

PRELIMINARY INFORMATION MARCH 2011

# 16Mb LOW VOLTAGE, ULTRA LOW POWER PSEUDO CMOS STATIC RAM

### **FEATURES**

- High-speed access time:
  - 70ns (IS66WV1M16DALL/DBLL)
  - 55ns (IS66WV1M16DBLL)
- CMOS low power operation
- Single power supply
  - $-V_{DD} = 1.7V 1.95V (IS66WV1M16DALL)$
  - $-V_{DD} = 2.5V 3.6V (IS66WV1M16DBLL)$
- · Three state outputs
- Data control for upper and lower bytes
- Industrial temperature available
- Lead-free available

### DESCRIPTION

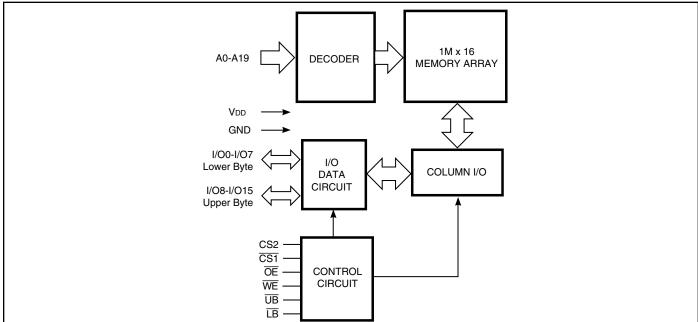
The *ISSI* IS66WV1M16DALL/DBLL is a high-speed, 16M bit static RAMs organized as 1Mb words by 16 bits. It is fabricated using *ISSI*'s high-performance CMOS technology. This highly reliable process coupled with innovative circuit design techniques, yields high-performance and low power consumption devices.

When  $\overline{CS1}$  is HIGH (deselected) or when CS2 is LOW (deselected) or when  $\overline{CS1}$  is LOW, CS2 is HIGH and both  $\overline{LB}$  and  $\overline{UB}$  are HIGH, the device assumes a standby mode at which the power dissipation can be reduced down with CMOS input levels.

Easy memory expansion is provided by using Chip Enable and Output Enable inputs. The active LOW Write Enable  $\overline{(WE)}$  controls both writing and reading of the memory. A data byte allows Upper Byte  $\overline{(UB)}$  and Lower Byte  $\overline{(LB)}$  access.

The IS66WV1M16DALL/DBLL is packaged in the JEDEC standard 48-ball mini BGA (6mm x 8mm). The device is also available for die sales.

### <u>FUNCTIONAL BLOCK DIAGRAM</u>



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a.) the risk of injury or damage has been minimized;

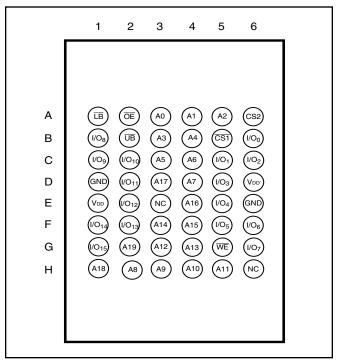
b.) the user assume all such risks; and

c.) potential liability of Integrated Silicon Solution, Inc is adequately protected under the circumstances



## **PIN CONFIGURATIONS:**

## 48-Ball mini BGA (6mm x 8mm)



Note:

TSOP package option is under evaluation.

## **PIN DESCRIPTIONS**

| A0-A19     | Address Inputs                  |
|------------|---------------------------------|
| I/O0-I/O15 | Data Inputs/Outputs             |
| CS1, CS2   | Chip Enable Input               |
| ŌĒ         | Output Enable Input             |
| WE         | Write Enable Input              |
| LB         | Lower-byte Control (I/O0-I/O7)  |
| ŪB         | Upper-byte Control (I/O8-I/O15) |
| NC         | No Connection                   |
| VDD        | Power                           |
| GND        | Ground                          |



