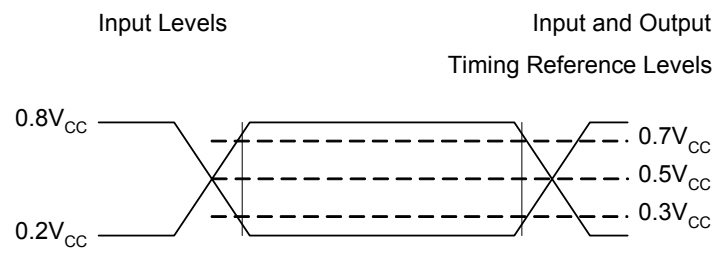


Table 15. AC Characteristics

Symbol	Alt.	Parameter	Min.	Typ.	Max.	Unit
f_c	f_c	Clock Frequency for the following instructions: FAST_READ, PP, SE, BE, DP, RES, RDID, WREN, WRDI, RDSR, WRSR (2.7V~3.6V) / (3.0V~3.6V)	D.C.		80/100	MHz
f_R		Clock Frequency for READ instructions	D.C.		50	MHz
t_{CH}^1	t_{CLH}	Clock High Time	6			ns
t_{CL}^1	t_{CLL}	Clock Low Time	5			ns
t_{CLCH}^2		Clock Rise Time ³ (peak to peak)	0.1			V/ns
t_{CHCL}^2		Clock Fall Time ³ (peak to peak)	0.1			V/ns
t_{SLCH}	t_{CSS}	\bar{S} Active Setup Time (relative to C)	5			ns
t_{CHSL}		\bar{S} Not Active Hold Time (relative to C)	5			ns
t_{DVCH}	t_{DSU}	Data In Setup Time	5			ns
t_{CHDX}	t_{DH}	Data In Hold Time	5			ns
t_{CHSH}		\bar{S} Active Hold Time (relative to C)	5			ns
t_{SHCH}		\bar{S} Not Active Setup Time (relative to C)	5			ns
t_{SHSL}	t_{CSH}	\bar{S} Deselect Time	100			ns
t_{SHQZ}^2	t_{DIS}	Output Disable Time			9	ns
t_{CLQV}	t_V	Clock Low to Output Valid			9	ns
t_{CLOX}	t_{HO}	Output Hold Time	0			ns
t_{HLCH}		\overline{HOLD} Setup Time (relative to C)	5			ns
t_{CHHH}		\overline{HOLD} Hold Time (relative to C)	5			ns
t_{HHCH}		HOLD Setup Time (relative to C)	5			ns
t_{CHHL}		HOLD Hold Time (relative to C)	5			ns
t_{HHQX}^2	t_{LZ}	HOLD to Output Low-Z			8	ns
t_{HLQZ}^2	t_{HZ}	\overline{HOLD} to Output High-Z			8	ns
t_{WHSL}^4		Write Protect Setup Time	20			ns
t_{SHWL}^4		Write Protect Hold Time	100			ns
t_{DP}^2		\bar{S} High to Deep Power-down Mode			3	μ s
t_{RES1}^2		\bar{S} High to Standby Mode without Electronic Signature Read			30	μ s
t_{RES2}^2		\bar{S} High to Standby Mode with Electronic Signature Read			30	μ s
t_W		Write Status Register Cycle Time		5	15	ms
t_{pp}		Page Program Cycle Time		2	3	ms
t_{SE}		Sector Erase Cycle Time		0.2	0.24	s
t_{BE}		Block Erase Cycle Time		0.5	1.3	s
t_{CE}		Chip Erase Cycle Time of A25L040A		4.5	10	s

- Note: 1. $t_{CH} + t_{CL}$ must be greater than or equal to $1/f_c$
 2. Value guaranteed by characterization, not 100% tested in production.
 3. Expressed as a slew-rate.
 4. Only applicable as a constraint for a WRSR instruction when SRWD is set at 1.

