

# Absolute encoders - bus interfaces

End shaft  $\varnothing 12$  mm

Magnetic single- or multiturn encoders 12 bit ST / 16 bit MT, DeviceNet

## BMSH 58, BMMH 58 DeviceNet - MAGRES



BMMH 58 DeviceNet with end shaft

### Features

- Encoder single- or multiturn / DeviceNet
- Magnetic sensing
- Resolution: singleturn 12 bit, multiturn 16 bit
- Integrated fieldbus interface
- High resistance to shock and vibrations
- Resolution and zero point programmable

### Technical data - electrical ratings

Voltage supply	10...30 VDC
Consumption w/o load (typ.)	100 mA (24 VDC)
Initializing time (typ.)	170 ms after power on
Interface	DeviceNet
Profile conformity	Device Profile Encoder V 1.0
Steps per turn	$\leq 4096$ / 12 bit
Absolute accuracy	$\pm 1^\circ$
Sensing method	Magnetic
Code	Binary
Code sequence	CW default, programmable
Interference immunity	DIN EN 61000-6-2
Emitted interference	DIN EN 61000-6-3
Programmable parameters	Operating modes Total resolution Preset Scaling
Diagnostic functions	Position or parameter error Multiturn sensing
Approval	UL approval / E217823
<b>BMSH 58</b>	
Function	Singleturn
<b>BMMH 58</b>	
Function	Multiturn
Number of turns	$\leq 65536$ / 16 bit

### Technical data - mechanical design

Dimensions (flange)	$\varnothing 58$ mm
Shaft	$\varnothing 12$ mm end shaft
Protection DIN EN 60529	IP 65
Operating speed	$\leq 12000$ rpm (mechanical) $\leq 6000$ rpm (electric)
Operating torque typ.	0.0093 Nm
Materials	Housing: aluminium Flange: aluminium
Operating temperature	$-20 \dots +85^\circ\text{C}$
Relative humidity	95 %
Resistance	DIN EN 60068-2-6 Vibration 30 g, 10-2000 Hz DIN EN 60068-2-27 Shock 500 g, 6 ms
Weight approx.	300 g
Connection	Connector D-SUB, 9-pin



# Absolute encoders - bus interfaces

End shaft  $\varnothing 12$  mm

Magnetic single- or multiturn encoders 12 bit ST / 16 bit MT, DeviceNet

## BMSH 58, BMMH 58 DeviceNet - MAGRES

### Terminal significance

+Vs	Encoder supply voltage.
0 V	Encoder ground connection relating to +Vs.
CAN_L	CAN bus signal (dominant Low).
CAN_H	CAN bus signal (dominant High).
CAN_GND	GND relating to CAN interface.

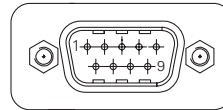
### DeviceNet features

Bus protocol	DeviceNet
Device profile	Device Profile for Encoders V 1.0
Operating modes	- I/O-Polling - Cyclic - Change of State
Preset	Parameter for setting the encoder to a requested position value assigned to a defined shaft position of the system. The offset of encoder zero point and mechanical zero point is stored in the encoder.
Rotating direction	Parameter for defining the rotating direction in which there have to be ascending or descending position values. Default setting: ascending position values when looking at the flange and rotating the shaft clockwise.
Scaling	Parameter defining the steps per turn as well as the total resolution.
Diagnosis	The encoder supports the following error warnings: - Position and parameter error - Lithium battery voltage control (Multiturn)
Default	125 kbit/s, Mac Id 63

### Terminal assignment

#### Connector D-Sub male

Connector	Signals	Description
Pin 1	d.u.	do not use
Pin 2	CAN_L	Bus (dominant Low)
Pin 3	CAN_GND	CAN Ground
Pin 4	d.u.	do not use
Pin 5	CAN_SHLD	CAN Shield
Pin 6	0 V	Supply voltage
Pin 7	CAN_H	Bus (dominant High)
Pin 8	n.c.	–
Pin 9	+Vs	Supply voltage



# Absolute encoders - bus interfaces

End shaft  $\varnothing 12$  mm

Magnetic single- or multiturn encoders 12 bit ST / 16 bit MT, DeviceNet

**BMSH 58, BMMH 58 DeviceNet - MAGRES**

## Dimensions

### BMSH/BMMH 58 DeviceNet connector D-SUB radial