## **TRUTH TABLE**

|                 |    |     |     | •  | •  | I/O PIN             |              |              |             |
|-----------------|----|-----|-----|----|----|---------------------|--------------|--------------|-------------|
| Mode            | WE | CS1 | CS2 | ŌĒ | LΒ | $\overline{\sf UB}$ | 1/00-1/07    | I/O8-I/O15   | VDD Current |
| Not Selected    | Х  | Н   | Х   | Х  | Х  | Х                   | High-Z       | High-Z       | ISB1, ISB2  |
|                 | Χ  | Χ   | L   | Χ  | Χ  | Χ                   | High-Z       | High-Z       | ISB1, ISB2  |
|                 | Χ  | Χ   | Χ   | Χ  | Н  | Н                   | High-Z       | High-Z       | ISB1, ISB2  |
| Output Disabled | Н  | L   | Н   | Н  | L  | Х                   | High-Z       | High-Z       | Icc         |
|                 | Н  | L   | Н   | Н  | Χ  | L                   | High-Z       | High-Z       | Icc         |
| Read            | Н  | L   | Н   | L  | L  | Н                   | <b>D</b> оит | High-Z       | Icc         |
|                 | Н  | L   | Н   | L  | Н  | L                   | High-Z       | <b>D</b> out |             |
|                 | Н  | L   | Н   | L  | L  | L                   | Dоит         | <b>D</b> оит |             |
| Write           | L  | L   | Н   | Χ  | L  | Н                   | Din          | High-Z       | Icc         |
|                 | L  | L   | Н   | Χ  | Н  | L                   | High-Z       | DIN          |             |
|                 | L  | L   | Н   | Χ  | L  | L                   | DIN          | DIN          |             |

## **OPERATING RANGE (VDD)**

| Range      | Ambient Temperature | (70ns)                    | (55ns)      |
|------------|---------------------|---------------------------|-------------|
| Commercial | 0°C to +70°C        | 1.7V - 1.95V, 2.5V - 3.6V | 2.5V - 3.6V |
| Industrial | -40°C to +85°C      | 1.7V - 1.95V, 2.5V - 3.6V | 2.5V - 3.6V |
| Automotive | –40°C to +105°C     | 2.5V-3.6V                 |             |



### ABSOLUTE MAXIMUM RATINGS(1)

| Symbol | Parameter                            | Value           | Unit |
|--------|--------------------------------------|-----------------|------|
| VTERM  | Terminal Voltage with Respect to GND | -0.2 to VDD+0.3 | V    |
| TBIAS  | Temperature Under Bias               | -40 to +85      | °C   |
| VDD    | VDD Related to GND                   | -0.2 to +3.8    | V    |
| Тѕтс   | Storage Temperature                  | -65 to +150     | °C   |
| Рт     | Power Dissipation                    | 1.0             | W    |

#### Note:

### DC ELECTRICAL CHARACTERISTICS (Over Operating Range)

### $V_{DD} = 2.5V-3.6V$

| Symbol | Parameter           | Test Conditions VDD             | Min.       | Max.           | Unit |
|--------|---------------------|---------------------------------|------------|----------------|------|
| Vон    | Output HIGH Voltage | Iон = -1 mA 2.5-3.6V            | 2.2        | _              | V    |
| Vol    | Output LOW Voltage  | IoL = 2.1 mA 2.5-3.6V           | _          | 0.4            | V    |
| VIH    | Input HIGH Voltage  | 2.5-3.6V                        | 2.2        | $V_{DD} + 0.3$ | V    |
| VIL    | Input LOW Voltage   | 2.5-3.6V                        | -0.2       | 0.6            | V    |
| ILI    | Input Leakage       | $GND \leq Vin \leq Vdd$         | <b>–</b> 1 | 1              | μA   |
| ILO    | Output Leakage      | GND ≤ Vouт ≤ Vdd, Outputs Disab | oled –1    | 1              | μA   |

### Notes:

 $V_{IL}$  (min.) = -2.0V AC (pulse width < 10ns). Not 100% tested.