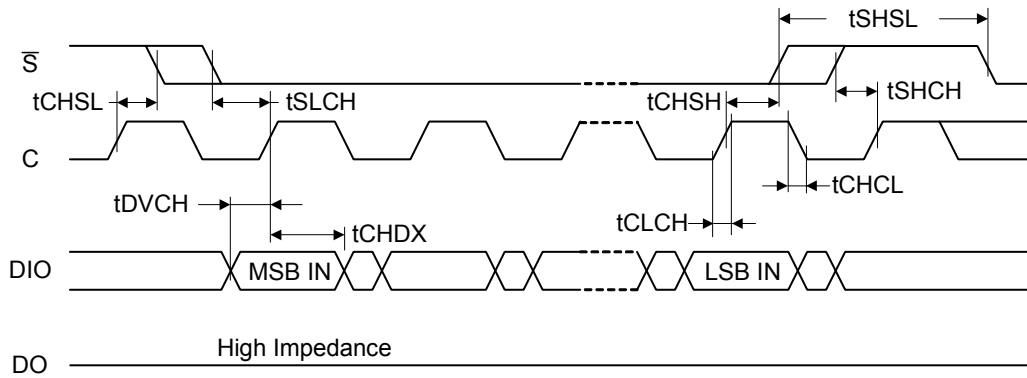
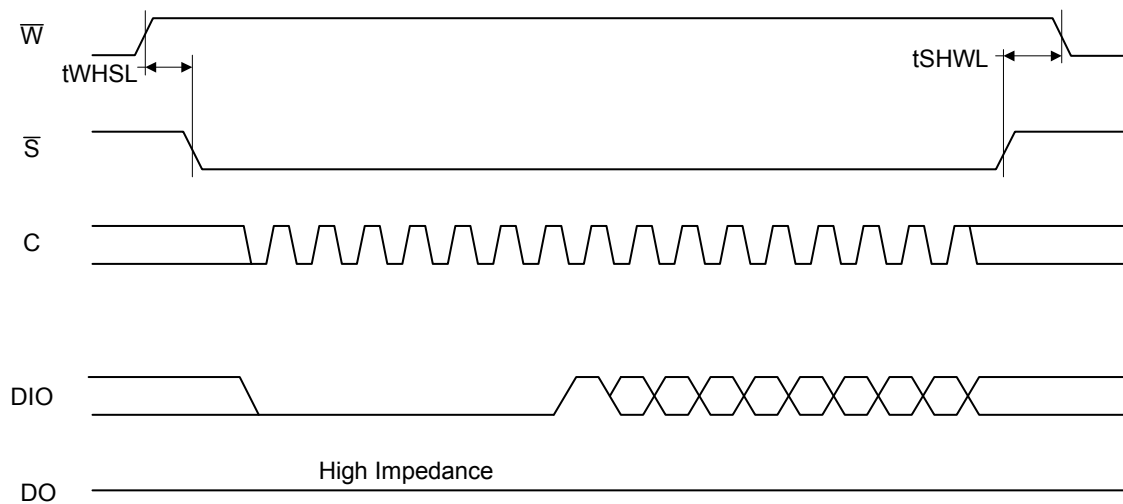
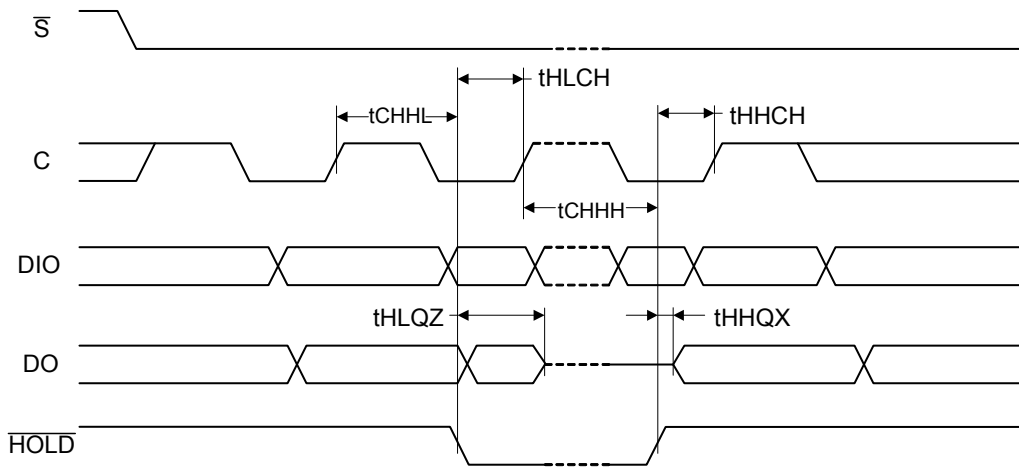
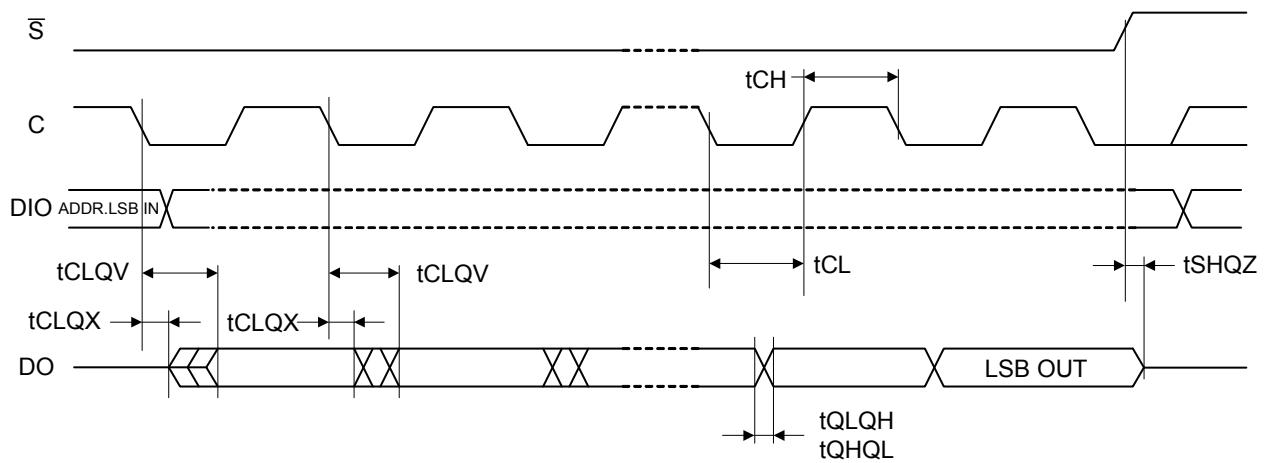
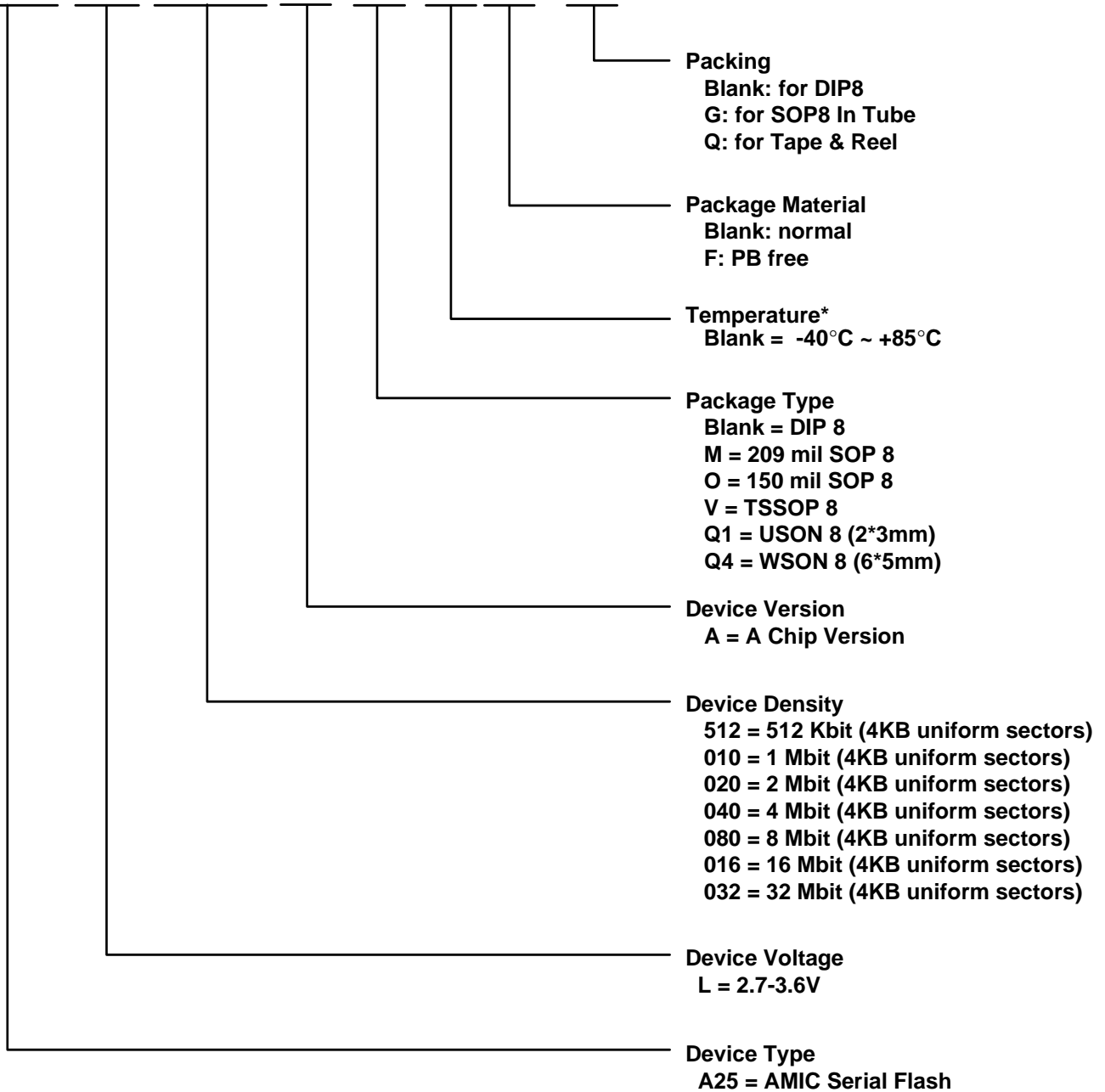
Figure 25. Serial Input Timing