 $V_{IH}$  (max.) =  $V_{DD}$  + 2.0V AC (pulse width < 10ns). Not 100% tested.

## DC ELECTRICAL CHARACTERISTICS (Over Operating Range)

### $V_{DD} = 1.7V-1.95V$

| Symbol | Parameter           | Test Conditions VDD                       | Min. | Max.                  | Unit |
|--------|---------------------|---|------|-----------------------|------|
| Vон    | Output HIGH Voltage | Iон = -0.1 mA 1.7-1.95V                   | 1.4  | _                     | V    |
| Vol    | Output LOW Voltage  | IoL = 0.1 mA 1.7-1.95V                    | _    | 0.2                   | V    |
| VIH    | Input HIGH Voltage  | 1.7-1.95V                                 | 1.4  | V <sub>DD</sub> + 0.2 | V    |
| VIL    | Input LOW Voltage   | 1.7-1.95V                                 | -0.2 | 0.4                   | V    |
| lu     | Input Leakage       | $GND \leq V_{IN} \leq V_{DD}$             | -1   | 1                     | μA   |
| ILO    | Output Leakage      | $GND \le VOUT \le VDD$ , Outputs Disabled | -1   | 1                     | μΑ   |

### Notes:

 $V_{IL}$  (min.) = -1.0V AC (pulse width < 10ns). Not 100% tested.

 $V_{IH}$  (max.) =  $V_{DD}$  + 1.0V AC (pulse width < 10ns). Not 100% tested.

Stress greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the
device. This is a stress rating only and functional operation of the device at these or any other conditions above
those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.



## CAPACITANCE<sup>(1)</sup>

| Symbol | Parameter                | Conditions    | Max. | Unit |  |
|--------|--------------------------|---------------|------|------|--|
| Cin    | Input Capacitance        | $V_{IN} = 0V$ | 8    | pF   |  |
| Соит   | Input/Output Capacitance | Vout = 0V     | 10   | pF   |  |

#### Note:

## **ACTEST CONDITIONS**

| Parameter                                   | 1.7V-1.95V<br>(Unit)         | 2.5V-3.6V<br>(Unit) |  |
|---|------------------------------|---------------------|--|
| Input Pulse Level                           | 0.4V to V <sub>DD</sub> -0.2 | 0.4V to VDD-0.3V    |  |
| Input Rise and Fall Times                   | 5 ns                         | 5ns                 |  |
| Input and Output Timing and Reference Level | VREF                         | VREF                |  |
| Output Load                                 | See Figures 1 and 2          | See Figures 1 and 2 |  |

|       | 1.7V - 1.95V | 2.5V - 3.6V |
|-------|--------------|-------------|
| R1(Ω) | 3070         | 1029        |
| R2(Ω) | 3150         | 1728        |
| VREF  | 0.9V         | 1.4V        |
| Vтм   | 1.8V         | 2.8V        |

## **ACTEST LOADS**

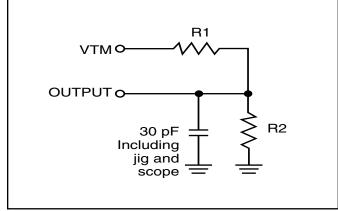


Figure 1

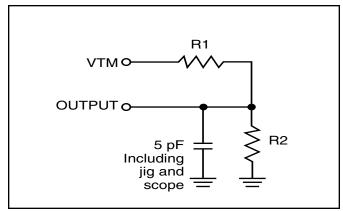


Figure 2

<sup>1.</sup> Tested initially and after any design or process changes that may affect these parameters.