Figure 26. Write Protect Setup and Hold Timing during WRSR when SRWD=1


Figure 27. Hold Timing

Figure 28. Output Timing


Part Numbering Scheme

A25 X XXX X X - X X / X



* Optional

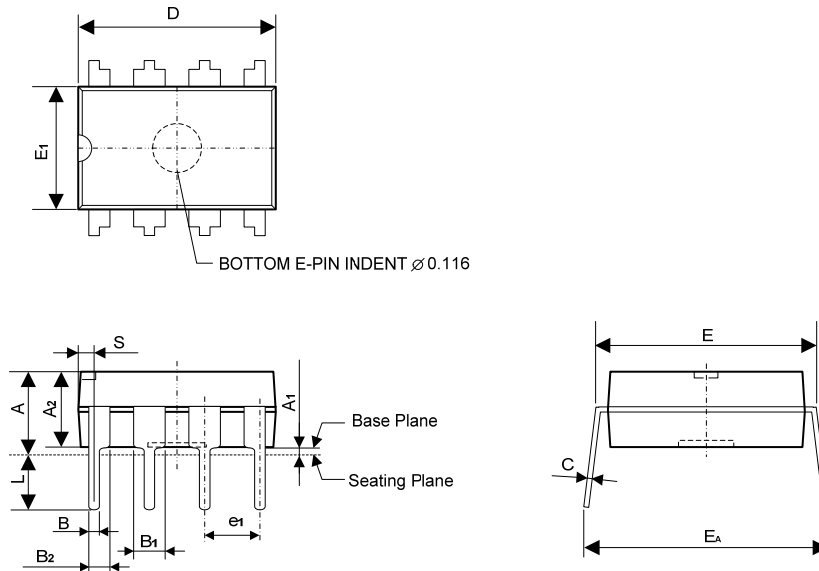
Ordering Information

Part No.	Speed (MHz)	Active Read Current Max. (mA)	Program/Erase Current Max. (mA)	Standby Current Max. (μ A)	Package
A25L040A-F	100	24	25	15	8 Pin Pb-Free DIP (300 mil)
A25L040AO-F					8 Pin Pb-Free SOP (150 mil)
A25L040AM-F					8 Pb-Free Pin SOP (209mil)
A25L040AV-F					8 Pin Pb-Free TSSOP
A25L040AQ1-F					8 Pin Pb-Free USON (2*3mm)
A25L040AQ4-F					8 Pin Pb-Free WSON (6*5mm)

Operating temperature range: -40°C ~ +85°C.