1.7V-1.95V POWER SUPPLY CHARACTERISTICS (Over Operating Range)

| Symbol | Parameter                               | Test Conditions  |                       | Max.<br>70ns      | Unit |
|--------|---|--|-----------------------|-------------------|------|
| Icc    | VDD Dynamic Operating<br>Supply Current | VDD = Max.,<br>IOUT = 0 mA, f = fMAX<br>All Inputs 0.4V<br>or VDD - 0.2V   | Com.<br>Ind.<br>Auto. | 20<br>25<br>30    | mA   |
| Icc1   | Operating Supply<br>Current             | $V_{DD} = Max., \overline{CS1} = 0.2V$ $\overline{WE} = V_{DD} - 0.2V$ $CS2 = V_{DD} - 0.2V, f = 1_{MHZ}$  | Com.<br>Ind.<br>Auto. | 4<br>4<br>10      | mA   |
| ISB1   | TTL Standby Current<br>(TTL Inputs)     | $\begin{aligned} &V_{DD} = Max., \\ &V_{IN} = V_{IH} \text{ or } V_{IL} \\ &\overline{CS1} = V_{IH} \text{ , } CS2 = V_{IL}, \\ &f = 1 \text{ MHz} \end{aligned}$  | Com.<br>Ind.<br>Auto. | 0.6<br>0.6<br>1   | mA   |
|        | OR                                      |  |                       |                   |      |
|        | ULB Control                             | $\frac{V_{DD} = Max., V_{IN} = V_{IH} \text{ or } V_{IL}}{\overline{CS1}} = V_{IL}, f = 0, \overline{UB} = V_{IH}, \overline{L}$   |                       |                   |      |
| ISB2   | CMOS Standby<br>Current (CMOS Inputs)   | $\begin{split} & \frac{\text{V}_{\text{DD}} = \text{Max.,}}{\text{CS1}} \geq \text{V}_{\text{DD}} - 0.2\text{V,}\\ & \text{CS2} \leq 0.2\text{V,}\\ & \text{V}_{\text{IN}} \geq \text{V}_{\text{DD}} - 0.2\text{V, or}\\ & \text{V}_{\text{IN}} \leq 0.2\text{V, f} = 0 \end{split}$ | Com.<br>Ind.<br>Auto. | 100<br>120<br>150 | μΑ   |
|        | OR                                      |  |                       |                   |      |
|        | ULB Control                             | $\begin{split} &V_{DD} = Max., \ \overline{CS1} = V_{IL}, \ C\\ &\underline{V_{IN}} \geq V_{DD} - 0.2V, \ or \ V_{IN} \leq \\ &\overline{UB} \ / \ \overline{LB} = V_{DD} - 0.2V \end{split}$  |                       |                   |      |

### Note:.

<sup>1.</sup> At  $f = f_{MAX}$ , address and data inputs are cycling at the maximum frequency, f = 0 means no input lines change.



## 2.5V-3.6V POWER SUPPLY CHARACTERISTICS (Over Operating Range)

| Symbol | Parameter             | Test Conditions   |                     | Max.<br>55ns | Unit |  |
|--------|-----------------------|---|---------------------|--------------|------|--|
| Icc    | VDD Dynamic Operating | V <sub>DD</sub> = Max.,   | Com.                | 25           | mA   |  |
|        | Supply Current        | IOUT = 0  mA, f = fMAX  | Ind.                | 28           |      |  |
|        |                       | All Inputs 0.4V   | Auto.               | 35           |      |  |
|        |                       | or V <sub>DD</sub> – 0.3V   | typ. <sup>(2)</sup> | 15           |      |  |
| Icc1   | Operating Supply      | $V_{DD} = Max., \overline{CS1} = 0.2V$  | Com.                | 5            | mA   |  |
|        | Current               | $\overline{\text{WE}} = V_{DD} - 0.2V$  | Ind.                | 5            |      |  |
|        |                       | $CS2 = V_{DD} - 0.2V, f = 1_{MHZ}$  | Аито.               | 10           |      |  |
| ISB1   | TTL Standby Current   | V <sub>DD</sub> = Max.,   | Com.                | 0.6          | mA   |  |
|        | (TTL Inputs)          | VIN = VIH  or  VIL  | Ind.                | 0.6          |      |  |
|        |                       | $\overline{\text{CS1}} = \text{V}_{\text{IH}}$ , $\text{CS2} = \text{V}_{\text{IL}}$ , $\text{f} = 1 \text{ MHz}$   | Аито.               | 1            |      |  |
|        | OR                    |   |                     |              |      |  |
|        | ULB Control           | $\frac{V_{DD}}{CS1} = Max., V_{IN} = V_{IH} \text{ or } V_{IL}$<br>$\overline{CS1} = V_{IL}, f = 0, \overline{UB} = V_{IH}, \overline{L}$   |                     |              |      |  |
| IsB2   | CMOS Standby          | V <sub>DD</sub> = Max.,   | Com.                | 100          | μA   |  |
|        | Current (CMOS Inputs) | $\overline{\text{CS1}} \geq \text{V}_{\text{DD}} - 0.2\text{V},$  | Ind.                | 130          | ·    |  |
|        |                       | $CS2 \leq 0.2V$ ,   | Auto.               | 150          |      |  |
|        |                       | $VIN \ge VDD - 0.2V$ , or $VIN \le 0.2V$ , $f = 0$  | typ. <sup>(2)</sup> | 75           |      |  |
|        | OR                    |   |                     |              |      |  |
|        | ULB Control           | $\begin{aligned} &V_{DD} = Max., \ \overline{CS1} = V_{IL}, \ C\\ &\underline{V_{IN}} \geq V_{DD} - 0.2V, \ or \ V_{IN} \leq \\ &\overline{UB} \ / \ \overline{LB} = V_{DD} - 0.2V \end{aligned}$ |                     |              |      |  |

At f = fMAX, address and data inputs are cycling at the maximum frequency, f = 0 means no input lines change.
 Typical values are measured at VDD = 3.0V, TA = 25°C and not 100% tested.



## READ CYCLE SWITCHING CHARACTERISTICS<sup>(1)</sup> (Over Operating Range)

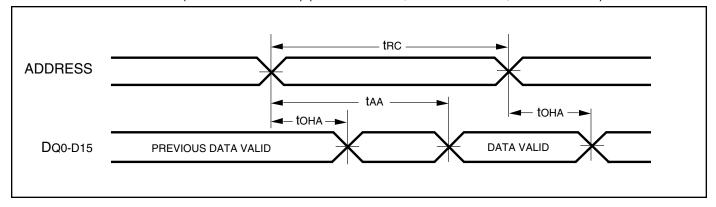
|                              |                          | 55 n | IS   | 70 ns |      |      |
|------------------------------|--------------------------|------|------|-------|------|------|
| Symbol                       | Parameter                | Min. | Max. | Min.  | Max. | Unit |
| trc                          | Read Cycle Time          | 55   | _    | 70    | _    | ns   |
| taa                          | Address Access Time      | _    | 55   | _     | 70   | ns   |
| tона                         | Output Hold Time         | 10   | _    | 10    | _    | ns   |
| tacs1/tacs2                  | CS1/CS2 Access Time      | _    | 55   | _     | 70   | ns   |
| <b>t</b> DOE                 | OE Access Time           | _    | 25   | _     | 35   | ns   |
| thzoe(2)                     | OE to High-Z Output      | _    | 20   | _     | 25   | ns   |
| tLZOE <sup>(2)</sup>         | OE to Low-Z Output       | 5    | _    | 5     | _    | ns   |
| thzcs1/thzcs2 <sup>(2)</sup> | CS1/CS2 to High-Z Output | 0    | 20   | 0     | 25   | ns   |
| tLZCS1/tLZCS2 <sup>(2)</sup> | CS1/CS2 to Low-Z Output  | 10   | _    | 10    | _    | ns   |
| <b>t</b> BA                  | LB, UB Access Time       | _    | 55   | _     | 70   | ns   |
| tнzв                         | LB, UB to High-Z Output  | 0    | 20   | 0     | 25   | ns   |
| <b>t</b> LZB                 | LB, UB to Low-Z Output   | 0    | _    | 0     | _    | ns   |

### Notes:

- 1. Test conditions assume signal transition times of 5 ns or less, timing reference levels of 0.9V/1.5V, input pulse levels of 0.4 to VDD-0.2V/0.4V to VDD-0.3V and output loading specified in Figure 1.
- 2. Tested with the load in Figure 2. Transition is measured ±100 mV from steady-state voltage. Not 100% tested.