Package Information
P-DIP 8L Outline Dimensions

unit: inches/mm



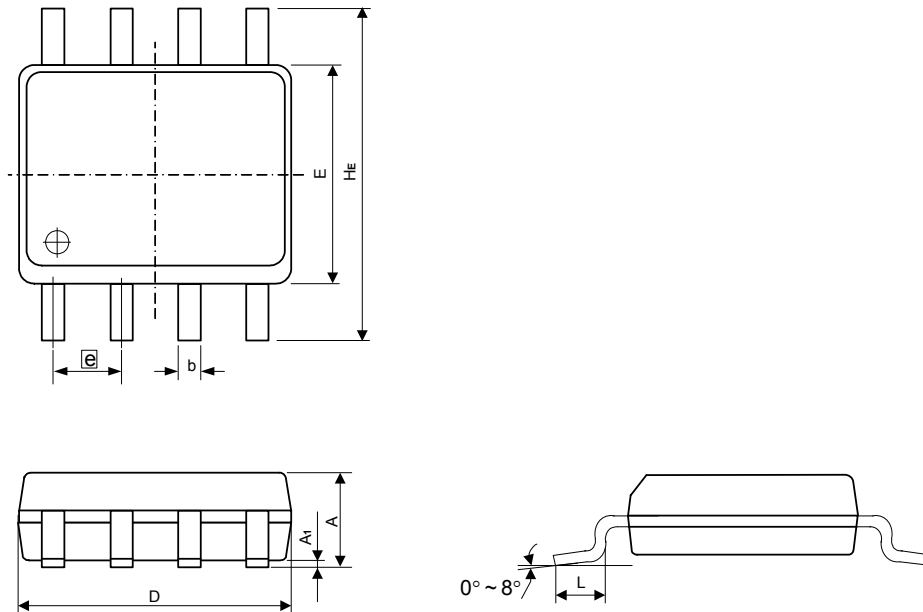
Symbol	Dimensions in inches			Dimensions in mm		
	Min	Nom	Max	Min	Nom	Max
A	-	-	0.180	-	-	4.57
A1	0.015	-	-	0.38	-	-
A2	0.128	0.130	0.136	3.25	3.30	3.45
B	0.014	0.018	0.022	0.36	0.46	0.56
B1	0.050	0.060	0.070	1.27	1.52	1.78
B2	0.032	0.039	0.046	0.81	0.99	1.17
C	0.008	0.010	0.013	0.20	0.25	0.33
D	0.350	0.360	0.370	8.89	9.14	9.40
E	0.290	0.300	0.315	7.37	7.62	8.00
E1	0.254	0.260	0.266	6.45	6.60	6.76
e1	-	0.100	-	-	2.54	-
L	0.125	-	-	3.18	-	-
E _A	0.345	-	0.385	8.76	-	9.78
S	0.016	0.021	0.026	0.41	0.53	0.66

Notes:

1. Dimension D and E₁ do not include mold flash or protrusions.
2. Dimension B₁ does not include dambar protrusion.
3. Tolerance: ±0.010" (0.25mm) unless otherwise specified.

Package Information
SOP 8L (150mil) Outline Dimensions

unit: mm



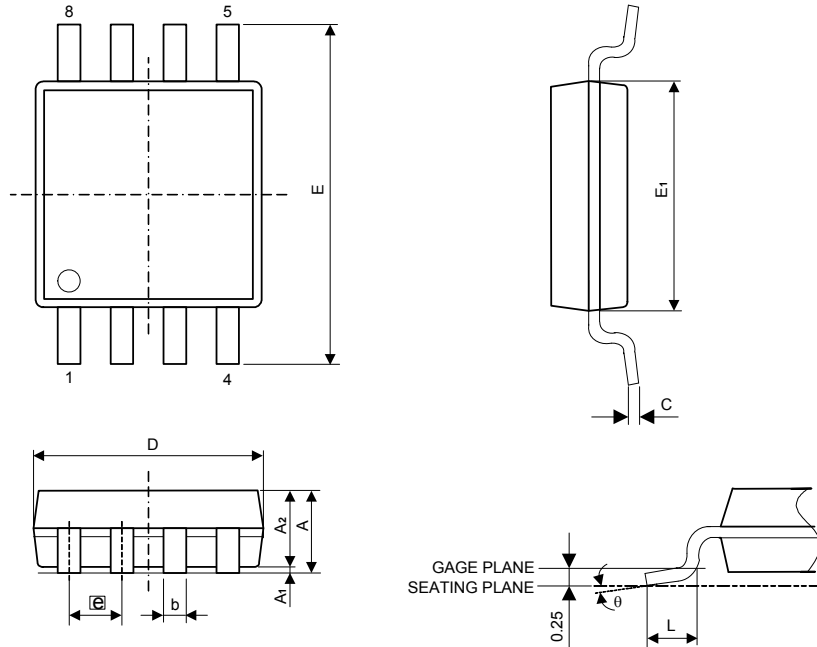
Symbol	Dimensions in mm
A	1.35~1.75
A1	0.10~0.25
b	0.33~0.51
D	4.7~5.0
E	3.80~4.00
e	1.27 BSC
HE	5.80~6.20
L	0.40~1.27

Notes:

1. Maximum allowable mold flash is 0.15mm.
2. Complies with JEDEC publication 95 MS -012 AA.
3. All linear dimensions are in millimeters (max/min).
4. Coplanarity: Max. 0.1mm

Package Information
SOP 8L (209mil) Outline Dimensions

unit: mm



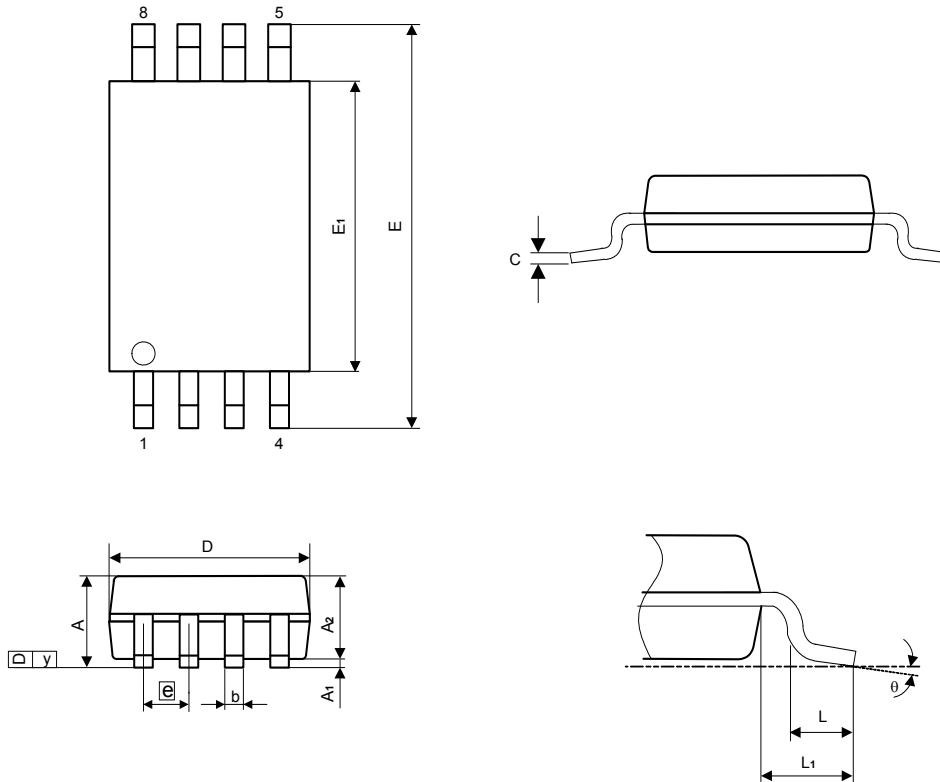
Symbol	Dimensions in mm		
	Min	Nom	Max
A	1.75	1.95	2.16
A1	0.05	0.15	0.25
A2	1.70	1.80	1.91
b	0.35	0.42	0.48
C	0.19	0.20	0.25
D	5.13	5.23	5.33
E	7.70	7.90	8.10
E1	5.18	5.28	5.38
\boxed{e}	1.27 BSC		
L	0.50	0.65	0.80
θ	0°	-	8°