### **AC WAVEFORMS**

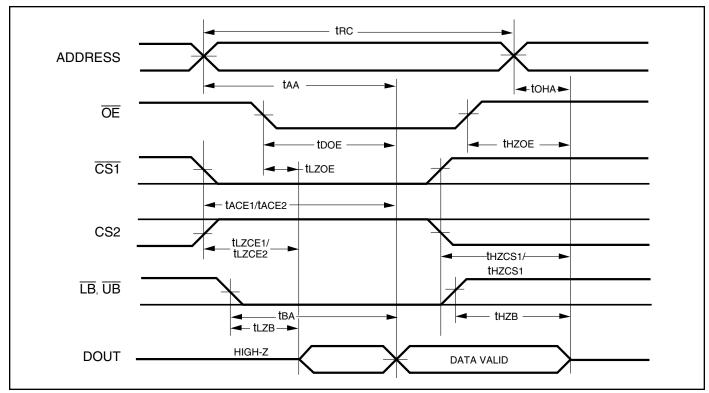
**READ CYCLE NO. 1**<sup>(1,2)</sup> (Address Controlled) ( $\overline{CS1} = \overline{OE} = V_{IL}$ ,  $\overline{CS2} = \overline{WE} = V_{IH}$ ,  $\overline{UB}$  or  $\overline{LB} = V_{IL}$ )





### **AC WAVEFORMS**

**READ CYCLE NO. 2**(1,3)  $(\overline{CS1}, CS2, \overline{OE}, AND \overline{UB}/\overline{LB} Controlled)$ 



#### Notes:

- 1. WE is HIGH for a Read Cycle.
- 2. The device is continuously selected.  $\overline{OE}$ ,  $\overline{CS1}$ ,  $\overline{UB}$ , or  $\overline{LB}$  = V<sub>IL</sub>.  $CS2=\overline{WE}=V_{IH}$ .
- 3. Address is valid prior to or coincident with  $\overline{\text{CS1}}$  LOW transition.



## WRITE CYCLE SWITCHING CHARACTERISTICS<sup>(1,2)</sup> (Over Operating Range)

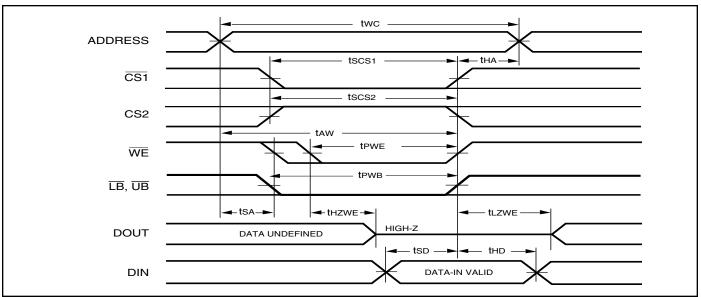
|                      |                                     | 55   | ns     | 70 ns     |      |
|----------------------|-------------------------------------|------|--------|-----------|------|
| Symbol               | Parameter                           | Min. | Max.   | Min. Max. | Unit |
| twc                  | Write Cycle Time                    | 55   | _      | 70 —      | ns   |
| tscs1/tscs           | s <sub>2</sub> CS1/CS2 to Write End | 45   | _      | 60 —      | ns   |
| taw                  | Address Setup Time to Write End     | 45   | _      | 60 —      | ns   |
| <b>t</b> HA          | Address Hold from Write End         | 0    | _      | 0 —       | ns   |
| <b>t</b> sa          | Address Setup Time                  | 0    | _      | 0 —       | ns   |
| tрwв                 | LB, UB Valid to End of Write        | 45   | _      | 60 —      | ns   |
| tpwe <sup>(4)</sup>  | WE Pulse Width                      | 45   | 15,000 | 60 15,000 | ns   |
| tsp                  | Data Setup to Write End             | 25   | _      | 30 —      | ns   |
| <b>t</b> HD          | Data Hold from Write End            | 0    | _      | 0 —       | ns   |
| thzwe <sup>(3)</sup> | WE LOW to High-Z Output             | _    | 20     | — 30      | ns   |
| tLZWE <sup>(3)</sup> | WE HIGH to Low-Z Output             | 5    | _      | 5 —       | ns   |