Notes:

Maximum allowable mold flash is 0.15mm at the package ends and 0.25mm between leads

Package Information
TSSOP 8L Outline Dimensions

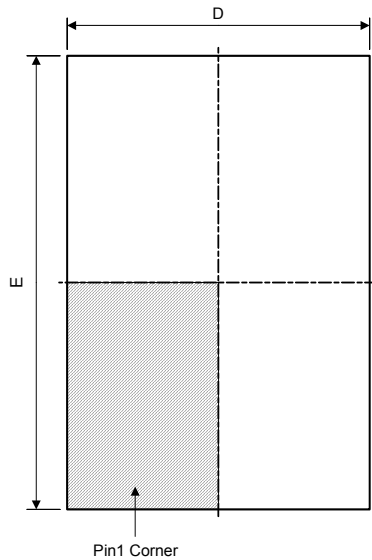
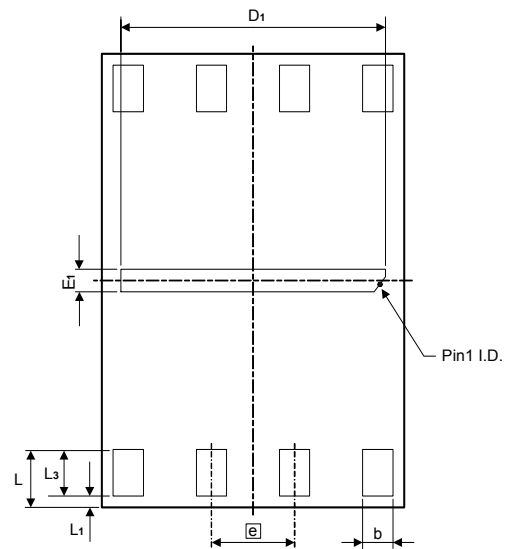
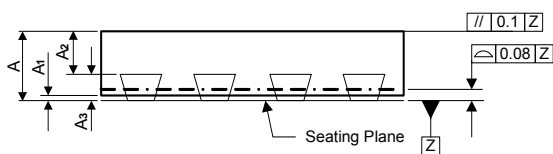
unit: inches/mm



Symbol	Dimensions in inches			Dimensions in mm		
	Min	Nom	Max	Min	Nom	Max
A	-	-	0.0472	-	-	1.200
A ₁	0.0020	-	0.0059	0.050	-	0.150
A ₂	0.0315	0.0394	0.0413	0.800	1.000	1.050
b	0.0075	-	0.0118	0.190	-	0.300
c	0.0035	-	0.0079	0.090	-	0.200
E	0.2441	0.2520	0.2598	6.200	6.400	6.600
E ₁	0.1693	0.1732	0.1772	4.300	4.400	4.500
\boxed{e}	-	0.0256	-	-	0.650	-
D	0.1142	0.1181	0.1220	2.900	3.000	3.100
L	0.0177	0.0236	0.0295	0.450	0.600	0.750
L ₁	-	0.0394	-	-	1.000	-
y	-	-	0.0039	-	-	0.100
θ	0°	-	8°	0°	-	8°