#### Notes:

- 1. Test conditions assume signal transition times of 5 ns or less, timing reference levels of 0.9V/1.5V, input pulse levels of 0.4 to VDD-0.2V/0.4V to VDD-0.3V and output loading specified in Figure 1.
- 2. The internal write time is defined by the overlap of CS1 LOW, CS2 HIGH and UB or LB, and WE LOW. All signals must be in valid states to initiate a Write, but any one can go inactive to terminate the Write. The Data Input Setup and Hold timing are referenced to the rising or falling edge of the signal that terminates the write.
- 3. Tested with the load in Figure 2. Transition is measured ±100 mV from steady-state voltage. Not 100% tested.
- 4.  $t_{PWE} > t_{HZWE} + t_{SD}$  when  $\overline{OE}$  is LOW.

### **AC WAVEFORMS**

## WRITE CYCLE NO. $1^{(1,2)}$ ( $\overline{CS1}$ Controlled, $\overline{OE}$ = HIGH or LOW)

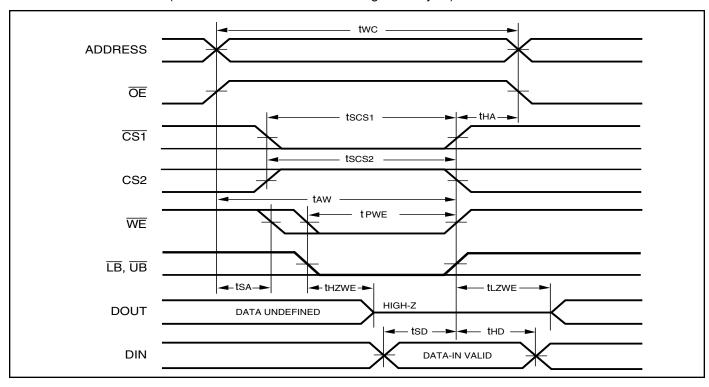


### Notes:

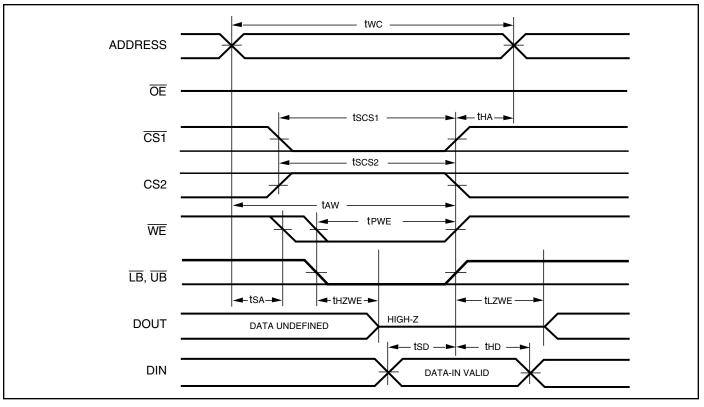
- 1. WRITE is an internally generated signal asserted during an overlap of the LOW states on the  $\overline{\text{CS1}}$ , CS2 and  $\overline{\text{WE}}$  inputs and at least one of the  $\overline{\text{LB}}$  and  $\overline{\text{UB}}$  inputs being in the LOW state.
- 2. WRITE =  $(\overline{CS1})$  [  $(\overline{LB})$  =  $(\overline{UB})$  ]  $(\overline{WE})$ .



## WRITE CYCLE NO. 2 (WE Controlled: OE is HIGH During Write Cycle)

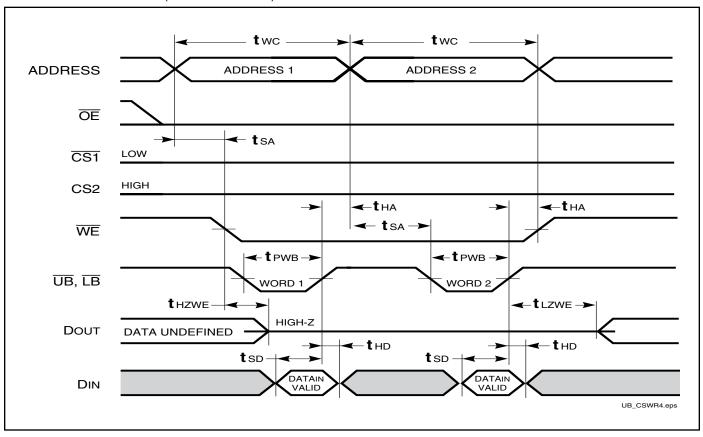


## WRITE CYCLE NO. 3 (WE Controlled: OE is LOW During Write Cycle)

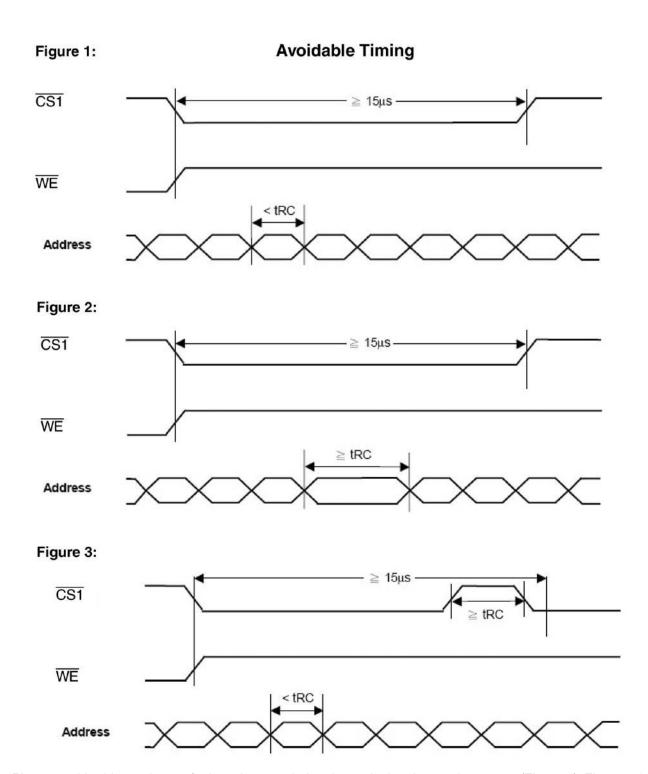




## WRITE CYCLE NO. 4 (UB/LB Controlled)







Please avoid address change for less than tRC during the cycle time longer than 15  $\mu s$  (Figure 1). Figure 2 & 3 provide work around solution for this issue.



### IS66WV1M16DALL

Industrial Range: -40°C to +85°C Voltage Range: 1.7V to 1.95V

| Speed (ns) | Order Part No.       | Package                         |
|------------|----------------------|---------------------------------|
| 70         | IS66WV1M16DALL-70BLI | mini BGA (6mm x 8mm), Lead-free |

## IS66WV1M16DBLL

Industrial Range: -40°C to +85°C Voltage Range: 2.5V to 3.6V

| Speed (ns) | Order Part No.       | Package                         |
|------------|----------------------|---------------------------------|
| 55         | IS66WV1M16DBLL-55BLI | mini BGA (6mm x 8mm), Lead-free |
| 70         | IS66WV1M16DBLL-70BLI | mini BGA (6mm x 8mm), Lead-free |