Package Information
USON 8L (2 X 3 X 0.6mm) Outline Dimensions

unit: inches/mm


Top View

Bottom View

Side View

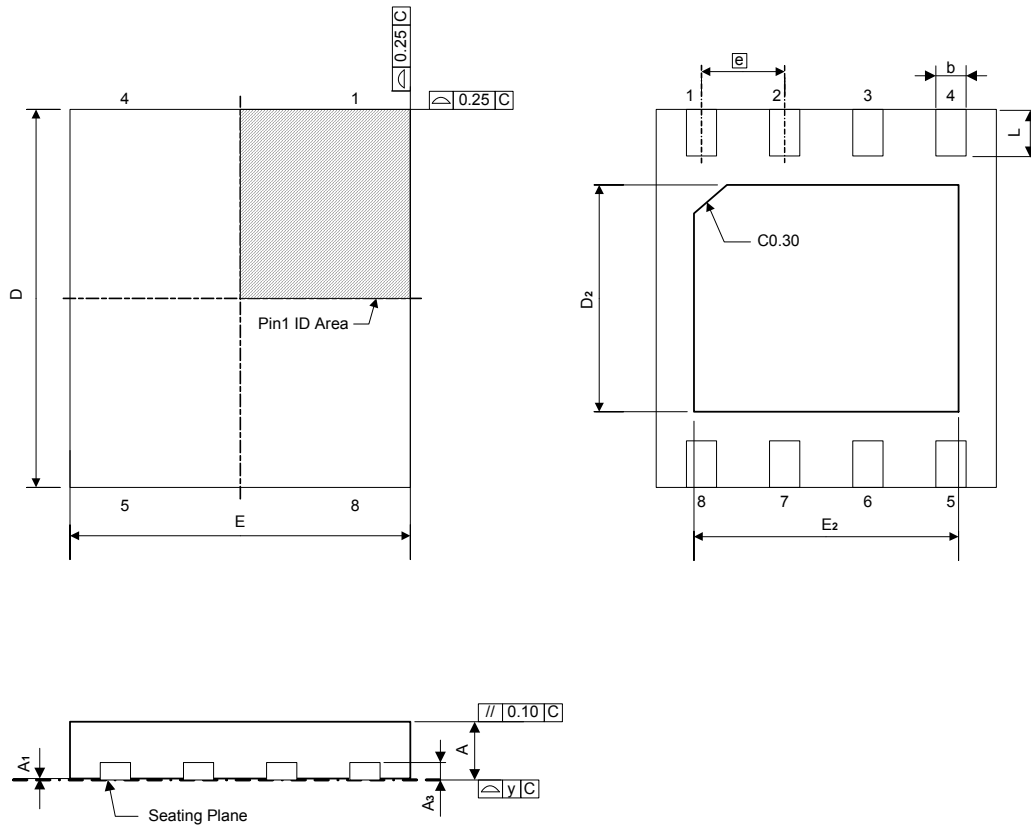
Symbol	Dimensions in inches			Dimensions in mm		
	Min	Nom	Max	Min	Nom	Max
A	0.020	0.022	0.024	0.50	0.55	0.60
A1	0	0.0014	0.002	0	0.035	0.05
A2	-	0.016	0.0167	-	0.40	0.425
A3	-	0.0060	-	-	0.152	-
b	0.008	0.010	0.012	0.20	0.25	0.30
D	0.075	0.079	0.083	1.90	2.00	2.10
D1	0.059	0.063	0.067	1.50	1.60	1.70
E	0.114	0.118	0.122	2.90	3.00	3.10
E1	0.004	0.008	0.012	0.10	0.20	0.30
[e]	-	0.020	-	-	0.50	-
L	0.016	0.018	0.020	0.40	0.45	0.50
L1	-	-	0.006	-	-	0.15
L3	0.012	-	-	0.30	-	-

Note:

1. This package has exposed metal pad underneath the package, it can't contact to metal trace or pad on board.
2. The exposed pad size must not violate the min. metal separation requirement, 0.2mm with terminals.

Package Information
WSO8 8L (6 X 5 X 0.8mm) Outline Dimensions

unit: mm/mil



Symbol	Dimensions in mm			Dimensions in mil		
	Min	Nom	Max	Min	Nom	Max
A	0.700	0.750	0.800	27.6	29.5	31.5
A ₁	0.000	0.020	0.050	0.0	0.8	2.0
A ₃	0.203 REF			8.0 REF		
b	0.350	0.400	0.480	13.8	15.8	18.9
D	5.900	6.000	6.100	232.3	236.2	240.2
D ₂	3.200	3.400	3.600	126.0	133.9	141.7
E	4.900	5.000	5.100	192.9	196.9	200.8
E ₂	3.800	4.000	4.200	149.6	157.5	165.4
L	0.500	0.600	0.750	19.7	23.6	29.5
e	1.270 BSC			50.0 BSC		
y	0	-	0.080	0	-	3.2

Note:

1. Controlling dimension: millimeters
2. Leadframe thickness is 0.203mm (8mil)